

FREE Advance Logic Controller

Hardware Guide

Original instructions

9MA10291.04
09/2024



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Safety Information

Important Information




Read these instructions carefully, and look at the equipment to become familiar with the device before trying to install, operate, service, or maintain it. The following special messages may appear throughout this documentation or on the equipment to warn of potential hazards or to call attention to information that clarifies or simplifies a procedure.



The addition of this symbol to a "Danger" or "Warning" safety label indicates that an electrical hazard exists which will result in personal injury if the instructions are not followed.



This is the safety alert symbol. It is used to alert you to potential personal injury hazards. Obey all safety messages that follow this symbol to avoid possible injury or death.

| |
|--|
|  DANGER |
| DANGER indicates a hazardous situation which, if not avoided, will result in death or serious injury. |
|  WARNING |
| WARNING indicates a hazardous situation which, if not avoided, could result in death or serious injury. |
|  CAUTION |
| CAUTION indicates a hazardous situation which, if not avoided, could result in minor or moderate injury. |
| NOTICE |
| NOTICE is used to address practices not related to physical injury. |

Please Note

Electrical equipment should be installed, operated, serviced, and maintained only by qualified personnel. No responsibility is assumed by Schneider Electric and Eliwell for any consequences arising out of the use of this material.

A qualified person is one who has skills and knowledge related to the construction and operation of electrical equipment and its installation, and has received safety training to recognize and avoid the hazards involved.

Qualification of Personnel

Only appropriately trained persons who are familiar with and understand the contents of this manual and all other pertinent product documentation are authorized to work on and with this product.

The qualified person must be able to detect possible hazards that may arise from parameterization, modifying parameter values and generally from mechanical, electrical, or electronic equipment. The qualified person must be familiar with the

standards, provisions, and regulations for the prevention of industrial accidents, which they must observe when designing and implementing the system.

Intended Use

The products described or affected by this document, together with software, accessories, and options, are controllers, intended for commercial HVAC machines according to the instructions, directions, examples, and safety information contained in the present document and other supporting documentation.

The product may only be used in compliance with all applicable safety regulations and directives, the specified requirements, and the technical data.

Prior to using the product, you must perform a risk assessment in view of the planned application. Based on the results, the appropriate safety-related measures must be implemented.

Since the product is used as a component in an overall machine or process, you must ensure the safety of persons by means of the design of this overall system.

Operate the product only with the specified cables and accessories. Use only genuine accessories and spare parts.

Any use other than the use explicitly permitted is prohibited and can result in unanticipated hazards.

Prohibited Use

Any use other than that expressed above under Permitted use is strictly prohibited.

The relay contacts supplied are of an electromechanical type and subject to wear. Functional safety protection devices, specified in international or local standards, must be installed externally to this device.

Liability and Residual Risks

The liability of Schneider Electric and Eliwell is limited to the proper and professional use of this product under the guidelines contained in the present and other supporting documents, and does not extend to damages caused by (but not limited to):

- Unspecified installation/use and, in particular, in contravention of the safety requirements of established legislation or specified in this document;
- Use on equipment which does not provide adequate protection against electrocution, water and dust in the actual installation conditions;
- Use on equipment in which dangerous components can be accessed without the use of specific tools;
- Installation/use on equipment which does not comply with established legislation and standards.

Disposal

The appliance (or the product) must be disposed of separately in compliance with the local standards in force on waste disposal.

About the Book

Document Scope

This document describes the FREE Advance Logic controllers, expansion modules, remote displays, and accessories, including installation and wiring information.

NOTE: Read and understand this document and all related documents, page 9 before installing, operating, or maintaining your device.

Validity Note

This document has been updated for the release of FREE Studio Plus V1.5.0.

For product compliance and environmental information (RoHS, REACH, PEP, EOLI, etc.), go to <https://www.eliwell.com/en/Support/Green-Premium.html>.

The technical characteristics of the devices described in the present document also appear online. To access the information online, go to the Eliwell home page www.eliwell.com.

Related Documents

| Title of documentation | Reference number |
|---|------------------|
| FREE Studio Plus - Operating Guide | 9MA10256 (ENG) |
| FREE Advance 7/18 IO – Instruction Sheet | 9IS54609 |
| FREE Advance 28/42 IO – Instruction Sheet | 9IS54473 |
| FREE Advance 28/42 IO isolated – Instruction Sheet | 9IS54655 |
| FREE EVE6000 / EVE10200 Expansion module – Instruction Sheet | 9IS54478 |
| FREE AVP1000 Display Color Touchscreen – Instruction Sheet | 9IS54479 |
| FREE AVP1000 Display Color Touchscreen Flush Mounting – Instruction Sheet | 9IS54608 |
| FREE AVK1000000500 Monochrome Display – Instruction Sheet | 9IS54800 |
| FREE EVS Plugin – Instruction Sheet | 9IS54405 |

You can download these technical publications, the present document and other technical information from our website www.eliwell.com.

Product Related Information

DANGER

HAZARD OF ELECTRIC SHOCK, EXPLOSION OR ARC FLASH

- Disconnect all power from all equipment including connected devices prior to removing any covers or doors, or installing or removing any accessories, hardware, cables, or wires except under the specific conditions specified in the appropriate hardware guide for this equipment.
- Always use a properly rated voltage sensing device to confirm the power is off where and when indicated.
- Replace and secure all covers, accessories, hardware, cables, and wires and confirm that a proper ground connection exists before applying power to the unit.
- Use only the specified voltage when operating this equipment and any associated products.

Failure to follow these instructions will result in death or serious injury.

This equipment has been designed to operate outside of any hazardous location, and exclusive of applications that generate, or have the potential to generate, hazardous atmospheres. Only install this equipment in zones known to be free, at all times, of hazardous atmospheres.

DANGER

POTENTIAL FOR EXPLOSION

- Install and use this equipment in non-hazardous locations only.
- Do not install and use this equipment in applications capable of generating hazardous atmospheres, such as those applications employing flammable refrigerants.

Failure to follow these instructions will result in death or serious injury.

For information concerning the use of control equipment in applications capable of generating hazardous materials, consult your local, regional, or national standards bureau or certification agency.

| |
|---|
| ▲ WARNING |
| <p>LOSS OF CONTROL</p> <ul style="list-style-type: none"> • The designer of any control scheme must consider the potential failure modes of control paths and, for certain critical control functions, provide a means to achieve a safe state during and after a path failure. Examples of critical control functions are emergency stop and overtravel stop, power outage and restart. • Separate or redundant control paths must be provided for critical control functions. • System control paths may include communication links. Consideration must be given to the implications of unanticipated transmission delays or failures of the link. • Observe all accident prevention regulations and local safety guidelines.¹ • Each implementation of this equipment must be individually and thoroughly tested for proper operation before being placed into service. <p>Failure to follow these instructions can result in death, serious injury, or equipment damage.</p> |

¹ For additional information, refer to NEMA ICS 1.1 (latest edition), "Safety Guidelines for the Application, Installation, and Maintenance of Solid State Control" and to NEMA ICS 7.1 (latest edition), "Safety Standards for Construction and Guide for Selection, Installation and Operation of Adjustable-Speed Drive Systems" or their equivalent governing your particular location.

| |
|--|
| ▲ WARNING |
| <p>UNINTENDED EQUIPMENT OPERATION</p> <ul style="list-style-type: none"> • Only use software approved by Eliwell for use with this equipment. • Update your application program every time you change the physical hardware configuration. <p>Failure to follow these instructions can result in death, serious injury, or equipment damage.</p> |

Terminology Derived from Standards

The technical terms, terminology, symbols and the corresponding descriptions in the information contained herein, or that appear in or on the products themselves, are generally derived from the terms or definitions of international standards.

In the area of functional safety systems, drives and general automation, this may include, but is not limited to, terms such as *safety, safety function, safe state, fault, fault reset, malfunction, failure, error, error message, dangerous, etc.*

Among others, these standards include:

| Standard | Description |
|------------------|---|
| IEC 61131-2:2007 | Programmable controllers, part 2: Equipment requirements and tests. |
| ISO 13849-1:2023 | Safety of machinery: Safety related parts of control systems. General principles for design. |
| EN 61496-1:2013 | Safety of machinery: Electro-sensitive protective equipment. Part 1: General requirements and tests. |
| ISO 12100:2010 | Safety of machinery — General principles for design — Risk assessment and risk reduction. |

| | |
|------------------|---|
| EN 60204–1:2006 | Safety of machinery — Electrical equipment of machines — Part 1: General requirements. |
| ISO 14119:2013 | Safety of machinery — Interlocking devices associated with guards — Principles for design and selection. |
| ISO 13850:2015 | Safety of machinery — Emergency stop — Principles for design. |
| IEC 62061:2021 | Safety of machinery — Functional safety of safety-related electrical, electronic, and electronic programmable control systems. |
| IEC 61508–1:2010 | Functional safety of electrical/electronic/programmable electronic safety-related systems: General requirements. |
| IEC 61508–2:2010 | Functional safety of electrical/electronic/programmable electronic safety-related systems: Requirements for electrical/electronic/programmable electronic safety-related systems. |
| IEC 61508–3:2010 | Functional safety of electrical/electronic/programmable electronic safety-related systems: Software requirements. |
| IEC 61784–3:2021 | Industrial communication networks — Profiles — Part 3: Functional safety fieldbuses — General rules and profile definitions. |
| 2006/42/EC | Machine Directive |
| 2014/30/EU | Electromagnetic Compatibility Directive |
| 2014/35/EU | Low Voltage Directive |

In addition, terms used in the present document may tangentially be used as they are derived from other standards such as:

| Standard | Description |
|------------------|---|
| IEC 60034 series | Rotating electrical machines. |
| IEC 61800 series | Adjustable speed electrical power drive systems. |
| IEC 61158 series | Digital data communications for measurement and control — Fieldbus for use in industrial control systems. |

Finally, the term *zone of operation* may be used in conjunction with the description of specific hazards, and is defined as it is for a *hazard zone* or *danger zone* in the *Machinery Directive (2006/42/EC)* and *ISO 12100:2010*.

NOTE: The aforementioned standards may or may not apply to the specific products cited in the present documentation. For more information concerning the individual standards applicable to the products described herein, see the characteristics tables for those product references.

Information on Non-Inclusive Terminology

As part of a group of responsible, inclusive companies, we are updating our communications and products that contain non-inclusive terminology. Until we complete this process, however, our content may still contain standardized industry terms that may be deemed inappropriate by our customers.

Overview

What's in This Part

| | |
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| FREE Advance Range Overview | 14 |
|-----------------------------------|----|

FREE Advance Range Overview

What's in This Chapter

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FREE Advance Logic Controller Offer Overview

General Description

FREE Advance Logic Controller are suitable for customized applications designed to control simple or complex machines:

- Air/water-cooled chiller
- Rooftop unit
- Heat pump
- Compressor rack
- Ventilation unit

The FREE Advance offer is made of:

- Controllers, page 15
- Expansion modules, page 16
- Communication modules, page 18
- Remote displays, page 19
- Accessories, page 20

Programming Software

In association with the controllers hardware, the FREE Studio Plus development tool is available to program and customize applications.

You can download FREE Studio Plus - Programming software for FREE Advance Logic Controller from Schneider-electric web site download centerEliwell web site download center.

The use of several programming languages in accordance with IEC 61131-3 regulations (programming standard for industrial control), makes it possible to develop new algorithms or entire programs easily, which can then be uploaded to the FREE Advance controllers via a PC and a Programming cable, helping to provide confidentiality with appropriate security.

For more information, refer to Connection Types, page 162.

Controller Range Overview

Type Code

Controller type code:

| Type code description | | | | | | | | | |
|----------------------------|--|---|----|---|---|----|---|---|----|
| AVD1260060500 | AV | D | 12 | 6 | 0 | 06 | 0 | 5 | 00 |
| Product family | FREE Advance series | | | | | | | | |
| Physical feature | D = Built-in Display C = Blind | | | | | | | | |
| Number of digital outputs | 3 6 8 12 | | | | | | | | |
| Number of analog outputs | 0 2 4 6 | | | | | | | | |
| Digital output type | 00: The digital outputs are relay SS: 2 digital outputs are SSR NOTE: Only one digit in case of 12 digital outputs. | | | | | | | | |
| Embedded Communication | 06 = RS-485 and Ethernet based communication protocols 05 = RS-485 based communication protocols | | | | | | | | |
| Power supply isolation (1) | I: Power Supply Isolated | | | | | | | | |
| Power supply | 5 = 24 Vac/dc | | | | | | | | |
| Not relevant | 00 | | | | | | | | |
| (1) Only for 28 and 42 I/O | | | | | | | | | |

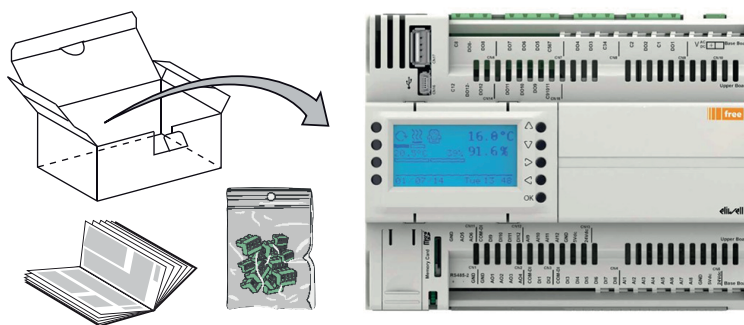
Controllers References

| Reference | Complementary product family | Inputs/Outputs | | | | | Micro SD card | USB | | Communication | | |
|------------------------------------|------------------------------|----------------|----|----|-----------|----|---------------|-------|------------|---------------|------------|----------------|
| | | Display | DI | DO | AI | AO | | USB A | USB Mini-B | 2 RS-485 | 1 Ethernet | 1 CAN Exp. bus |
| 7 Inputs/Outputs , page 51 | | | | | | | | | | | | |
| AVC3000060500 | /C/L/U(/SSR)(/I) | - | 2 | 3 | 2 | 0 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| AVD3000060500 | | ✓ | | | | | | | | | | |
| 18 Inputs/Outputs , page 53 | | | | | | | | | | | | |
| AVC6200060500 | /C/L/U(/SSR)(/I) | - | 2 | 6 | 8 | 2 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| AVD6200060500 | | ✓ | | | | | | | | | | |
| AVD62SS060500 | | | | | 4 + 2 SSR | | | | | | | |
| AVC6200050500 | /C(/I) | - | 2 | 6 | 8 | 2 | - | - | ✓ | ✓ | - | ✓ |

| Reference | Complementary product family | Display | Inputs/Outputs | | | | Micro SD card | USB | | Communication | | |
|-----------------------------------|------------------------------|---------|----------------|----|------------|----|---------------|-------|------------|---------------|------------|----------------|
| | | | DI | DO | AI | AO | | USB A | USB Mini-B | 2 RS-485 | 1 Ethernet | 1 CAN Exp. bus |
| AVD6200050500 | | ✓ | | | | | | | | | | |
| 28 Inputs/Outputs, page 55 | | | | | | | | | | | | |
| AVC8400060500 | /C/L/U(/SSR)(/I) | - | 8 | 8 | 8 | 4 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| AVC8400061500 | | ✓ | | | | | | | | | | |
| AVD8400060500 | | | | | | | | | | | | |
| AVD8400061500 | | | | | | | | | | | | |
| AVD84SS060500 | | | | | 6 + 2 SSR | | | | | | | |
| AVD84SS061500 | | | | | | | | | | | | |
| AVC8400050500 | /C(/I) | - | 8 | 8 | 8 | 4 | - | - | ✓ | ✓ | - | ✓ |
| AVD8400050500 | | ✓ | | | | | | | | | | |
| 42 Inputs/Outputs, page 58 | | | | | | | | | | | | |
| AVC1260060500 | /C/L/U(/SSR)(/I) | - | 12 | 12 | 12 | 6 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| AVC1260061500 | | ✓ | | | | | | | | | | |
| AVD1260060500 | | | | | | | | | | | | |
| AVD1260061500 | | | | | | | | | | | | |
| AVD126S060500 | | | | | 10 + 2 SSR | | | | | | | |
| AVD126S061500 | | | | | | | | | | | | |
| AVC1260051500 | /C(/I) | - | 12 | 12 | 12 | 6 | - | - | ✓ | ✓ | - | ✓ |
| AVD1260051500 | | ✓ | | | | | | | | | | |

The controller runs on 24 Vac/dc power supply.

AV.....6•500 / AV.....5•500 Delivery Content



Expansion Modules Range Overview

Type Code

Expansion module type code:

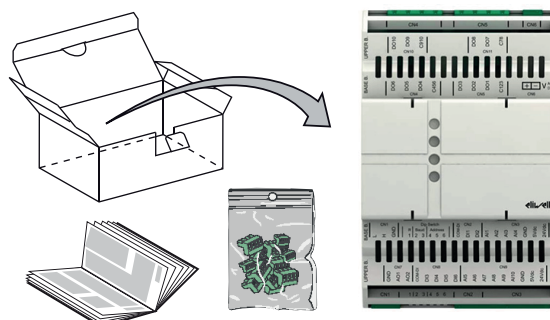
| Type code description | | | | | | | | | | |
|---------------------------|-----------------------|---|--|---|----|---------------|---|---|----|--|
| EVE1020000500 | E-V | E | 10 | 2 | 0 | 00 | 0 | 5 | 00 | |
| Product family | FREE Evolution series | | | | | | | | | |
| Physical feature | E = Expansion module | | | | | | | | | |
| Number of digital outputs | | | 6 | | 10 | | | | | |
| Number of analog outputs | | | 0 | | 2 | | | | | |
| Digital output type | | | 00: The digital outputs are relay SS: 2 digital outputs are SSR NOTE: Only one digit in case of 10 digital outputs. | | | | | | | |
| Not relevant | | | | | | 00 | | | | |
| Not relevant | | | | | | 0 | | | | |
| Power supply | | | | | | 5 = 24 Vac/dc | | | | |
| Not relevant | | | | | | 00 | | | | |

Expansion Modules References

| Reference | Inputs/Outputs | | | | 1 CAN Exp. bus | 1 TTL ⁽¹⁾ | Compatible controllers |
|--|----------------|----|----|----|----------------|----------------------|--|
| | DI | DO | AI | AO | | | |
| 12 Inputs/Outputs, page 62 | | | | | | | |
| EVE6000000500 | 2 | 6 | 4 | - | ✓ | ✓ | AV.....6•500 ⁽²⁾ AV.....5•500 ⁽²⁾ |
| 28 Inputs/Outputs, page 64 | | | | | | | |
| EVE1020000500 | 6 | 10 | 10 | 2 | ✓ | ✓ | AV.....6•500 ⁽²⁾ AV.....5•500 ⁽²⁾ |
| (1) For service only. | | | | | | | |
| (2) Also compatible with FREE Evolution controller range. | | | | | | | |

The expansion modules run on 24 Vac/dc power supply.

EVE.....0500 Delivery Content



Communication Modules Range Overview

Overview

This section presents communication modules.

Communication Modules References

| Reference | Description | Terminal type | Compatible controllers |
|---------------|--|-------------------------------------|-----------------------------|
| EVS00CA000000 | CAN | 2 screw terminal blocks | AV•••••6•500 |
| EVS0LON000000 | LonWorks | 1 screw terminal block | AV•••••5•500 ⁽¹⁾ |
| EVS00R4000000 | Modbus SL (RS-485) | 2 screw terminal blocks | |
| EVS10R2000000 | RS-232 serial link, Relay output | 1 SUB-D 9 1 screw terminal block | |
| EVS00BM000000 | Modbus SL, and BACnet MS/TP | 2 screw terminal blocks | |
| EVS00ET000000 | Ethernet, Modbus TCP, and BACnet/IP | 1 RJ45 | AV•••••5•500 ⁽¹⁾ |
| EVS00EB000000 | Ethernet, Modbus TCP, BACnet/IP, Modbus SL, and BACnet MS/TP | 1 RJ45 2 screw terminal blocks | |

(1) Also compatible with FREE Evolution controller range.

For further information about communication modules, refer to the FREE EVS Plugin Instruction Sheet 9IS54405.

Remote Display Range Overview

Type Code

Remote display type code:

| Type code description | | | | | | | | | |
|------------------------------|---|---|---|---|----|-----|---|---|----|
| AVP13000W0500 | AV | P | 1 | 3 | 00 | 0-W | 0 | 5 | 00 |
| Product family | FREE Advance series | | | | | | | | |
| Complementary product family | P = Remote display with touch interface K = Remote display with keys | | | | | | | | |
| Number of serial connections | 1 | | | | | | | | |
| Number of embedded sensors | 0 = No sensor embedded 1 = Temperature sensor 2 = Temperature and relative humidity sensor 3 = Temperature, relative humidity, and presence sensor (PIR) | | | | | | | | |
| Color | 00: No color option available 0G: Gray color 0W: White color | | | | | | | | |
| Mounting type | 00 = Vertical mounting 0W = Vertical mounting 0P = Flush mounting | | | | | | | | |
| Not relevant | 0 | | | | | | | | |
| Power supply | 5 = 24 Vac/dc | | | | | | | | |
| Not relevant | 00 | | | | | | | | |

Remote Displays References

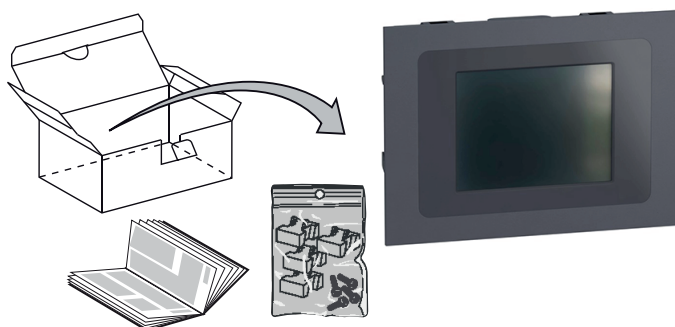
| Reference | Embedded sensors | | | 1 RS-485 | 1 USB Micro-B | 1 CAN | Compatible controllers |
|-------------------------|------------------|----------|----------|----------|---------------|-------|-------------------------------|
| | Temperature | Humidity | Presence | | | | |
| AVP11000W0500, page 109 | ✓ | - | - | ✓ | ✓ | - | AV•••••6•500 |
| AVP12000W0500, page 109 | ✓ | ✓ | - | ✓ | ✓ | - | AV•••••5•500 |
| AVP13000W0500, page 109 | ✓ | ✓ | ✓ | ✓ | ✓ | - | EV•7500 |
| AVP100G0P0500, page 110 | - | - | - | ✓ | ✓ | - | SMP•••• / SMD•••• |
| AVP100W0P0500, page 110 | - | - | - | ✓ | ✓ | - | /SMC•••• |
| | | | | | | | Third-party Modbus SL devices |
| AVK1000000500, page 111 | - | - | - | - | - | ✓ | AV•••••6•500 AV•••••5•500 |

The remote displays run on 24 Vac/dc power supply.

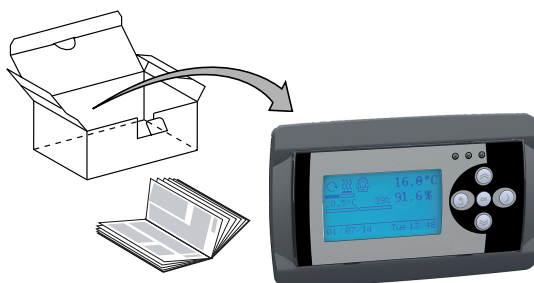
AVP1•000W0500 Delivery Content



AVP100•0P0500 Delivery Content



AVK1000000500 Delivery Content



Accessories

Overview

This section describes the accessories.

Mounting and Wiring Accessories References

| Description | | Use | Reference |
|--------------------------------------|-------|--|---------------|
| Vertical surface support for display | White | To install a AVP100•0P0500 on a vertical surface | AVA00WMRC0000 |
| | Gray | | AVA00WMRC0001 |

| Description | | Use | Reference |
|------------------|-------|--|---------------|
| | White | To install a AVK1000000500 on a vertical surface | EVA00WMRC0000 |
| | Gray | | EVA00WMRC0001 |
| 12 clips-on lock | | To install the AV***** controllers and the expansion modules on a panel surface, page 39 | AVA00PMCL0000 |

Global Features

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| Wiring Best Practices | 26 |
| Installation | 32 |

Before Starting

What's in This Chapter

Before Starting23

Before Starting

Before Starting

Read and understand this chapter before beginning the installation of your system.

Pay particular attention in conforming to any safety information, different electrical requirements, and normative standards that would apply to your machine or process in the use of this equipment.

The use and application of the information contained herein require expertise in the design and programming of automated control systems. Only you, the user, machine builder or integrator, can be aware of all the conditions and factors present during installation and setup, operation, and maintenance of the machine or process, and can therefore determine the automation and associated equipment and the related safeties and interlocks which can be effectively and properly used. When selecting automation and control equipment, and any other related equipment or software, for a particular application, you must also consider any applicable local, regional or national standards and/or regulations.

⚠ WARNING

REGULATORY INCOMPATIBILITY

Ensure that all equipment applied and systems designed comply with all applicable local, regional, and national regulations and standards.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Disconnecting Power

All options and modules should be assembled and installed before installing the control system on a mounting rail, onto a mounting plate or in a panel. Remove the control system from its mounting rail, mounting plate or panel before disassembling the equipment.

⚡⚠ DANGER

HAZARD OF ELECTRIC SHOCK, EXPLOSION OR ARC FLASH

- Disconnect all power from all equipment including connected devices prior to removing any covers or doors, or installing or removing any accessories, hardware, cables, or wires except under the specific conditions specified in the appropriate hardware guide for this equipment.
- Always use a properly rated voltage sensing device to confirm the power is off where and when indicated.
- Replace and secure all covers, accessories, hardware, cables, and wires and confirm that a proper ground connection exists before applying power to the unit.
- Use only the specified voltage when operating this equipment and any associated products.

Failure to follow these instructions will result in death or serious injury.

Programming Considerations

The products described in this manual have been designed and tested using Eliwell programming, configuration, and maintenance software products.

⚠ WARNING

UNINTENDED EQUIPMENT OPERATION

- Only use software approved by Eliwell for use with this equipment.
- Update your application program every time you change the physical hardware configuration.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Operating Environment

This equipment has been designed to operate outside of any hazardous location, and exclusive of applications that generate, or have the potential to generate, hazardous atmospheres. Only install this equipment in zones known to be free, at all times, of hazardous atmospheres.

⚠ DANGER

POTENTIAL FOR EXPLOSION

- Install and use this equipment in non-hazardous locations only.
- Do not install and use this equipment in applications capable of generating hazardous atmospheres, such as those applications employing flammable refrigerants.

Failure to follow these instructions will result in death or serious injury.

For information concerning the use of control equipment in applications capable of generating hazardous materials, consult your local, regional, or national standards bureau or certification agency.

⚠ WARNING

UNINTENDED EQUIPMENT OPERATION

Install and operate this equipment according to the conditions described in the Environmental Characteristics.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Installation Considerations

⚠ WARNING

UNINTENDED EQUIPMENT OPERATION

- Use appropriate safety interlocks where personnel and/or equipment hazards exist.
- Install and operate this equipment in an enclosure appropriately rated for its intended environment and secured by a keyed or tooled locking mechanism.
- Use the sensor and actuator power supplies only for supplying power to the sensors or actuators connected to the module.
- Power line and output circuits must be wired and fused in compliance with local and national regulatory requirements for the rated current and voltage of the particular equipment.
- Do not use this equipment in safety-critical machine functions unless the equipment is otherwise designated as functional safety equipment and conforming to applicable regulations and standards.
- Do not disassemble, repair, or modify this equipment.
- Do not connect any wiring to unused connections, or to connections designated as No Connection (N.C.).

Failure to follow these instructions can result in death, serious injury, or equipment damage.

NOTE: JDYX2 or JDYX8 fuse types are UL-recognized and CSA approved.

The FREE Advance controllers are intended for Top Hat Section Rail (DIN rail) mounting, panel mounting, or wall mounting.

Care must be taken to avoid damage from electrostatic sources when handling this equipment. In particular exposed connectors and, in some cases, exposed printed circuit boards are exceptionally vulnerable to electrostatic discharge.

⚠ WARNING

UNINTENDED EQUIPMENT OPERATION DUE TO ELECTROSTATIC DISCHARGE DAMAGE

- Keep equipment in the protective conductive packaging until you are ready to install the equipment.
- Only install equipment in approved enclosures and / or locations that prevent casual access and provide electrostatic discharge protection.
- Use a conductive wrist strap or equivalent field force protective device attached to an earth ground when handling sensitive equipment.
- Always discharge yourself by touching a grounded surface or approved antistatic mat before handling the equipment.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

For more information about enclosures, refer to the definition found in IEC 1000-4-2.

Wiring Best Practices


What's in This Chapter


Wiring Best Practices.....26

Wiring Best Practices

Wiring Best Practices

The following information describes the wiring guidelines and associated best practices to be respected when using a FREE Advance Logic Controller.

| |
|---|
|  DANGER |
| HAZARD OF ELECTRIC SHOCK, EXPLOSION OR ARC FLASH |
| <ul style="list-style-type: none"> • Disconnect all power from all equipment including connected devices prior to removing any covers or doors, or installing or removing any accessories, hardware, cables, or wires except under the specific conditions specified in the appropriate hardware guide for this equipment. • Always use a properly rated voltage sensing device to confirm the power is off where and when indicated. • Replace and secure all covers, accessories, hardware, cables, and wires and confirm that a proper ground connection exists before applying power to the unit. • Use only the specified voltage when operating this equipment and any associated products. |
| Failure to follow these instructions will result in death or serious injury. |

| |
|--|
|  WARNING |
| LOSS OF CONTROL |
| <ul style="list-style-type: none"> • The designer of any control scheme must consider the potential failure modes of control paths and, for certain critical control functions, provide a means to achieve a safe state during and after a path failure. Examples of critical control functions are emergency stop and overtravel stop, power outage and restart. • Separate or redundant control paths must be provided for critical control functions. • System control paths may include communication links. Consideration must be given to the implications of unanticipated transmission delays or failures of the link. • Observe all accident prevention regulations and local safety guidelines.¹ • Each implementation of this equipment must be individually and thoroughly tested for proper operation before being placed into service. |
| Failure to follow these instructions can result in death, serious injury, or equipment damage. |

¹ For additional information, refer to NEMA ICS 1.1 (latest edition), "Safety Guidelines for the Application, Installation, and Maintenance of Solid State Control" and to NEMA ICS 7.1 (latest edition), "Safety Standards for Construction and Guide for Selection, Installation and Operation of Adjustable-Speed Drive Systems" or their equivalent governing your particular location.

Wiring Guidelines

The following rules must be applied when wiring FREE Advance offer product range:

- I/O and communication wiring must be kept separate from the power wiring. Route these two types of wiring in separate cable ducting.
- Verify that the operating conditions and environment are within the specification values.
- Use proper wire sizes to meet voltage and current requirements.
- Use copper conductors (required).
- Use twisted pair, shielded cables for analog, and/or fast I/O.
- Use twisted pair, shielded cables for networks, and fieldbus.

Use shielded, properly grounded cables for all analog and high-speed inputs or outputs and communication connections. If you do not use shielded cable for these connections, electromagnetic interference can cause signal degradation. Degraded signals can cause the controller or attached modules and equipment to perform in an unintended manner.








| |
|---|
| ⚠ WARNING |
| <p>UNINTENDED EQUIPMENT OPERATION</p> <ul style="list-style-type: none"> • Use shielded cables for all fast I/O, analog I/O and communication signals. • Ground cable shields for all analog I/O, fast I/O and communication signals at a single point¹. • Route communication and I/O cables separately from power cables. <p>Failure to follow these instructions can result in death, serious injury, or equipment damage.</p> |

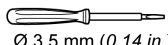

¹ Multipoint grounding is permissible if connections are made to an equipotential ground plane dimensioned to help avoid cable shield damage in the event of power system short-circuit currents.

NOTE: Surface temperatures may exceed 60 °C (140 °F). Route primary wiring (wires connected to power mains) separately and apart from secondary wiring (extra low voltage wiring coming from intervening power sources). If that is not possible, double insulation is required such as conduit or cable gains.

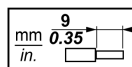








Rules for Screw Terminal Block

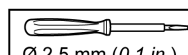

The following table presents the cable types and wire sizes for a 5.08 mm (0.20 in.) or 5.00 mm (0.197 in.) pitch screw terminal block:

| | | | | | | | | |
|--------------------------------|------------------|---|---|---|---|--|---|---|
| $\frac{\text{mm}}{\text{in.}}$ | $\frac{7}{0.28}$ |  |  |  |  |  |  |  |
| mm ² | 0.2...2.5 | 0.2...2.5 | 0.25...2.5 | 0.25...2.5 | 2 x 0.2...1 | 2 x 0.2...1.5 | 2 x 0.25...1 | 2 x 0.5...1.5 |
| AWG | 24...14 | 24...14 | 22...14 | 22...14 | 2 x 24...18 | 2 x 24...16 | 2 x 22...18 | 2 x 20...16 |

| | |
|---|---|
|  |  |
| Ø 3,5 mm (0.14 in.) | |
| N•m | 0.5...0.6 |
| lb-in | 4.42...5.31 |

The following table presents the cable types and wire sizes for a 3.81 mm (0.15 in.) or 3.50 mm (0.14 in.) pitch screw terminal block:

| | | | | | | | | |
|---|---|---|---|---|--|---|---|---|
|  |  |  |  |  |  |  |  |  |
| mm ² | 0.14...1.5 | 0.14...1.5 | 0.25...1.5 | 0.25...0.5 | 2 x 0.08...0.5 | 2 x 0.08...0.75 | 2 x 0.25...0.34 | 2 x 0.5 |
| AWG | 26...16 | 26...16 | 22...16 | 22...20 | 2 x 28...20 | 2 x 28...20 | 2 x 24...22 | 2 x 20 |

| | | | |
|---|---|-------|-------------|
|  |  | N*m | 0.22...0.25 |
| Ø 2,5 mm (0.1 in.) | | lb-in | 1.95...2.21 |

The use of copper conductors is required.

⚠️ ⚠️ DANGER

LOOSE WIRING CAUSES ELECTRIC SHOCK

- Tighten connections in conformance with the torque specifications.
- Do not insert more than one wire per connector of the terminal block unless using the cable ends (ferrules) specified above.

Failure to follow these instructions will result in death or serious injury.

⚠️ WARNING

FIRE HAZARD

- Use only the recommended wire sizes for the current capacity of the I/O channels and power supplies.
- For relay output wiring up to 2 A, use conductors of at least 0.5 mm² (AWG 20) with a temperature rating of at least 80 °C (176 °F).
- For relay output wiring of 3 A, use conductors of at least 1.5 mm² (AWG 16) with a temperature rating of at least 80 °C (176 °F).
- For common conductors of relay output wiring of 9 A, or relay output wiring greater than 3 A, use conductors of at least 2.0 mm² (AWG 12) with a temperature rating of at least 80 °C (176 °F).

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Protecting Outputs from Inductive Load Damage

Depending on the load, a protection circuit may be needed for the relay outputs. Inductive loads using DC voltages may create voltage reflections resulting in overshoot that will damage or shorten the life of output devices.

⚠️ CAUTION

OUTPUT CIRCUIT DAMAGE DUE TO INDUCTIVE LOADS

Use an appropriate external protective circuit or device to reduce the risk of inductive direct current load damage.

Failure to follow these instructions can result in injury or equipment damage.

Choose a protection circuit from the following diagrams according to the power supply used. Connect the protection circuit to the outside of the controller or relay output module.

If your controller or module contains relay outputs, these types of outputs can support up to 240 Vac. Inductive damage to these types of outputs can result in welded contacts and loss of control. Each inductive load must include a protection

device such as a peak limiter, RC circuit or flyback diode. Capacitive loads are not supported by these relays.

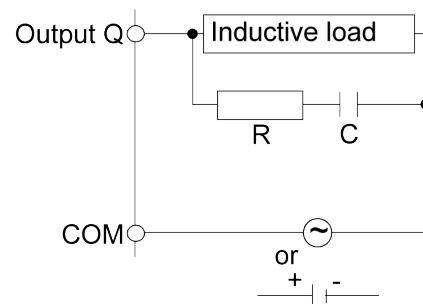
⚠ WARNING

RELAY OUTPUTS WELDED CLOSED

- Always protect relay outputs from inductive alternating current load damage using an appropriate external protective circuit or device.
- Do not connect relay outputs to capacitive loads.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

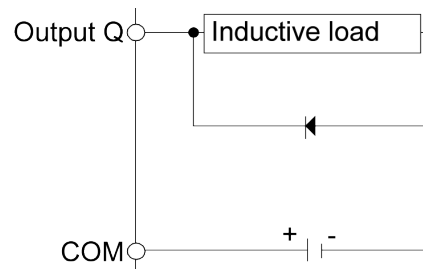
Protective circuit A: this protection circuit can be used for both AC and DC load power circuits.



C Value from 0.1 to 1 μF

R Resistor of approximately the same resistance value as the load

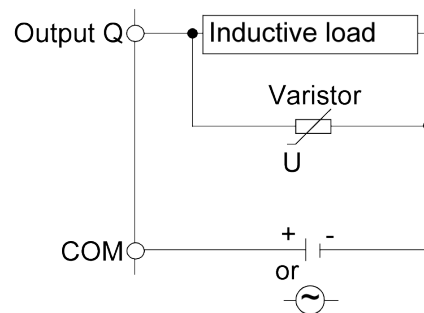
Protective circuit B: this protection circuit can be used for DC load power circuits.



Use a diode with the following ratings:

- Reverse withstand voltage: power voltage of the load circuit x 10.
- Forward current: more than the load current.

Protective circuit C: this protection circuit can be used for both AC and DC load power circuits.



In applications where the inductive load is switched on and off frequently and/or rapidly, verify that the continuous energy rating (J) of the varistor exceeds the peak load energy by 20 % or more.

NOTE: Place protection devices as close to the load as possible.

Special Handling Considerations

Care must be taken to avoid damage from electrostatic sources when handling this equipment. In particular exposed connectors and, in some cases, exposed printed circuit boards are exceptionally vulnerable to electrostatic discharge.

⚠ WARNING

UNINTENDED EQUIPMENT OPERATION DUE TO ELECTROSTATIC DISCHARGE DAMAGE

- Keep equipment in the protective conductive packaging until you are ready to install the equipment.
- Only install equipment in approved enclosures and / or locations that prevent casual access and provide electrostatic discharge protection.
- Use a conductive wrist strap or equivalent field force protective device attached to an earth ground when handling sensitive equipment.
- Always discharge yourself by touching a grounded surface or approved antistatic mat before handling the equipment.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Analog Inputs-Probes

Temperature probes have no connection polarity and can be extended using a normal bipolar cable.

The extension of the probes wiring influences the electromagnetic compatibility (EMC) of the instrument

Verify the polarity for probes which have a specific connection polarity.

NOTICE

INOPERABLE EQUIPMENT

Verify all wiring connections before applying power.

Failure to follow these instructions can result in equipment damage.

Do not power any connected devices that are externally powered without also applying power to the FREE Advance.

NOTICE

INOPERABLE EQUIPMENT

Ensure that the controller has power applied when applying power to other connected and externally powered devices.

Failure to follow these instructions can result in equipment damage.

Signal leads (probes, digital inputs, communication, and the electronic supply) must be routed separately from power cables.

Installation

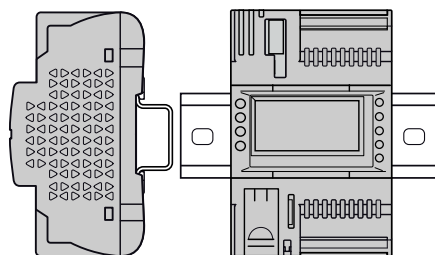
What's in This Chapter

- AV•30••••0500 / AV•62••••0500 Controllers Mounting Positions 32
- AV•84••••500 / AV•126••••500 Controllers Mounting Positions 33
- EVE•••••0500 Expansion Modules Mounting Positions 34
- Controllers and Expansion Modules Clearances 35
- Top Hat Section Rail (DIN Rail)..... 36
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- AVP1•000W0500 Remote Display Installation 40
- AVP100•0P0500 Remote Display Installation 42
- AVK1000000500 Remote Display Installation 45

AV•30••••0500 / AV•62••~•0500 Controllers Mounting Positions

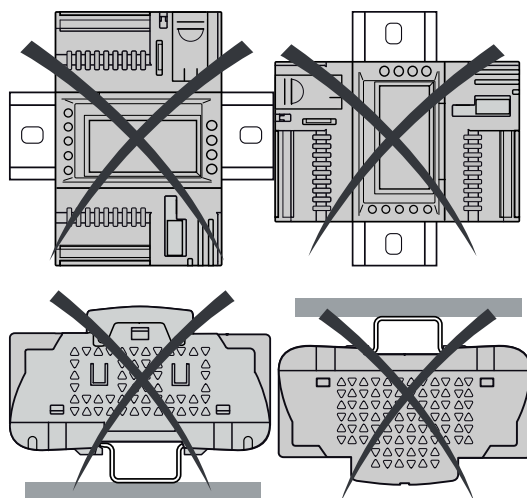
Correct Mounting Position

AV•30••••0500 / AV•62••~•0500 controllers must be mounted horizontally on a vertical plane as shown in the figure below:



Incorrect Mounting Position

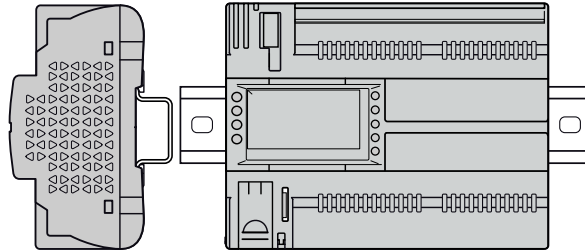
AV•30••~•0500 / AV•62••~•0500 controllers cannot be mounted neither vertically, nor horizontally backward:



AV•84•••••500 / AV•126•••••500 Controllers Mounting Positions

Correct Mounting Position

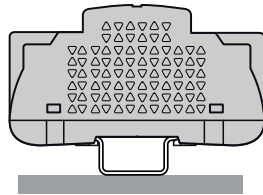
AV•84•••••500 / AV•126•••••500 controllers should be mounted horizontally on a vertical plane as shown in the figure below:



Acceptable Mounting Position

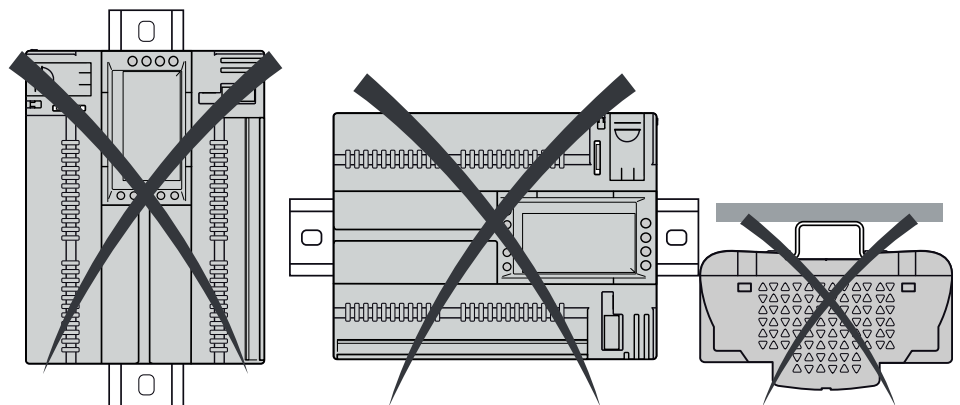
AV•8400•••500 / AV•1260•••500 controllers can be mounted horizontally upward with a temperature derating (maximum ambient temperature: 60 °C (140 °F)).

AVD84SS06I500 / AVD126S06I500 controllers can be mounted horizontally upward with a temperature derating (maximum ambient temperature: 55 °C (131 °F)).

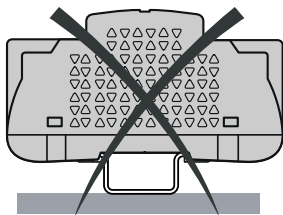


Incorrect Mounting Position

AV•84••~500 / AV•126••~500 controllers cannot be mounted neither vertically, nor horizontally backward:



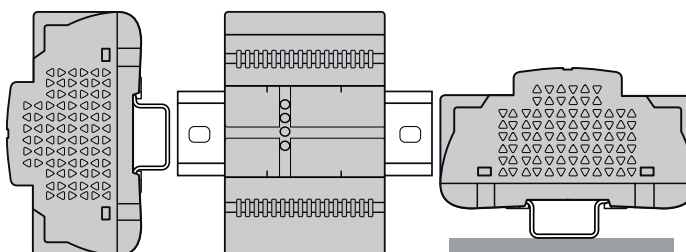
AVD84SS060500 / AVD126S060500 controllers cannot be mounted horizontally upward:



EVE.....0500 Expansion Modules Mounting Positions

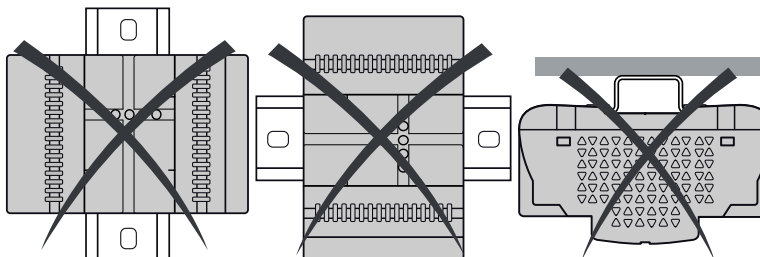
Correct Mounting Position

EVE.....0500 expansion modules must be mounted horizontally on a vertical plane or horizontally upward as shown in the figure below:



Incorrect Mounting Position

EVE.....0500 expansion modules cannot be mounted neither vertically, nor horizontally backward:



Controllers and Expansion Modules Clearances

Minimum Clearances

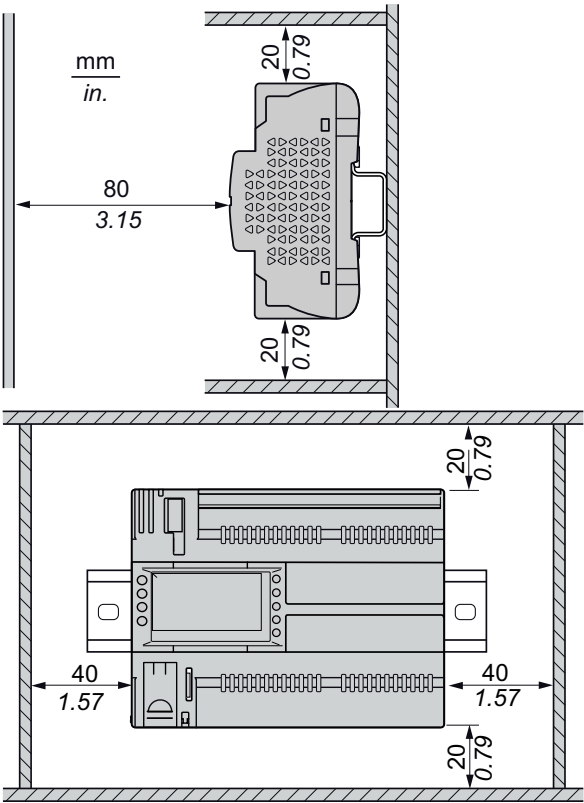
| |
|---|
| ▲ WARNING |
| <p>UNINTENDED EQUIPMENT OPERATION</p> <ul style="list-style-type: none"> Place devices dissipating the most heat at the top of the cabinet and ensure adequate ventilation. Avoid placing this equipment next to or above devices that might cause overheating. Install the equipment in a location providing the minimum clearances from all adjacent structures and equipment as directed in this document. Install all equipment in accordance with the specifications in the related documentation. <p>Failure to follow these instructions can result in death, serious injury, or equipment damage.</p> |

AV..... controllers and expansion modules have been designed as IP20 products and must be installed in an enclosure appropriately rated for its intended environment and secured by a keyed or tooled locking mechanism.

There are 3 types of clearances between:

- The FREE Advance device and the sides of the cabinet (including the panel door).
- The FREE Advance device terminal blocks and the wiring ducts. This distance reduces electromagnetic interference between the controller and the wiring ducts.
- The FREE Advance device and other heat generating devices installed in the same cabinet.

The following figure shows the minimum clearances that apply to AV..... references:



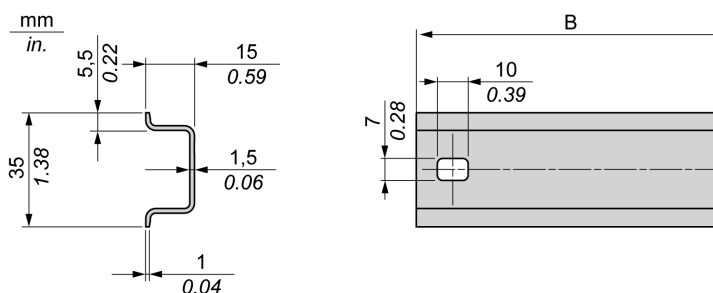
Top Hat Section Rail (DIN Rail)

Dimensions of Top Hat Section Rail (DIN Rail)

You can mount the controller and expansion module on a 35 mm (1.38 in.) top hat section rail (DIN rail). It can be attached to a smooth mounting surface or suspended from a EIA rack or mounted in a NEMA cabinet.

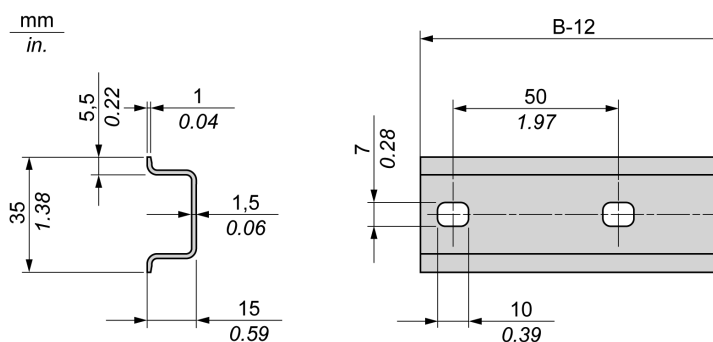
Symmetric Top Hat Section Rails (DIN Rail)

The following illustration and table show the references of the top hat section rails (DIN rail) for the wall-mounting range:



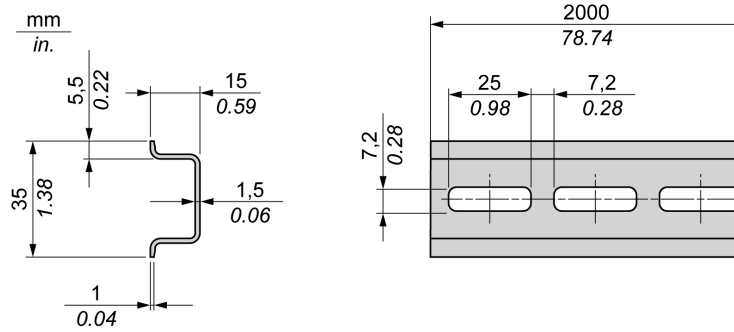
| Schneider Electric Reference | Type | Rail length (B) |
|------------------------------|------|--------------------|
| NSYSDR50A | A | 450 mm (17.71 in.) |
| NSYSDR60A | A | 550 mm (21.65 in.) |
| NSYSDR80A | A | 750 mm (29.52 in.) |
| NSYSDR100A | A | 950 mm (37.40 in.) |

The following illustration and table show the references of the symmetric top hat section rails (DIN rail) for the metal enclosure range:



| Schneider Electric Reference | Type | Rail length (B-12 mm) |
|------------------------------|------|-----------------------|
| NSYSDR60 | A | 588 mm (23.15 in.) |
| NSYSDR80 | A | 788 mm (31.02 in.) |
| NSYSDR100 | A | 988 mm (38.89 in.) |
| NSYSDR120 | A | 1188 mm (46.77 in.) |

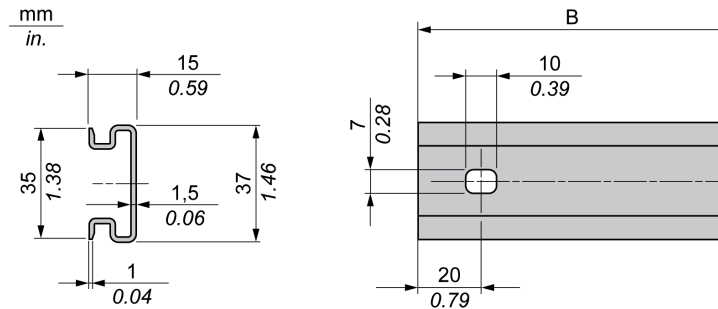
The following illustration and table shows the references of the symmetric top hat section rails (DIN rail) of 2000 mm (78.74 in.):



| Schneider Electric Reference | Type | Rail length |
|---------------------------------|------|---------------------|
| NSYSDR200 ¹ | A | 2000 mm (78.74 in.) |
| NSYSDR200D ² | A | |
| 1 Unperforated galvanized steel | | |
| 2 Perforated galvanized steel | | |

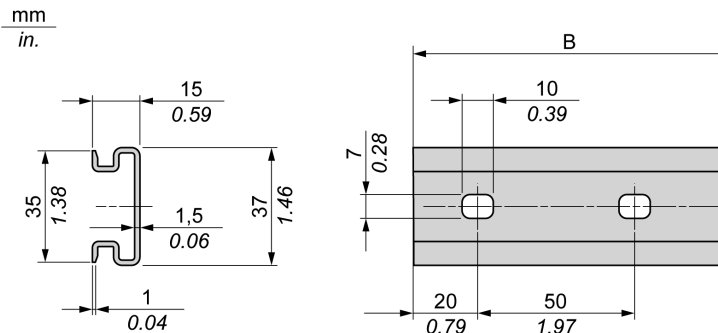
Double-Profile Top Hat Section Rails (DIN Rail)

The following illustration and table show the references of the double-profile top hat section rails (DIN rails) for the wall-mounting range:



| Schneider Electric Reference | Type | Rail length (B) |
|------------------------------|------|--------------------|
| NSYDPR25 | W | 250 mm (9.84 in.) |
| NSYDPR35 | W | 350 mm (13.77 in.) |
| NSYDPR45 | W | 450 mm (17.71 in.) |
| NSYDPR55 | W | 550 mm (21.65 in.) |
| NSYDPR65 | W | 650 mm (25.60 in.) |
| NSYDPR75 | W | 750 mm (29.52 in.) |

The following illustration and table show the references of the double-profile top hat section rails (DIN rail) for the floor-standing range:



| Schneider Electric Reference | Type | Rail length (B) |
|------------------------------|------|---------------------|
| NSYDPR60 | F | 588 mm (23.15 in.) |
| NSYDPR80 | F | 788 mm (31.02 in.) |
| NSYDPR100 | F | 988 mm (38.89 in.) |
| NSYDPR120 | F | 1188 mm (46.77 in.) |

Controllers and Expansion Modules Installation

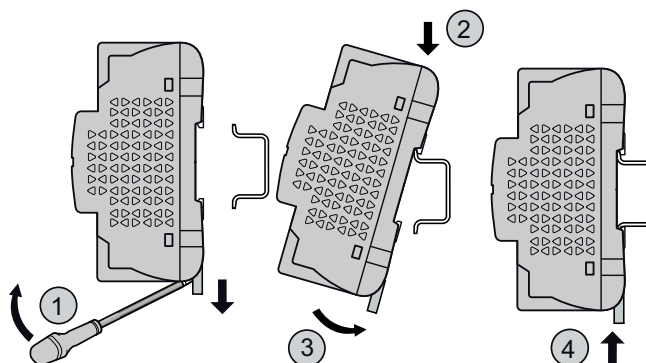
Overview

This section describes how to install and remove a AV..... controller or expansion module from a top hat section rail (DIN rail).

Installing on a Top Hat Section Rail (DIN Rail)

The following procedure describes how to install a controller or an expansion module on a top hat section rail (DIN rail):

| Step | Action |
|------|---|
| 1 | Move the two spring docking devices to their standby position (use a screwdriver to press against the relative compartments). |
| 2 | Position the top groove of the controller or the expansion modules on the top edge of the Top Hat Section Rail (DIN rail). |
| 3 | Press the assembly against the Top Hat Section Rail (DIN rail). |
| 4 | Press the spring docking devices to put them into the locked position. |



Removing from a Top Hat Section Rail (DIN Rail)

The following procedure describes how to remove a controller or an expansion module from a top hat section rail (DIN rail):

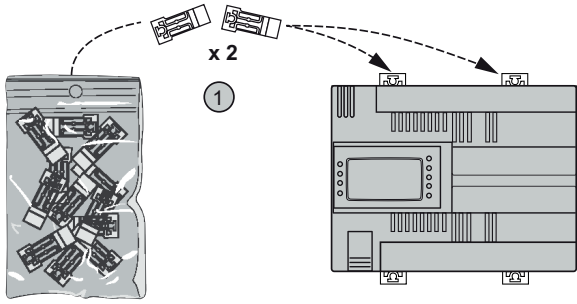
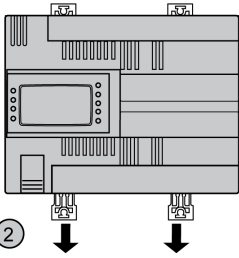
| Step | Action |
|------|---|
| 1 | Remove the power from the controller or the expansion module. |
| 2 | Insert a flat screwdriver into the spring docking devices. |
| 3 | Pull down the spring docking device to move it to its standby position. |
| 4 | Pull the controller or the expansion module from the top hat section rail (DIN rail) from the bottom. |

Panel Installation

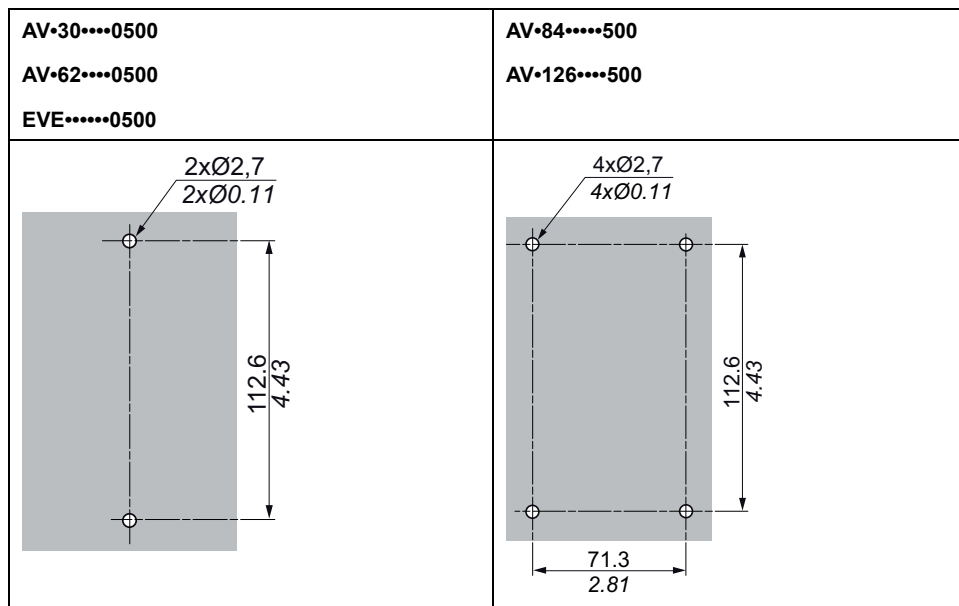
To install the controllers and expansion modules on a panel you must use clip-on locks.

NOTE: Upper clip-on locks are not provided with the logic controllers and must be ordered separately, page 20. Only one additional upper clip-on lock is necessary for AV•30•••60500, AV•62••••0500, and EVE•••••0500.

The following procedure shows how to install a AV•84•••••500 or a AV•126•••••500 controller on a panel using the clip-on locks. The same procedure shall be followed for the AV•••••6•500 / AV•••••5•500 / EVE•••••0500:

| Step | Action |
|------|---|
| 1 | Install the 2 upper clip-on locks  |
| 2 | Move the 2 lower clip-on locks to their standby position  |
| 3 | Secure the device in position with 4 screws. Refer to the mounting holes layout, page 40. |

Mounting Holes Layout



AVP1•000W0500 Remote Display Installation

AVP1•000W0500 Panel installation

The AVP1•000W0500 remote display can be mounted horizontally or vertically on a vertical wall.

AVP1•000W0500 display incorporates a temperature sensor. To function correctly, air must circulate through the product to accurately determine the temperature.

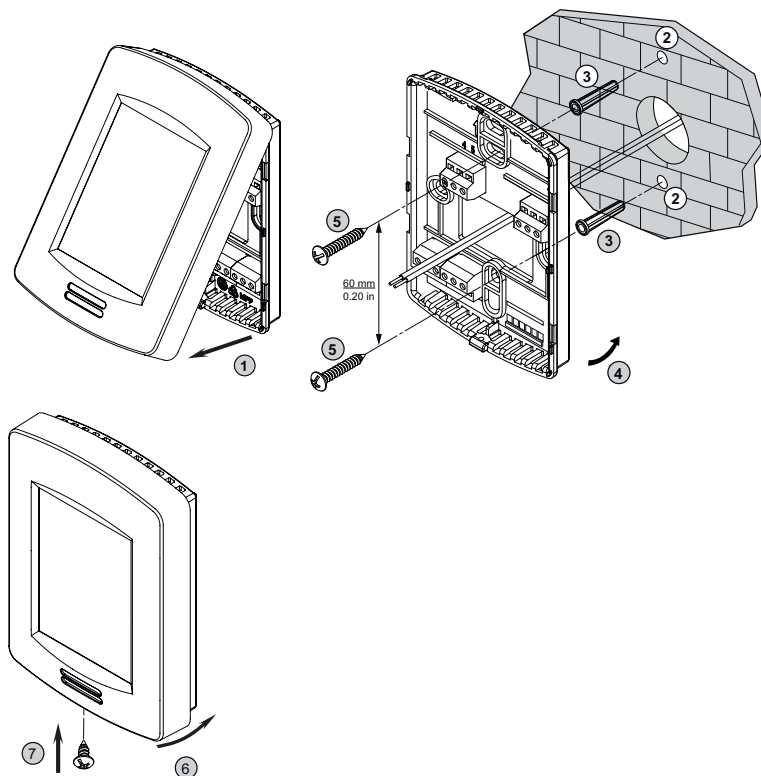
NOTICE

INACCURATE TEMPERATURE MEASUREMENT

Mount the AVP1•000W0500 in an upright, vertical (portrait) position when using the temperature sensor.

Failure to follow these instructions can result in equipment damage.

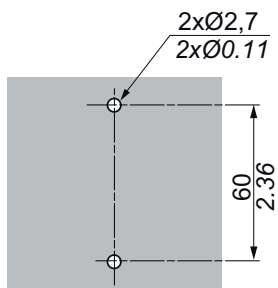
The following graphic and procedure explain how to install AVP1•000W0500 remote display on a wall:



| Step | Action |
|------|--|
| 1 | Open unit by pulling on bottom side of the display(1) |
| 2 | Ensure correct side of base faces up |
| 3 | Pull cables 150 mm (5.90 in.) out from wall |
| 4 | Align base and mark location of two mounting holes on wall or panel (2) |
| 5 | Install anchors in wall (3) |
| 6 | Insert cable in central hole of base |
| 7 | Place rear cover on the wall and align it with mounting holes (4) |
| 8 | Insert screws in mounting holes on each side of base (5) |
| 9 | Strip each wire 6 mm (0.24 in.) from end |
| 10 | Insert each wire according to wiring chart, page 26 |
| 11 | Gently push excess wiring back into hole |
| 12 | Gently align cover to top of base and snap in place from bottom (6) |
| 13 | Install the isolated screw connection for securing the plastic housing (7) |

Mounting Holes Layout

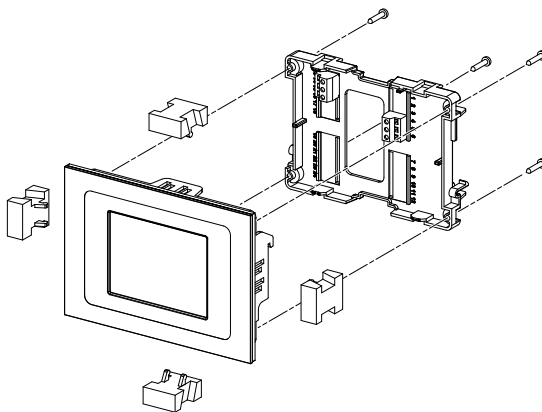
Mounting holes layout for AVP1•000W0500:



AVP100•0P0500 Remote Display Installation

AVP100•0P0500 Wiring

The AVP100•0P0500 remote display must be wired prior to the mounting phase.

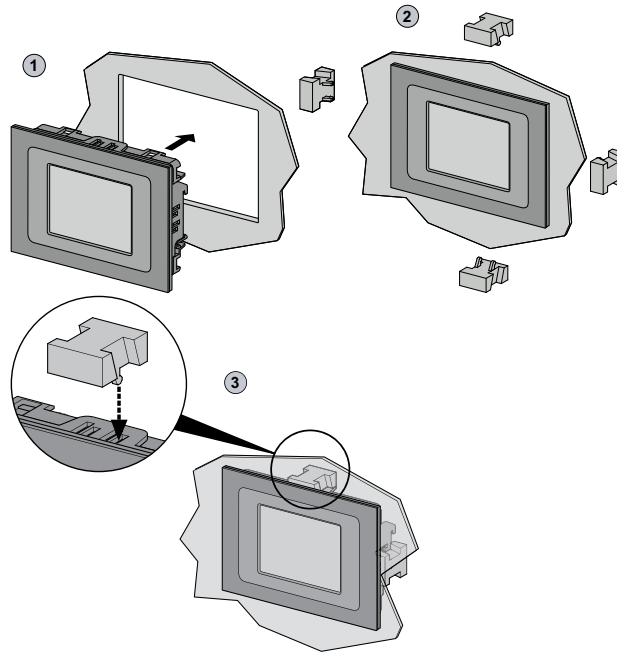


The following procedure explain how to wire a AVP100•0P0500 remote display:

| Step | Action |
|------|---|
| 1 | Open unit by pulling on bottom side of the display |
| 2 | Insert cable in central hole of base |
| 3 | Strip each wire 6 mm (0.24 in.) from end |
| 4 | Insert each wire according to wiring chart, page 26 |
| 5 | Gently align cover to top of base and snap in place. |
| 6 | Install the 4 isolated screws connection for securing the plastic housing |

AVP100•0P0500 Panel Installation

The AVP100•0P0500 remote display can be mounted horizontally or vertically on a vertical panel.

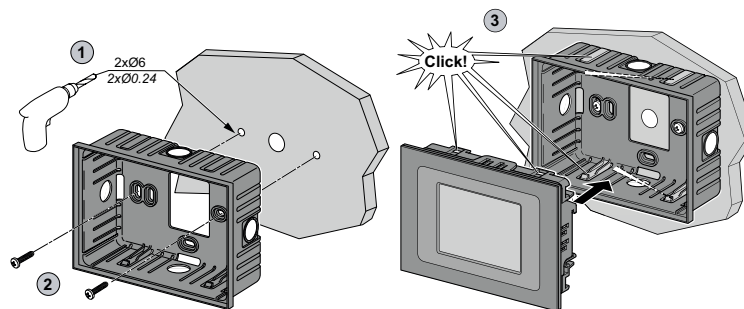


The following procedure explain how to install a AVP100•0P0500 remote display on a panel:

| Step | Action |
|------|--|
| 1 | Make a hole using the mounting hole layout. |
| 2 | Pull cables 150 mm (5.90 in.) out from hole. |
| 3 | Wire the unit according to the wiring procedure. |
| 4 | Insert the unit in the hole (1). |
| 5 | Secure it with 4 panel mounting locks provided (2)(3). |

AVP100•0P0500 Vertical Surface Installation

The AVP100•0P0500 remote display can be mounted horizontally or vertically on a vertical surface using AVA00WMRC0001 or AVA00WMRC0000 accessory.

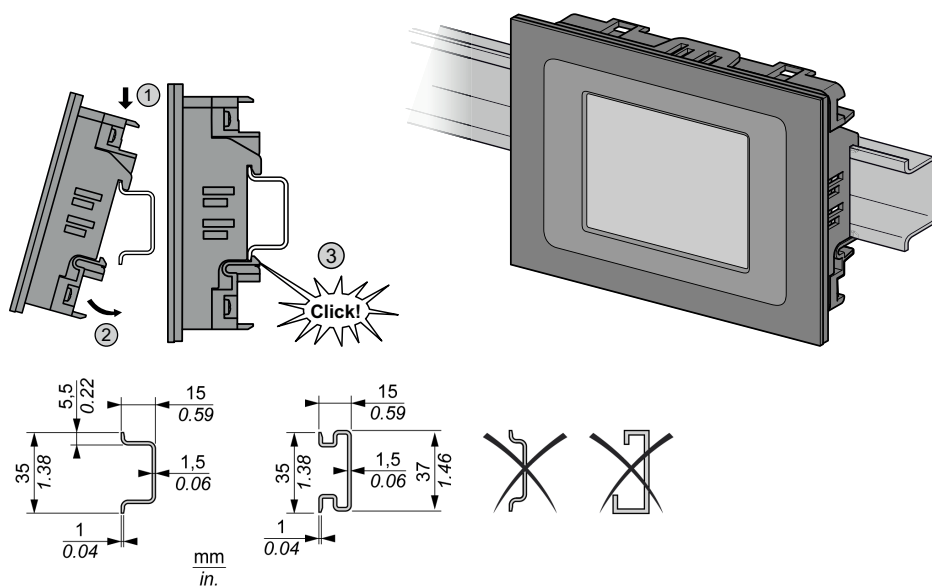


The following procedure explain how to install AVP100•0P0500 remote display on a vertical surface:

| Step | Action |
|------|--|
| 1 | Place the AVA00WMRC000• accessory. |
| 2 | Ensure correct side of AVA00WMRC000• faces up. |
| 3 | Pull cables 150 mm (5.90 in.) out from vertical surface if necessary. |
| 4 | Align AVA00WMRC000• and mark location of two mounting holes on the vertical surface. |
| 5 | Drill holes in the vertical surface (1). |
| 6 | Pull cables 150 mm (5.90 in.) out from a hole of AVA00WMRC000•. |
| 7 | Place AVA00WMRC000• on the vertical surface and align it with mounting holes. |
| 8 | Insert screws in mounting holes on each side of AVA00WMRC000• (2). |
| 9 | Wire the unit according to the wiring procedure. |
| 10 | Gently push excess wiring back into hole. |
| 11 | Gently snap in place AVP100•0P0500 into AVA00WMRC000• (3). |

AVP100•0P0500 Top Hat Section Rail (DIN Rail) Installation

The AVP100•0P0500 remote display can be mounted horizontally on a top hat section rail (DIN rail).

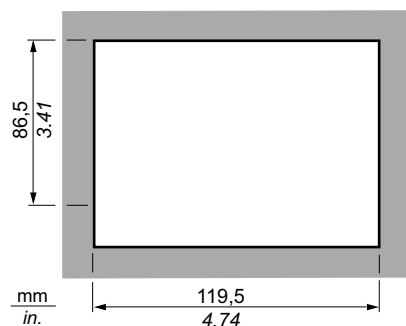


The following procedure describes how to install a AVP100•0P0500 remote display on a top hat section rail (DIN rail):

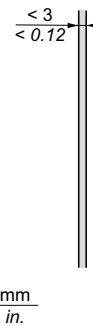
| Step | Action |
|------|---|
| 1 | Wire the unit according to the wiring procedure. |
| 2 | Position the top groove of the remote display on the top edge of the Top Hat Section Rail (DIN rail) (1). |
| 3 | Press the assembly against the Top Hat Section Rail (DIN rail) (2) up to the locked position (3). |

Mounting Holes Layout

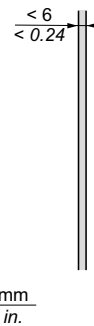
Mounting hole layout for AVP100•0P0500:



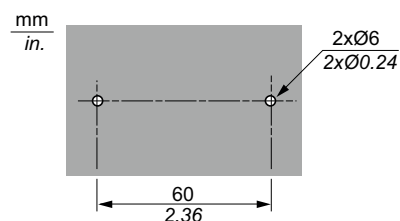
with seals:



without seals:



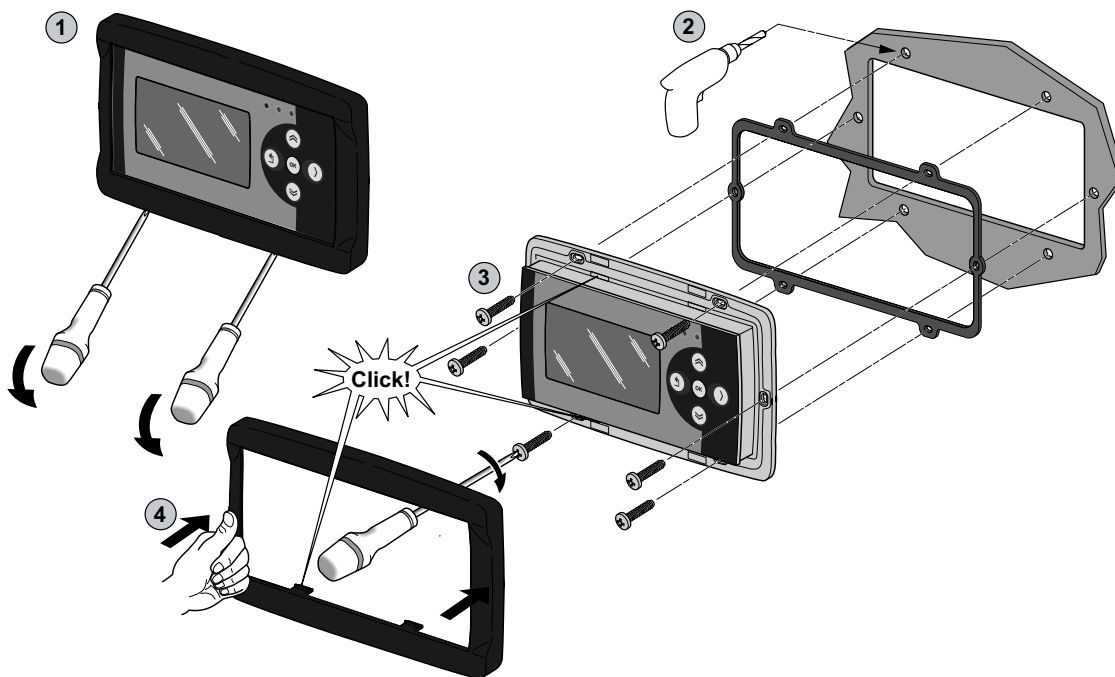
Mounting holes layout for AVA00WMRC0001 or AVA00WMRC0000:



AVK1000000500 Remote Display Installation

AVK1000000500 Panel Installation

The AVK1000000500 remote display can be mounted horizontally on a vertical panel.

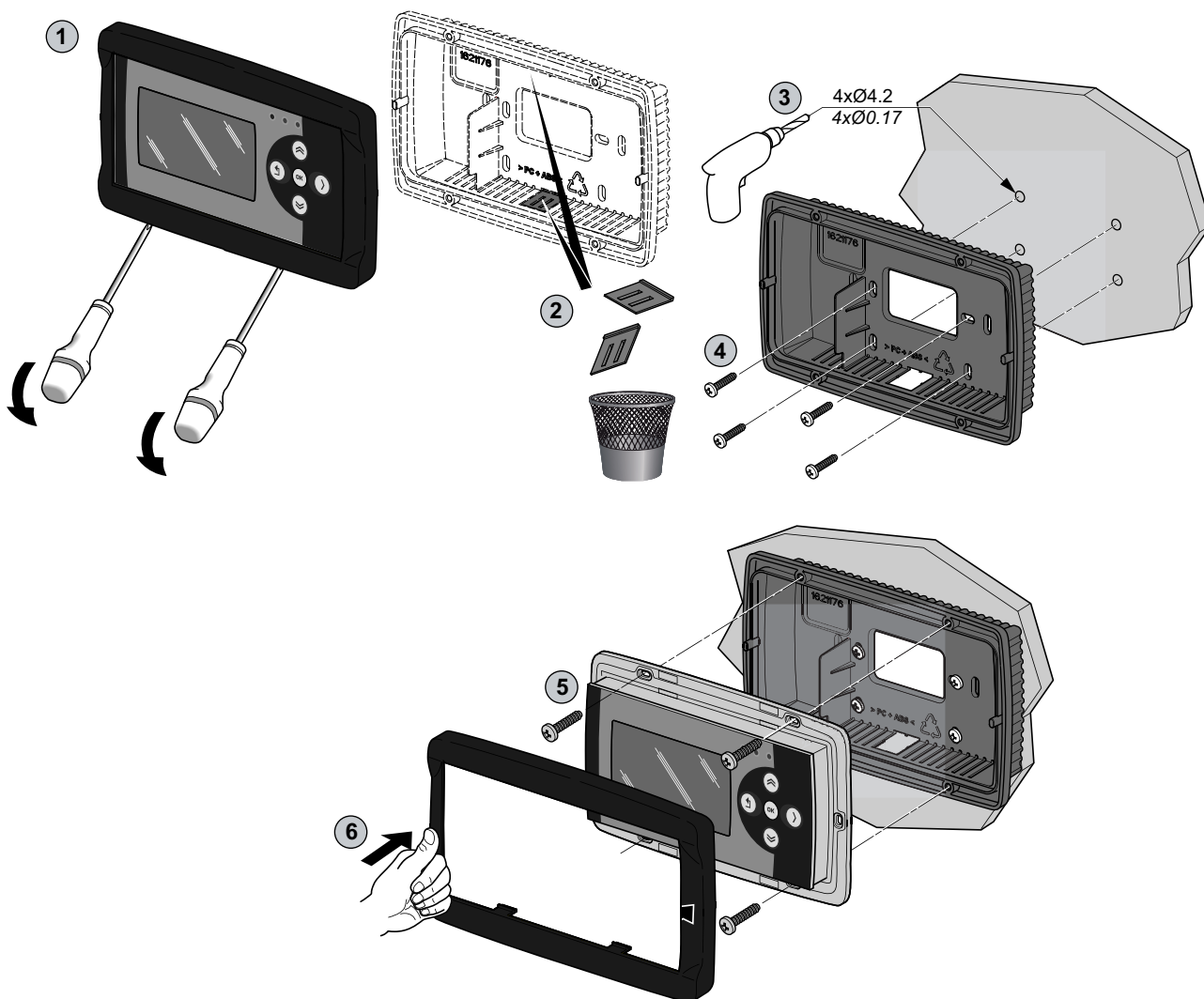


The following procedure explain how to install a AVK100000500 remote display on a panel:

| Step | Action |
|------|---|
| 1 | Open unit by pulling on bottom side of the display |
| 2 | Make a hole using the mounting hole layout. Drill, at the specified spacing, 6 holes using the mounting hole layout, page 47. Insert cable in central hole of the panel. Strip each wire 6 mm (0.24 in.) from end. Connect each wire according to wiring chart, page 26 |
| 3 | Place the seal, insert the unit in the hole, and fix it with the 6 screws. |
| 4 | Gently align cover to top of base and snap in place. |

AVK100000500 Vertical Surface Installation

The AVK100000500 remote display can be mounted horizontally on a vertical surface using EVA00WMRC0000 or EVA00WMRC0001 accessory.

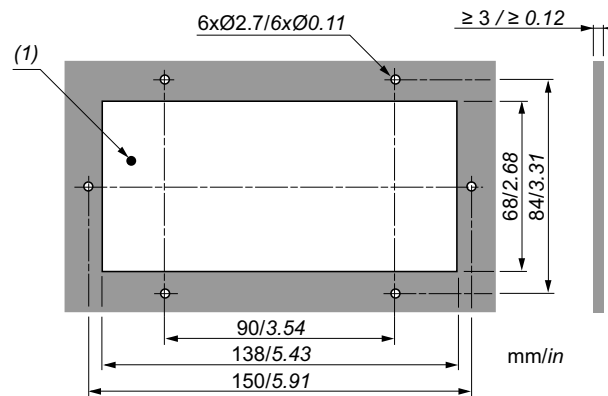


The following procedure explain how to install AVK100000500 remote display on a vertical surface:

| Step | Action |
|------|---|
| 1 | Open unit by pulling on bottom side of the display |
| 2 | On the AVA00WMRC000• accessory, use the two side slots, one at the bottom and one at the top, under the pre-formatted removable doors, preventing the opening of holes in the wall. |
| 3 | Drill, at the specified spacing, 4 holes using the mounting hole layout, page 47. |
| 4 | Place the AVA00WMRC000• accessory and fix it with the 4 screws Pull cables 150 mm (5.90 in.) out from AVA00WMRC000• side slots. Strip each wire 6 mm (0.24 in.) from end. Connect each wire according to wiring chart, page 26 |
| 5 | Insert the AVK100000500 remote display in the AVA00WMRC000• accessory, and fix it with the 4 screws. |
| 6 | Gently align cover to top of base and snap in place. |

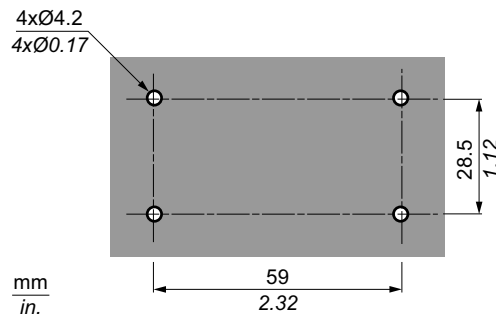
Mounting Holes Layout

Mounting hole layout for AVK100000500 Panel Installation:



1: Panel cut out

Mounting hole layout for AVK100000500 Vertical Surface Installation with AVA00WMRC000• accessory:



Controllers and Expansion Modules

What's in This Part

| | |
|---|-----|
| Environmental Characteristics | 49 |
| AV•••••6•500 / AV•••••5•500 Controllers Description | 51 |
| EVE•••••0500 Expansion Modules Description..... | 62 |
| Electrical Characteristics and Wiring Diagrams | 66 |
| User Interface | 104 |

Environmental Characteristics

What's in This Chapter

Environmental Characteristics 49

Environmental Characteristics

Technical Data

The FREE Advance Logic Controller offer components meet European Community (CE) requirements for open equipment. You must install them in an enclosure or other location designed for the specific environmental conditions and to minimize the possibility of unintended contact with hazardous voltages. Use metal enclosures to improve the electromagnetic immunity of your FREE Advance system. This equipment meets CE requirements as indicated in the following tables.

| |
|---|
| ⚠ WARNING |
| UNINTENDED EQUIPMENT OPERATION |
| Do not exceed any of the rated values specified within this chapter. |
| Failure to follow these instructions can result in death, serious injury, or equipment damage. |

Controller and Expansion Modules Specifications

| Characteristics | Specification | AV-30**60500 | AV-6200060500 / AV-6200050500 | AVD62SS060500 | AV-8400051500 | AVC8400061500 / AVD8400061500 | AVD84SS061500 | AV-1260051500 | AVC1260061500 / AVD1260061500 | AVD126S061500 | AV-8400-60500 / AV-1260-60500 | AVD84SS060500 / AVD126S060500 | EVE6000000500 | EVE1020000500 |
|--|--|--|-------------------------------|---------------|---------------|-------------------------------|---------------|---------------|-------------------------------|---------------|-------------------------------|-------------------------------|---------------|---------------|
| | | The product complies with the following harmonized Standards | EN 60730-1 / EN 60730-2-9 | | | | | | | | | | | |
| Construction of control | Electronic automatic Incorporated Control | | | | | | | | | | | | | |
| Purpose of control | Operating control (non-safety-related) | | | | | | | | | | | | | |
| Mounting | Top Hat Section Rail (DIN rail) | | | | | | | | | | | | | |
| | Optional panel mounting (with accessories) | | | | | | | | | | | | | |
| Type of action | 1.B | | | | | | | | | | | | | |
| | 1.Y | - | ✓ | - | ✓ | - | ✓ | - | ✓ | - | ✓ | - | - | - |
| Type of disconnection or suspension for each circuit | Micro disconnection | | | | | | | | | | | | | |
| Pollution degree | 2 (normal) | | | | | | | | | | | | | |
| Over-voltage category | II | | | | | | | | | | | | | |

| Characteristics | Specification | AV-30***60500 | AV-6200060500 / AV-6200050500 | AVD62S060500 | AV-8400051500 | AVC8400061500 / AVD8400061500 | AVD84SS061500 | AV-1260051500 | AVC1260061500 / AVD1260061500 | AVD126S061500 | AV-8400•60500 / AV•1260•60500 | AVD84SS060500 / AVD126S060500 | EVE6000000500 | EVE1020000500 |
|---|--|-----------------------|-------------------------------|------------------|---------------|-------------------------------|------------------|---------------|-------------------------------|------------------|-------------------------------|-------------------------------|---------------|---------------|
| | | Rated impulse voltage | 2500 V | | | | | | | ✓ | | | | |
| Period of electric stress on the insulating parts | Long period, EN 60730 | | | | | | | ✓ | | | | | | |
| Power supply | 24 Vac (+/- 10 %) 50 Hz / 60 Hz 20...38 Vdc (non-isolated) | | | | | - | | | | | | ✓ | | |
| | 24 Vac (+/- 10 %) 50 Hz / 60 Hz 20...38 Vdc (isolated) | | | | | ✓ | | | | | | - | | |
| Power Consumption | 20 VA / 10 W | ✓ | | | | | | - | | | | | ✓ | - |
| | 21 VA / 11 W | - | ✓ | | | | | | | | | | | |
| | 23 VA / 12 W | | | | | ✓ | | | | | | | | |
| | 24 VA / 15 W | | | | | | | | | | | | | ✓ |
| | 25 VA / 14 W | | | | | | | | ✓ | | | | | |
| | 35 VA / 15 W | | | | | | | | | | | ✓ | | - |
| Insulation class | II | | | | | | | ✓ | | | | | | |
| Ambient operating temperature | -20...55 °C (-4...131 °F) | - | ✓ | | | | | | | | | ✓ | | - |
| | -20...60 °C (-4...140 °F) | ✓ | | | | | ✓ ⁽¹⁾ | | - | ✓ ⁽¹⁾ | | | | - |
| | -20...65 °C (-4...149 °F) | - | | ✓ ⁽²⁾ | | | | - | ✓ ⁽²⁾ | | - | ✓ ⁽³⁾ | | ✓ |
| Ambient operating humidity (non-condensing) | 5...95 % | | | | | | | ✓ | | | | | | |
| Ambient storage temperature | -30...70 °C (-22...158 °F) | | | | | | | ✓ | | | | | | |
| Ambient storage humidity (non-condensing) | 5...95 % | | | | | | | ✓ | | | | | | |
| Temperature for ball pressure test | 125 °C (257 °F) | | | | | ✓ | | | | | | - | | ✓ |
| Insulation material group | IIIa | | | | | | | ✓ | | | | | | |
| Fire-resistance category | D | | | | | | | ✓ | | | | | | |
| Software class and structure | A | | | | | | | ✓ | | | | | | |
| Operating altitude | 0...2000 m (0...6560 ft) | | | | | | | ✓ | | | | | | |
| Digital outputs | Refer to the label on the device | | | | | | | ✓ | | | | | | |
| Degree of protection by enclosure | IP20 | | | | | | | ✓ | | | | | | |
| <p>(1) Limited to 55°C (131°F), if mounted other than horizontally on vertical plane.</p> <p>(2) Limited to 60°C (140°F), if mounted other than horizontally on vertical plane.</p> <p>(3) Limited to 60°C (140°F), if DO8 is active or if mounted other than horizontally on vertical plane.</p> | | | | | | | | | | | | | | |

AV.....6•500 / AV.....5•500 Controllers Description

What's in This Chapter

| | |
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| AV•30...60500 | 51 |
| AV•62...60500 / AV•62...50500 | 53 |
| AV•84...6•500 / AV•840005I500 | 55 |
| AV•12...6•500 / AV•126005I500 | 58 |

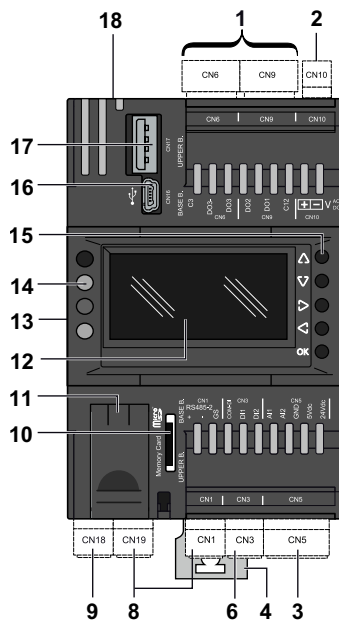
AV•30...60500

Overview

| Reference | Description |
|---------------|--|
| AVC3000060500 | FREE AVC3000/C/L/U Blind 7 I/Os Isolated |
| AVD3000060500 | FREE AVC3000/C/L/U Display 7 I/Os Isolated |

Physical Description

The following illustration presents the AV•30...60500 controller:



| Number | Name | Description |
|--------|------|--|
| 1 | CN6 | DO3 High voltage relay digital output 250 Vac 3 A SPDT, page 76 |
| | CN9 | DO1...DO2 High voltage relay digital output 250 Vac 3 A SPST, page 73 |
| 2 | CN10 | 24 Vac/dc isolated power supply, page 67 |
| 3 | CN5 | Power out +24 Vdc power out for analog inputs, max current 100 mA +5 Vdc power out for ratiometric analog inputs, max current 40 mA (2) |
| | | AI1...AI2 Analog inputs are configurable as, page 78: <ul style="list-style-type: none"> • NTC resistive input or digital input • Current analog input • Voltage analog input • PTC resistive input |
| 4 | - | Clip-on lock, page 32 |

| Number | Name | Description |
|--------|------|--|
| 6 | CN3 | DI1...DI2 Fast digital input, pulse/frequency counter up 2 kHz, opto-isolated, page 70 |
| 8 | CN1 | RS-485 serial port-2, page 94 |
| | CN19 | RS-485 serial port-1, page 94 |
| 9 | CN18 | CAN expansion bus master, page 91 |
| 10 | - | Micro SD memory card slot, page 101 |
| 11 | - | Service battery door, page 103 |
| 12 | - | User interface - Display, page 104 (1) |
| 13 | - | Communication module connector, page 18 |
| 14 | - | User interface - LEDs, page 104 (1) |
| 15 | - | User interface - Keys, page 104 (1) |
| 16 | CN16 | USB type Mini-B female for PC connection, page 97 |
| 17 | CN17 | USB type A female for a mass storage device (FAT32), page 97 |
| 18 | CN20 | Ethernet Modbus TCP/IP or BACnet IP, page 98 |

(1) Only for AVD.....500.

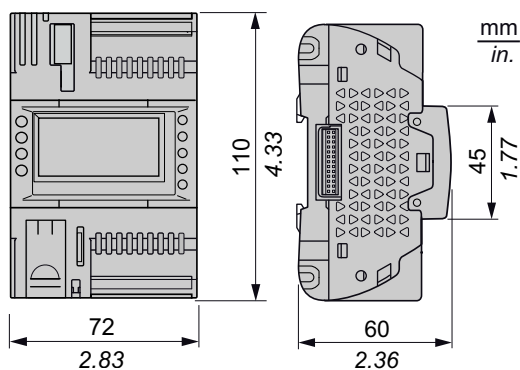
(2) 0-5 V Ratiometric: ratiometric range is 0.5 V to 4.5 V. Maximum current at +5 Vdc is 40 mA.

| |
|--|
| NOTICE |
| INOPERABLE EQUIPMENT |
| Configure the analog inputs and outputs, and related parameters, according to the physical types of resources connected. |
| Failure to follow these instructions can result in equipment damage. |

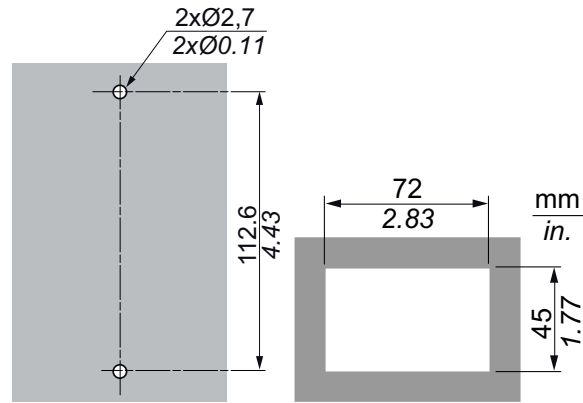
For more details, refer to analog inputs configuration, page 78 and analog outputs configuration, page 87.

For more information about the wiring, refer to wiring best practices, page 26.

Dimensions



Mounting Holes Layout



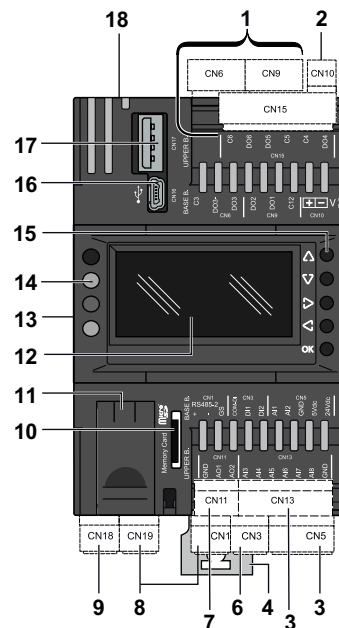
AV•62•••60500 / AV•62•••50500

Overview

| Reference | Description |
|---------------|--|
| AVC6200060500 | AVC6200/C/L/U Blind 18 I/Os Isolated |
| AVD6200060500 | AVD6200/C/L/U Display 18 I/Os Isolated |
| AVD62SS060500 | AVD6200/C/L/U/SSR Display 18 I/Os 2 SSR Isolated |
| AVC6200050500 | AVC6200/C Blind 18 I/Os Isolated |
| AVD6200050500 | AVD6200/C Display 18 I/Os Isolated |

Physical Description

The following illustration presents the AV•62•••0500 controller:



| Number | Name | Description |
|--------|------|---|
| 1 | CN6 | DO3 High voltage relay digital output 250 Vac 3 A SPDT, page 76 |

| Number | Name | Description |
|--------|------|---|
| | CN9 | DO1...DO2 High voltage relay digital output 250 Vac 3 A SPST, page 73 |
| | CN15 | DO5...DO6 <ul style="list-style-type: none"> AV.....0...500: High voltage relay digital output 250 Vac 3 A SPST, page 73 AVD62SS060500: High voltage SSR digital output 240 Vac 0.2 A, page 75 |
| | | DO4 |
| 2 | CN10 | 24 Vac/dc isolated power supply, page 67 |
| 3 | CN5 | Power out <ul style="list-style-type: none"> +24 Vdc power out for analog inputs, max current 100 mA +5 Vdc power out for ratiometric analog inputs, max current 40 mA ⁽²⁾ |
| | | AI1...AI2 |
| | CN13 | AI3...AI8 |
| 4 | - | Clip-on lock, page 32 |
| 6 | CN3 | DI1...DI2 Fast digital input, pulse/frequency counter up 2 kHz, opto-isolated, page 70 |
| 7 | CN11 | AO1...AO2 Low voltage SELV analog outputs, configurable as, page 87: <ul style="list-style-type: none"> Current modulation analog output Current ON/OFF analog output Voltage modulation analog output PWM open collector |
| 8 | CN1 | RS-485 serial port-2, page 94 |
| | CN19 | RS-485 serial port-1, page 94 |
| 9 | CN18 | CAN expansion bus master, page 91 |
| 10 | - | Micro SD memory card slot, page 101 ⁽³⁾ |
| 11 | - | Service battery door, page 103 |
| 12 | - | User interface - Display, page 104 ⁽¹⁾ |
| 13 | - | Communication module connector, page 18 |
| 14 | - | User interface - LEDs, page 104 ⁽¹⁾ |
| 15 | - | User interface - Keys, page 104 ⁽¹⁾ |
| 16 | CN16 | USB type Mini-B female for PC connection, page 97 |
| 17 | CN17 | USB type A female for a mass storage device (FAT32), page 97 ⁽³⁾ |
| 18 | CN20 | Ethernet Modbus TCP/IP or BACnet IP, page 98 ⁽³⁾ |

(1) Only for AVD.....500.

(2) 0-5 V Ratiometric: ratiometric range is 0.5 V to 4.5 V. Maximum current at +5 Vdc is 40 mA.

(3) Only for AV.....6•500.

NOTICE

INOPERABLE EQUIPMENT

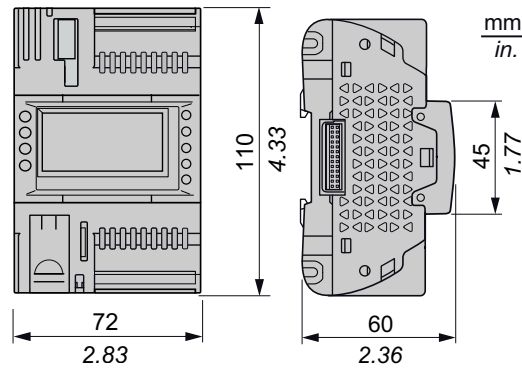
Configure the analog inputs and outputs, and related parameters, according to the physical types of resources connected.

Failure to follow these instructions can result in equipment damage.

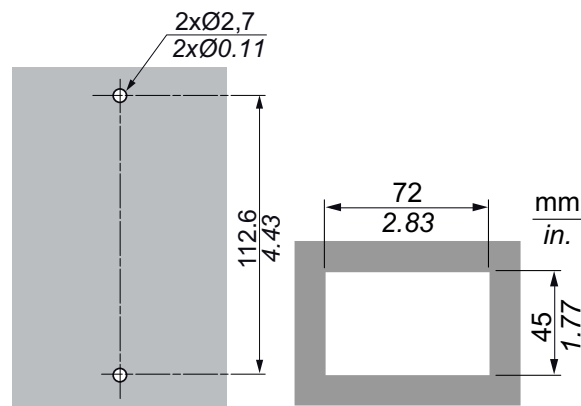
For more details, refer to analog inputs configuration, page 78 and analog outputs configuration, page 87.

For more information about the wiring, refer to wiring best practices, page 26.

Dimensions



Mounting Holes Layout



AV•84...6•500 / AV•840005I500

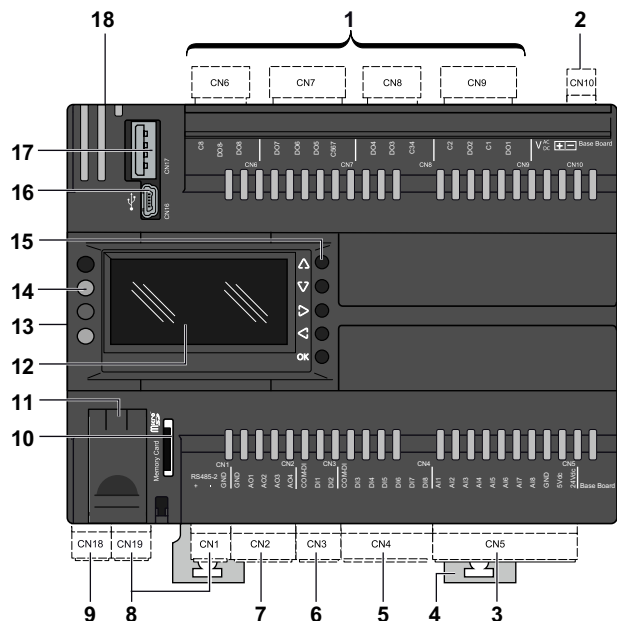
Overview

| Reference | Description |
|---------------|--|
| AVC8400060500 | AVC8400/C/L/U Blind 28 I/Os |
| AVC840006I500 | AVC8400/C/L/U/I Blind 28 I/Os Isolated |
| AVD8400060500 | AVD8400/C/L/U Display 28 I/Os |
| AVD840006I500 | AVD8400/C/L/U/I Display 28 I/Os Isolated |
| AVD84SS060500 | AVD8400/C/L/U/SSR Display 28 I/Os 2 SSR |
| AVD84SS06I500 | AVD8400/C/L/U/SSR/I Display 28 I/Os 2 SSR Isolated |
| AVC8400050500 | AVC8400/C Blind 28 I/Os Isolated |
| AVD8400050500 | AVD8400/C Display 28 I/Os Isolated |

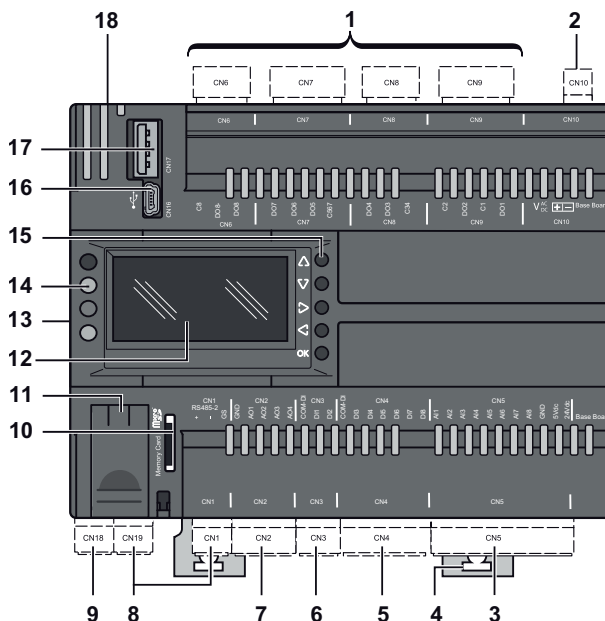
Physical Description

The following illustration presents the AV•84•••6•500 controller:

AV•84•••60500 controller:



AV•84•••6I500 / AV•840005I500 controller:



| Number | Name | Description | |
|--------|------|--|--|
| 1 | CN6 | DO8 <ul style="list-style-type: none"> AV•84•••60500: High voltage relay digital output 250 Vac 1 A SPDT, page 76 AV•84•••6I500 / AV•840005I500: High voltage relay digital output 250 Vac 3 A SPDT, page 76 | |
| | CN7 | DO5...DO7 | High voltage relay digital output 250 Vac 3 A SPST, page 73 |
| | CN8 | DO3...DO4 | |
| | CN9 | DO1...DO2 <ul style="list-style-type: none"> AV•••••0•••500: High voltage relay digital output 250 Vac 3 A SPST, page 73 AV•••••S•••500: High voltage SSR digital output 240 Vac 0.5 A, page 75 | |
| 2 | CN10 | 24 Vac/dc power supply, page 67 | |
| 3 | CN5 | Power out <ul style="list-style-type: none"> +24 Vdc power out for analog inputs, max current 150 mA +5 Vdc power out for ratiometric analog inputs, max current 50 mA ⁽²⁾ | |
| | | AI1...AI8 <ul style="list-style-type: none"> Analog inputs are configurable as, page 78: <ul style="list-style-type: none"> NTC resistive input or digital input Current analog input Voltage analog input PTC resistive input | |
| 4 | - | Clip-on lock, page 32 | |
| 5 | CN4 | DI3...DI8 | Regular digital input opto-isolated, page 71 |
| 6 | CN3 | DI1...DI2 | Fast digital input, pulse/frequency counter up 2 kHz, opto-isolated, page 70 |
| 7 | CN2 | AO1...AO2 | Low voltage (SELV) analog outputs 0...10 Vdc, page 89 |
| | | AO3...AO4 <ul style="list-style-type: none"> Low voltage SELV analog outputs, configurable as, page 87: <ul style="list-style-type: none"> Current modulation analog output Current ON/OFF analog output Voltage modulation analog output PWM open collector | |
| 8 | CN1 | RS-485 serial port-2, page 94 | |
| | CN19 | RS-485 serial port-1, page 94 | |
| 9 | CN18 | CAN expansion bus master, page 91 | |

| Number | Name | Description |
|--------|------|---|
| 10 | - | Micro SD memory card slot, page 101 ⁽³⁾ |
| 11 | - | Service battery door, page 103 |
| 12 | - | User interface - Display, page 104 ⁽¹⁾ |
| 13 | - | Communication module connector, page 18 |
| 14 | - | User interface - LEDs, page 104 ⁽¹⁾ |
| 15 | - | User interface - Keys, page 104 ⁽¹⁾ |
| 16 | CN16 | USB type Mini-B female for PC connection, page 97 |
| 17 | CN17 | USB type A female for a mass storage device (FAT32), page 97 ⁽³⁾ |
| 18 | CN20 | Ethernet Modbus TCP/IP or BACnet IP, page 98 ⁽³⁾ |

(1) Only for AVD.....500.

(2) 0-5 V Ratiometric: ratiometric range is 0.5 V to 4.5 V. Maximum current at +5 Vdc is 50 mA.

(3) Only for AV.....6•500.

NOTICE

INOPERABLE EQUIPMENT

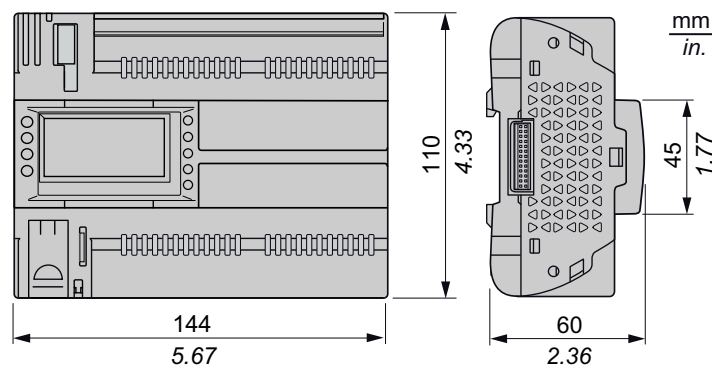
Configure the analog inputs and outputs, and related parameters, according to the physical types of resources connected.

Failure to follow these instructions can result in equipment damage.

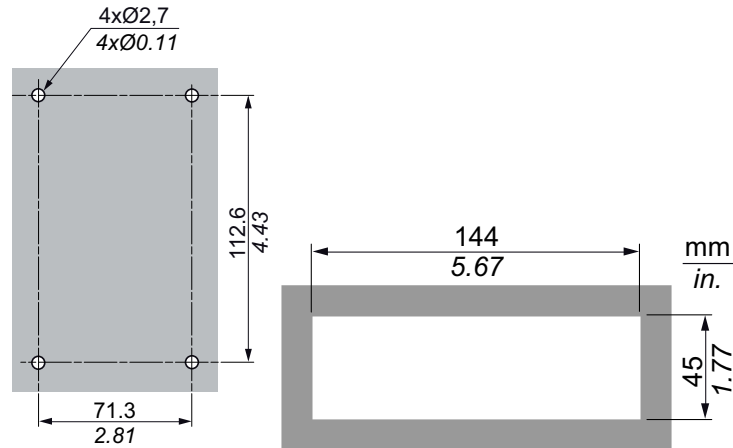
For more details, refer to analog inputs configuration, page 78 and analog outputs configuration, page 87.

For more information about the wiring, refer to wiring best practices, page 26.

Dimensions



Mounting Holes Layout



AV•12••••6•500 / AV•126005I500

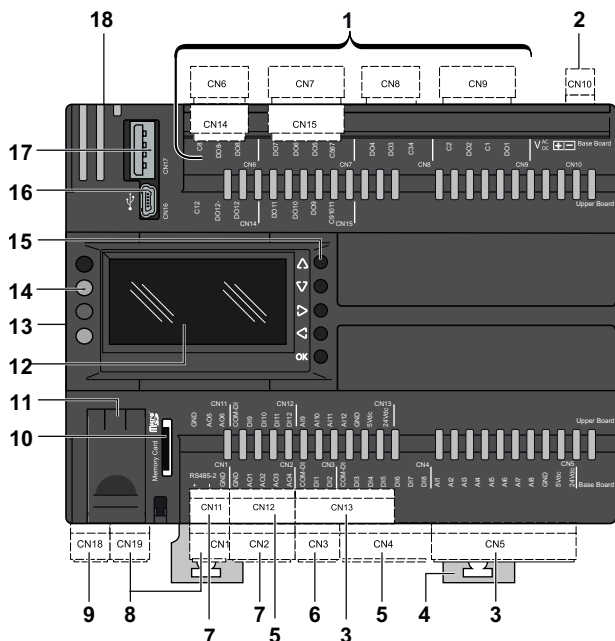
Overview

| Reference | Description |
|---------------|---|
| AVC1260060500 | AVC12600/C/L/U Blind 42 I/Os |
| AVC126006I500 | AVC12600/C/L/U/I Blind 42 I/Os Isolated |
| AVD1260060500 | AVD12600/C/L/U Display 42 I/Os |
| AVD126006I500 | AVD12600/C/L/U/I Display 42 I/Os Isolated |
| AVD126S060500 | AVD12600/C/L/U/SSR Display 42 I/Os 2 SSR |
| AVD126S06I500 | AVD12600/C/L/U/SSR/I Display 42 I/Os 2 SSR Isolated |
| AVC126005I500 | AVC12600/C/I Blind 42 I/Os Isolated |
| AVD126005I500 | AVD12600/C/I Display 42 I/Os Isolated |

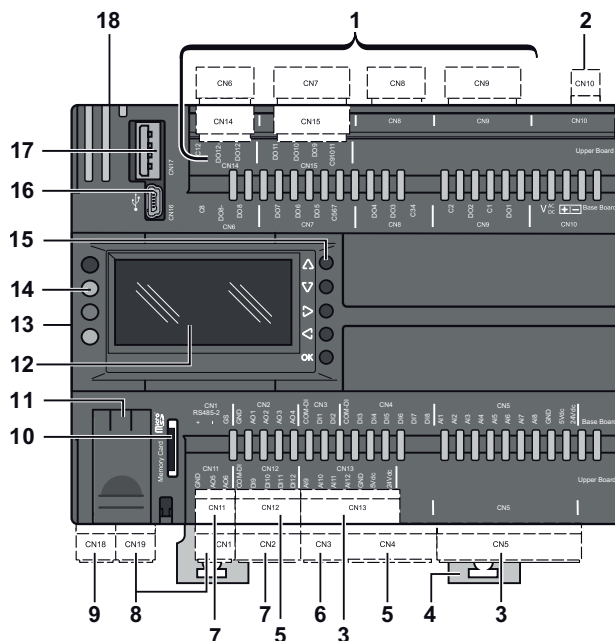
Physical Description

The following illustration presents the AV•126•••500 controller:

AV•126•••0500 controller:



AV•126•••I500 / AV•126005I500 controller:



| Number | Name | Description | |
|--------|------|--|--|
| 1 | CN6 | DO8 <ul style="list-style-type: none"> AV•126•••0500: High voltage relay digital output 250 Vac 1 A SPDT, page 76 AV•126•••I500 / AV•126005I500: High voltage relay digital output 250 Vac 3 A SPDT, page 76 | |
| | CN7 | DO5...DO7 | High voltage relay digital output 250 Vac 3 A SPST, page 73 |
| | CN8 | DO3...DO4 | |
| | CN9 | DO1...DO2 | <ul style="list-style-type: none"> AV•••••0•••500: High voltage relay digital output 250 Vac 3 A SPST, page 73 AV•••••S•••500: High voltage SSR digital output 240 Vac 0.5 A, page 75 |
| | CN14 | DO12 | <ul style="list-style-type: none"> AV•126•••0500: High voltage relay digital output 250 Vac 1 A SPDT, page 76 AV•126•••I500 / AV•126005I500: High voltage relay digital output 250 Vac 3 A SPDT, page 76 |
| | CN15 | DO9...DO11 | High voltage relay digital output 250 Vac 3 A SPST, page 73 |
| 2 | CN10 | 24 Vac/dc power supply, page 67 | |
| 3 | CN5 | Power out | +24 Vdc power out for analog inputs, max current 150 mA ⁽³⁾ +5 Vdc power out for ratiometric analog inputs, max current 50 mA ⁽²⁾⁽³⁾ |
| | | AI1...AI8 | Analog inputs are configurable as, page 78: <ul style="list-style-type: none"> NTC resistive input or digital input Current analog input Voltage analog input PTC resistive input |
| | CN13 | AI9...AI12 | Identical to CN5. |
| 4 | - | Clip-on lock, page 32 | |
| 5 | CN4 | DI3...DI8 | Regular digital input opto-isolated, page 71 |
| | CN12 | DI9...DI12 | |
| 6 | CN3 | DI1...DI2 | Fast digital input, pulse/frequency counter up 2 kHz, opto-isolated, page 70 |
| 7 | CN2 | AO1...AO2 | Low voltage (SELV) analog outputs 0...10 Vdc, page 89 |

| Number | Name | Description |
|--------|------|--|
| | | AO3...AO4 Low voltage SELV analog outputs, configurable as, page 87: <ul style="list-style-type: none"> • Current modulation analog output • Current ON/OFF analog output • Voltage modulation analog output • PWM open collector |
| | CN11 | AO5...AO6 Low voltage (SELV) analog outputs 0...10 Vdc, page 89 |
| 8 | CN1 | RS-485 serial port-2, page 94 |
| | CN19 | RS-485 serial port-1, page 94 |
| 9 | CN18 | CAN expansion bus master, page 91 |
| 10 | - | Micro SD memory card slot, page 101 (4) |
| 11 | - | Service battery door, page 103 |
| 12 | - | User interface - Display, page 104 (1) |
| 13 | - | Communication module connector, page 18 |
| 14 | - | User interface - LEDs, page 104 (1) |
| 15 | - | User interface - Keys, page 104 (1) |
| 16 | CN16 | USB type Mini-B female for PC connection, page 97 |
| 17 | CN17 | USB type A female for a mass storage device (FAT32), page 97 (4) |
| 18 | CN20 | Ethernet Modbus TCP/IP or BACnet IP, page 98 (4) |

(1) Only for AVD.....500.

(2) 0-5 V Ratiometric: ratiometric range is 0.5 V to 4.5 V. Maximum current at +5 Vdc is 50 mA.

(3) The maximum current value is the sum between the maximum currents supplied by the corresponding terminals in the CN5 connector and in the CN13 connector.

(4) Only for AV.....6•500.

NOTICE

INOPERABLE EQUIPMENT

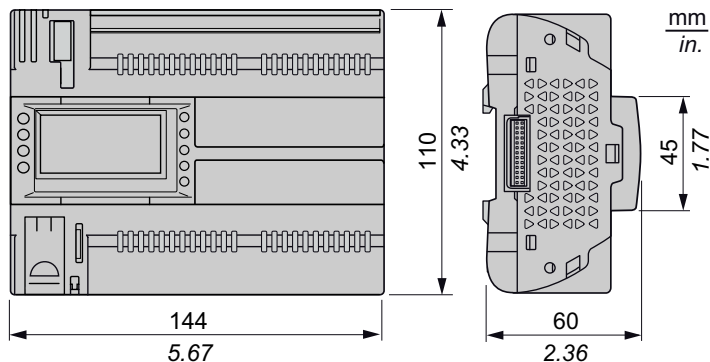
Configure the analog inputs and outputs, and related parameters, according to the physical types of resources connected.

Failure to follow these instructions can result in equipment damage.

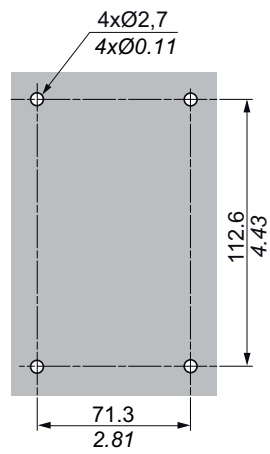
For more details, refer to analog inputs configuration, page 78 and analog outputs configuration, page 87.

For more information about the wiring, refer to wiring best practices, page 26.

Dimensions



Mounting Holes Layout



EVE.....0500 Expansion Modules Description

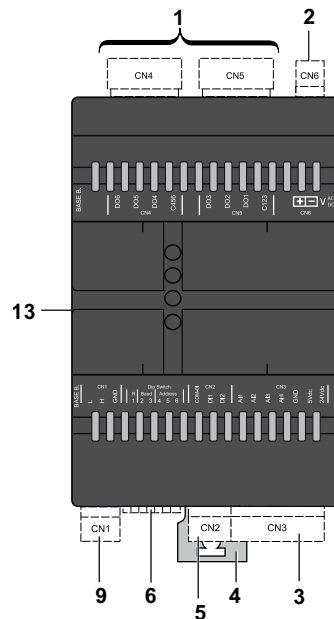
What's in This Chapter

| | |
|---------------------|----|
| EVE6000000500 | 62 |
| EVE1020000500 | 64 |

EVE6000000500

Physical Description

The following illustration presents the EVE6000000500 expansion module:



| Number | Name | Description | |
|--|------|--|---|
| 1 | CN4 | DO4...DO6 | High voltage relay digital output 250 Vac 3 A SPST, page 73 |
| | CN5 | DO1...DO3 | |
| 2 | CN6 | 24 Vac/dc non-isolated power supply, page 67 | |
| 3 | CN3 | Power out | +24 Vdc power out for analog inputs, max current 125 mA +5 Vdc power out for ratiometric analog inputs, max current 50 mA ⁽¹⁾ |
| | | AI1...AI4 | Analog inputs are configurable as, page 78: <ul style="list-style-type: none"> • NTC resistive input or digital input • Current analog input • Voltage analog input • PTC resistive input |
| 4 | - | Clip-on lock, page 32 | |
| 5 | CN2 | DI1...DI2 | Fast digital input, pulse/frequency counter up 2 kHz, page 70, opto-isolated |
| 6 | - | CAN configuration 6-position DIP switches, page 92 | |
| 9 | CN1 | CAN expansion bus slave, page 91 | |
| 13 | - | TTL Port (Service only) | |
| (1) 0...5 V Ratiometric: ratiometric range is 0.5 V to 4.5 V. Maximum current at +5 Vdc is 50 mA. | | | |

NOTICE

INOPERABLE EQUIPMENT

Configure the analog inputs and outputs, and related parameters, according to the physical types of resources connected.

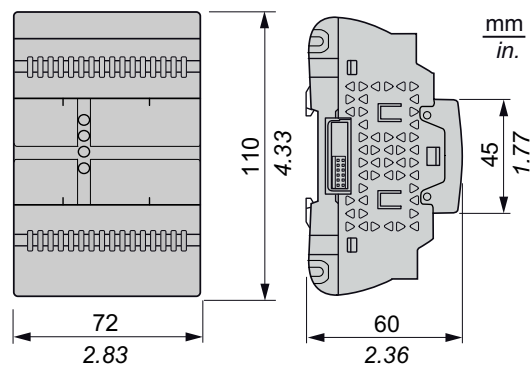
Failure to follow these instructions can result in equipment damage.

For more details, refer to analog inputs configuration, page 78 and analog outputs configuration, page 87.

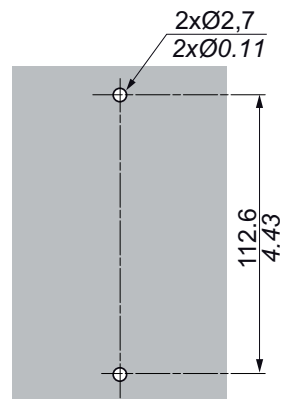
For more information about the wiring, refer to wiring best practices, page 26.

For details about Expansion module troubleshooting, refer to the section EVE•••••0500 Expansion Modules User Interface, page 105.

Dimensions



Mounting Holes Layout



| Number | Name | Description |
|--------|------|-------------------------|
| 13 | - | TTL Port (Service only) |

(1) 0...5 V Ratiometric: ratiometric range is 0.5 V to 4.5 V. Maximum current at +5 Vdc is 50 mA.

(2) The maximum current value is the sum between the maximum currents supplied by the corresponding terminals in the CN3 connector and in the CN9 connector.

NOTICE

INOPERABLE EQUIPMENT

Configure the analog inputs and outputs, and related parameters, according to the physical types of resources connected.

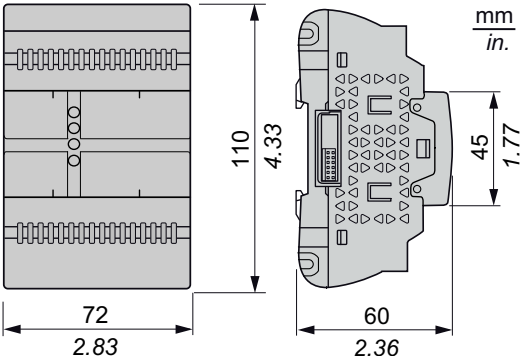
Failure to follow these instructions can result in equipment damage.

For more details, refer to analog inputs configuration, page 78 and analog outputs configuration, page 87.

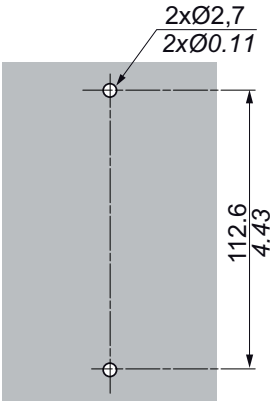
For more information about the wiring, refer to wiring best practices, page 26.

For details about Expansion module troubleshooting, refer to the section EVE.....0500 Expansion Modules User Interface, page 105.

Dimensions



Mounting Holes Layout



Electrical Characteristics and Wiring Diagrams

What's in This Chapter

| | |
|----------------------------|-----|
| Power Supply..... | 67 |
| Digital Input..... | 69 |
| Digital Output..... | 72 |
| Analog Inputs..... | 77 |
| Analog Outputs..... | 86 |
| Communication..... | 91 |
| Memory..... | 101 |
| RTC (Real-Time Clock)..... | 103 |

From time to time, new input modules, output modules, or other devices are made available that are not documented in the present documentation. For information on new devices, contact your local Eliwell representative.

NOTICE

INOPERABLE EQUIPMENT

Update the controller firmware to the latest version every time you install a newly released Input/Output expansion module or other device to this equipment.

Failure to follow these instructions can result in equipment damage.

NOTE: For more information on how to update the controller firmware, contact your local Eliwell representative.

Applying incorrect current or voltage levels on AV•30•••60500 / AV•62•••60500 / AV•62•••50500 / AV•84•••61500 / AV•8400051500 / AV•126•••1500 / AV•1260051500 controllers and EVE•••••0500 expansion modules inputs and outputs could damage the electronic circuitry. Further, connecting a current input device to an analog input configured for voltage, and vice versa, could damage the electronic circuitry.

NOTICE

INOPERABLE EQUIPMENT

- Do not apply current above 30 mA to the analog inputs of the expansion module.
- Do not apply voltages above 24 Vdc and less than -7 Vdc to the analog inputs of the expansion module.
- Do not mismatch the applied signal with the analog input configuration.

Failure to follow these instructions can result in equipment damage.

Applying incorrect current or voltage levels on AV•84•••6•500 / AV•12•••6•500 controllers analog inputs and outputs could damage the electronic circuitry. Further, connecting a current input device to an analog input configured for voltage, and vice versa, could damage the electronic circuitry.

NOTICE

INOPERABLE EQUIPMENT

- Do not apply voltages above 11 Vdc to the analog inputs of the controller or Input/Output expansion module when analog input is configured as 0-10V input.
- Do not apply current above 25 mA to the analog inputs of the controller or Input/Output expansion module when analog input is configured as 0-20 mA or 4-20 mA input.
- Do not mismatch applied signal with analog input configuration.

Failure to follow these instructions can result in equipment damage.

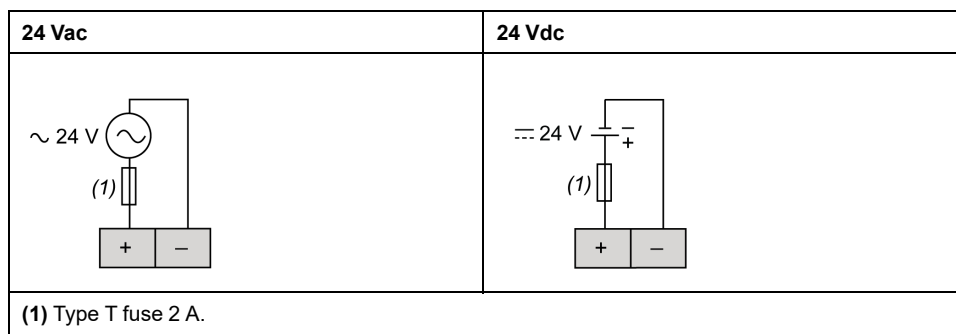
Power Supply

Power Supply

Controllers and Expansion Modules Power Supply

| References | Power supply characteristics | | Maximum power consumption |
|---|------------------------------|------------------------------|---------------------------|
| AV•30•••60500 controller | Isolated | 24 Vac (+/- 10 %) - 50/60 Hz | 20 VA |
| | | 20...38 Vdc | 10 W |
| AV•62••060500 / AV•6200050500 controllers | | 24 Vac (+/- 10 %) - 50/60 Hz | 21 VA |
| | | 20...38 Vdc | 11 W |
| AV•84•••61500 / AV•8400051500 controllers | | 24 Vac (+/- 10 %) - 50/60 Hz | 23 VA |
| | | 20...38 Vdc | 12 W |
| AV•126•••1500 / AV•1260051500 controllers | | 24 Vac (+/- 10 %) - 50/60 Hz | 25 VA |
| | | 20...38 Vdc | 14 W |
| AV•84•••60500 / AV•126•••0500 controllers | Non-isolated | 24 Vac (+/- 10 %) - 50/60 Hz | 35 VA |
| | | 20...38 Vdc | 15 W |
| EVE6000000500 expansion module | | 24 Vac (+/- 10 %) - 50/60 Hz | 20 VA |
| | | 20...38 Vdc | 10 W |
| EVE1020000500 expansion module | | 24 Vac (+/- 10 %) - 50/60 Hz | 24 VA |
| | | 20...38 Vdc | 15 W |

Power supply wiring diagram:



| | |
|------------------------------------|-----------------------|
| Pitch of the terminal block | Cabling length |
| 3.50 mm (0.14 in.) | 10 m (32.8 ft) |

NOTICE**INOPERABLE EQUIPMENT**

Do not connect a power cable longer than 10 m (32.8 ft).

Failure to follow these instructions can result in equipment damage.

For more information about the wiring, refer to *Best wiring practices*, page 26.

The power supplies for the AV•••••6•500, AV•••••5•500, and EVE•••••0500 must be rated Safety Extra Low Voltage (SELV) according to IEC 61140. These sources of power are isolated between the electrical input and output circuits of the power supply as well as simple separation from ground (earth), PELV, and other SELV systems.

⚠ DANGER**GROUND LOOP CAUSING ELECTRIC SHOCK AND/OR INOPERABLE EQUIPMENT**

- Do not connect the 0 V power supply/transformer connection supplying this equipment to any external ground (earth) connection.
- Do not connect any 0 V or ground (earth) of the sensors and actuators connected to this equipment to any external ground connection.
- If necessary, use separate power supplies/transformers to power sensors or actuators isolated from this equipment.

Failure to follow these instructions will result in death or serious injury.

In all cases, if the specified voltage range is not maintained, the products may not function as intended. Use appropriate safety interlocks and voltage monitoring circuits.

⚠ WARNING**POTENTIAL OF OVERHEATING AND FIRE**

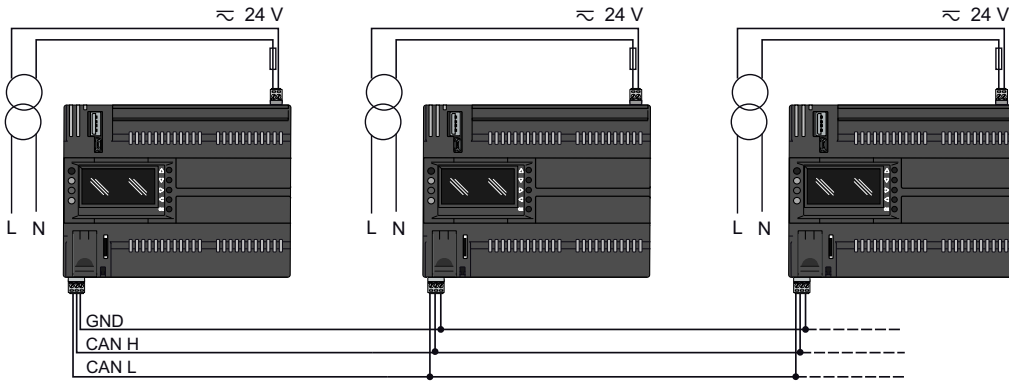
- Do not connect the equipment directly to line voltage.
- Use only isolating SELV, Class 2 power supplies / transformers to supply power to this equipment.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

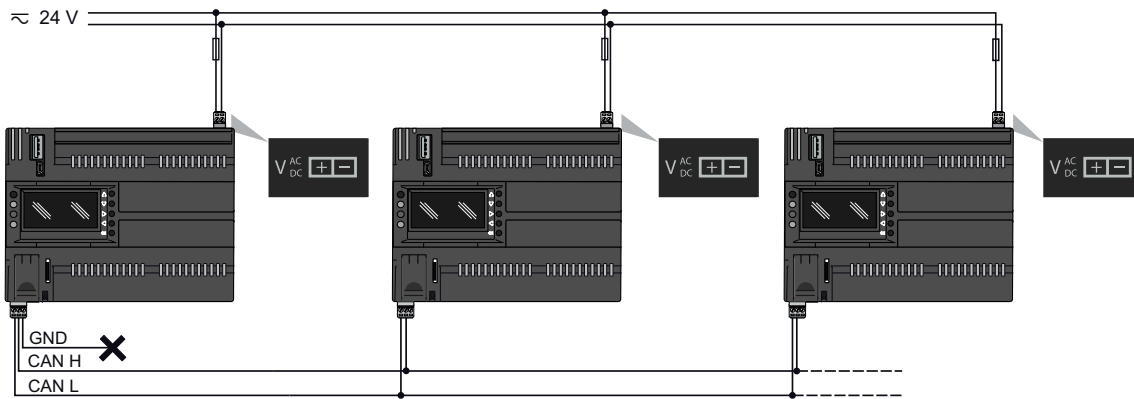
Power Supply and Field bus Wiring Restriction For Non Isolated Controllers and Expansion Modules

AV•84•••60500 / AV•126•••0500 / EVE•••••0500 power supply inputs are not isolated. If you connect the GND connection of the RS-485 network or the CAN expansion bus across multiple controllers, you must use separate, isolated power supplies. Alternatively, if you are interconnecting the equipment to a single power supply, do not connect the RS-485 or CAN GND signal. Pay special attention when connecting serial lines. Miswiring may lead to inoperable equipment.

CAN network example with separate power lines:



CAN network example with common power line and GND signal not connected:



NOTE: AV•30•••60500 / AV•62•••0500 / AV•8400051500 / AV•1260051500 / AV•84•••61500 / AV•126•••1500 power supply inputs are isolated. GS connection of the RS-485 network or the GND connection of the CAN expansion bus across multiple controllers must be connected regardless of the power supply type and wiring.

Digital Input

Digital Inputs

This table presents the digital inputs of controllers and expansion modules:

| Description | AV•30•••60500 | AV•62•0••0500 | AV•62SS••0500 | AV•8400•••500 | AV•84S••••500 | AV•1260••••500 | AV•126S••••500 | EVE6000000500 | EVE1020000500 |
|---------------------------------|---------------|---------------|---------------|---------------|---------------|----------------|----------------|---------------|---------------|
| Fast digital inputs, page 70 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 |
| Regular digital inputs, page 71 | - | - | - | 6 | 6 | 10 | 10 | - | 4 |

These devices have analog inputs that can be configured as dry contact digital inputs. For more details, refer to the configuration of analog inputs, page 78.

NOTE: The commons COM_DI are not internally connected together.

Fast Digital Inputs

Overview

If fast digital inputs are used as regular digital inputs, refer to regular digital inputs wiring diagram, page 72.

Characteristics

The table indicates the digital inputs characteristics:

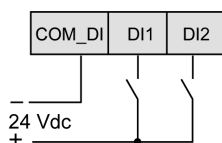
| Characteristic | Value | |
|--------------------------------|---------------------------------------|---|
| | Used as fast input | Used as regular input |
| Type | Digital input | |
| Power draw (maximum) | 5 mA | |
| Working voltage | +0...38 Vdc | +0...38 Vdc 0...24 Vac +/-10 % 50/60 Hz |
| Pulse detection minimum length | Positive pulse 0.15 ms | Positive or negative pulse: <ul style="list-style-type: none"> AV•30••••0500 / AV•62••••0500: 40 ms AV•84••••500 / AV•126••••500: 20 ms EVE1020000500: 40 ms |
| Maximum frequency measurement | 2 kHz | - |
| Logic type | Digital inputs work in positive logic | Digital inputs work in positive or negative logic |
| Level 1 | +20...38 Vdc | +20...38 Vdc 24 Vac +/-10 % 50/60 Hz |
| Level 0 | +0...4 Vdc | +0...4 Vdc 0...3 Vac 50/60 Hz |

Logic type description

| Logic type | Active state |
|----------------|--|
| Positive logic | Output supplies current (source output) Current flows to the input (sink input) |
| Negative logic | Output draws current (sink output) Current flows from the input (source input) |

Wiring Diagram Example

AV•30••••0500 / AV•62••••0500 / AV•84••••500 / AV•126••••500 (CN3) fast digital input:



| Pitch of the terminal block | Cabling length |
|-----------------------------|------------------|
| 3.50 mm (0.14 in) | 10 m (32.808 ft) |

For more information about the wiring, refer to Best wiring practices, page 26.

Related Devices and Connectors

The table indicates the related devices and connectors:

| Related Device | Connector | Label | Description | | | | |
|----------------|-----------|--|-------------|------------------------------|-----|--------|---------------------------------|
| AV•30••••0500 | CN3 | <table border="1"> <tr> <td>COM_DI</td> <td>DI1</td> <td>DI2</td> </tr> </table> | COM_DI | DI1 | DI2 | COM-DI | Common for digital inputs 1...2 |
| COM_DI | | | DI1 | DI2 | | | |
| AV•62••••0500 | | | DI1...DI2 | Regular digital inputs 1...2 | | | |
| AV•84••••500 | | | | | | | |
| AV•126••••500 | | | | | | | |
| EVE•••••0500 | CN2 | | | | | | |

Regular Digital Inputs

Characteristics

The table indicates the digital inputs characteristics:

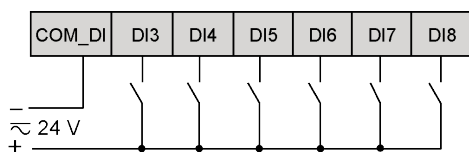
| Characteristic | Value |
|--------------------------------|--|
| Type | Digital input |
| Power draw (maximum) | 5 mA |
| Working voltage | +0...38 Vdc 0...24 Vac +/-10 % 50/60 Hz |
| Pulse detection minimum length | <ul style="list-style-type: none"> • AV•84••••500/AV•126••••500 positive or negative pulse <ul style="list-style-type: none"> ◦ DI3...DI4: 20 ms ◦ DI5...DI8: 40 ms • AV•126••••500 positive or negative pulse <ul style="list-style-type: none"> ◦ DI9...DI12: 40 ms • EVE1020000500 positive pulse <ul style="list-style-type: none"> ◦ DI3...DI6: 40 ms |
| Logic type | Digital inputs work in positive logic <ul style="list-style-type: none"> • AV•84••••500/AV•126••~500: Digital inputs work in positive or negative logic • EVE1020000500: Digital inputs work in positive logic |
| Level 1 | +20...38 Vdc 24 Vac +/-10 % 50/60 Hz |
| Level 0 | +0...4 Vdc 0...3 Vac 50/60 Hz |

Logic type description:

| Logic type | Active state |
|----------------|--|
| Positive logic | Output supplies current (source output) Current flows to the input (sink input) |
| Negative logic | Output draws current (sink output) Current flows from the input (source input) |

Wiring Diagram Example

AV•84•••••500 / AV•126•••••500 (CN4) regular digital input:



| | |
|------------------------------------|-----------------------|
| Pitch of the terminal block | Cabling length |
| 3.50 mm (0.14 in) | 10 m (32.808 ft) |

For more information about the wiring, refer to Best wiring practices, page 26.

Related Devices and Connectors

The table indicates the related devices and connectors:

| Related Device | Connector | Label | Description | | | | | | | |
|---------------------|--|-------------------------------|-------------|------|------|------|--------|----------------------------------|--------|---------------------------------|
| AV•84•••••500 | <table border="1"> <tr> <td>COM_DI</td> <td>DI3</td> <td>DI4</td> <td>DI5</td> <td>DI6</td> <td>DI7</td> <td>DI8</td> </tr> </table> | COM_DI | DI3 | DI4 | DI5 | DI6 | DI7 | DI8 | COM-DI | Common for digital inputs 3...8 |
| COM_DI | | DI3 | DI4 | DI5 | DI6 | DI7 | DI8 | | | |
| AV•126•••••500 | DI3...DI8 | Regular digital inputs 3...8 | | | | | | | | |
| AV•126•••••500 | <table border="1"> <tr> <td>COM_DI</td> <td>DI9</td> <td>DI10</td> <td>DI11</td> <td>DI12</td> </tr> </table> | COM_DI | DI9 | DI10 | DI11 | DI12 | COM-DI | Common for digital inputs 9...12 | | |
| COM_DI | | DI9 | DI10 | DI11 | DI12 | | | | | |
| | DI9...DI12 | Regular digital inputs 9...12 | | | | | | | | |
| EVE- E1020000500 | <table border="1"> <tr> <td>COM_DI</td> <td>DI3</td> <td>DI4</td> <td>DI5</td> <td>DI6</td> </tr> </table> | COM_DI | DI3 | DI4 | DI5 | DI6 | COM-DI | Common for digital inputs 3...6 | | |
| COM_DI | | DI3 | DI4 | DI5 | DI6 | | | | | |
| | DI3...DI6 | Regular digital inputs 3...6 | | | | | | | | |

Digital Output

Digital Output

This table presents the digital outputs of controllers and expansion modules:

| Description | AV•30•••••60500 | AV•62•0••0500 | AV•62SS••0500 | AV•8400•••••500 | AV•84SS•••••500 | AV•1260•••••500 | AV•126S•••••500 | EVE6000000500 | EVE1020000500 |
|--|-----------------|---------------|---------------|-----------------|-----------------|-----------------|-----------------|---------------|---------------|
| High voltage relay SPST digital output, page 73 | 2 | 5 | 3 | 7 | 5 | 10 | 8 | 6 | 10 |
| High voltage Solid-state relay digital output, page 75 | - | - | 2 | - | 2 | - | 2 | - | - |
| High voltage relay SPDT digital output, page 76 | 1 | 1 | 1 | 1 | 1 | 2 | 2 | - | - |

These devices have analog outputs that can be configured as low voltage (SELV), open collector outputs. For more details, refer to the configuration of analog outputs, page 78.

NOTE: The commons Cx are not internally connected together.

High voltage Relay SPST Digital Output

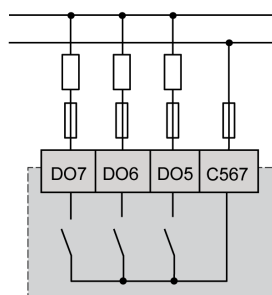
Characteristics

The table indicates the digital outputs characteristics:

| Characteristic | Value |
|---|------------------------------------|
| Maximum voltage | 250 Vac |
| Maximum current | 3 A resistive load, 2 FLA / 12 LRA |
| Minimum switching capacity | 100 mA / 5 Vdc |
| Electrical durability conforming to UL60730 | 100 000 cycles, 3 A at 250 Vac |

Wiring Diagram Example

AV•84•••••500 (CN7) SPST relay output:

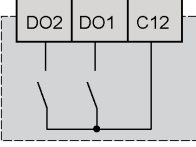
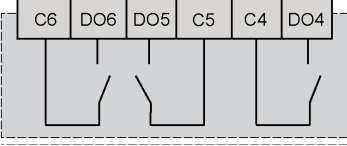
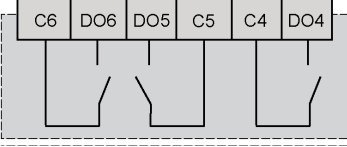
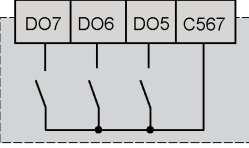
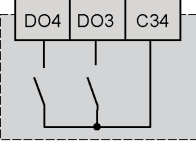
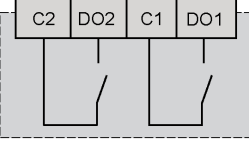
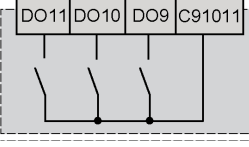
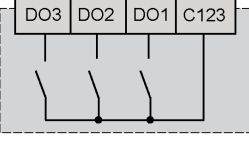
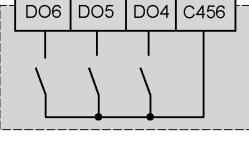


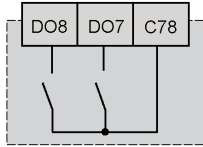
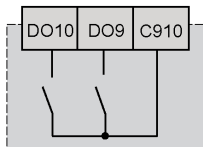
| Pitch of the terminal block |
|-----------------------------|
| 5.00 mm (0.197 in) |

For more information about the wiring, refer to Best wiring practices, page 26.

Related Devices and Connectors

The table indicates the related devices and connectors:

| Related Device | Connector | | Label | Description |
|----------------------------------|-----------|---|------------|--|
| AV•30•••••0500 AV•62•••••0500 | CN9 |  | C12 | Common for output relays 1...2 Maximum current: 6 A |
| | | | DO1...DO2 | Output relays 1...2 |
| AV•62•0••0500 | CN15 |  | C4 | Common for output relay 4 Maximum current: 3 A |
| | | | C5 | Common for output relay 5 Maximum current: 3 A |
| | | | C6 | Common for output relay 6 Maximum current: 3 A |
| | | | DO4...DO6 | Output relays 4...6 |
| AV•62SS••0500 | CN15 |  | C4 | Common for output relay 4 Maximum current: 3 A |
| | | | DO4 | Output relay 4 NOTE: DO5 and DO6 are SSR outputs, page 76. |
| AV•84•••••500 AV•126•••••500 | CN7 |  | C567 | Common for output relays 5...7 Maximum current: 9 A |
| | | | DO5...DO7 | Output relays 5...7 |
| | CN8 |  | C34 | Common for output relays 3...4 Maximum current: 6 A |
| | | | DO3...DO4 | Output relays 3...4 |
| AV•8400•••500 AV•1260•••500 | CN9 |  | C1 | Common for output relay 1 Maximum current: 3 A |
| | | | C2 | Common for output relay 2 Maximum current: 3 A |
| | | | DO1...DO2 | Output relays 1...2 |
| AV•126•••••500 | CN15 |  | C91011 | Common for output relays 9...11 Maximum current: 9 A |
| | | | DO9...DO11 | Output relays 9...11 |
| EVE•••••0500 | CN5 |  | C123 | Common for output relays 1...3 Maximum current: 9 A |
| | | | DO1...DO3 | Output relays 1...3 |
| | CN4 |  | C456 | Common for output relays 4...6 Maximum current: 9 A |
| | | | DO4...DO6 | Output relays 4...6 |

| Related Device | Connector | Label | Description | |
|----------------|-----------|---|-------------|---|
| EVE1020000500 | CN11 |  | C78 | Common for output relays 7...8 Maximum current: 6 A |
| | | | DO7...DO8 | Output relays 7...8 |
| | CN10 |  | C910 | Common for output relays 9...10 Maximum current: 6 A |
| | | | DO9...DO10 | Output relays 9...10 |

High Voltage Solid-State Relay Digital Output

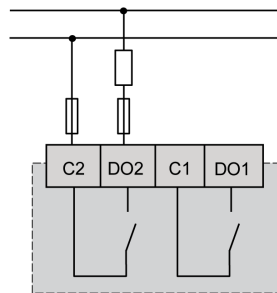
Characteristics

The table indicates the SSR output characteristics:

| Characteristic | Value | |
|----------------------------|---------------|--------------------------------|
| | AV•62SS••0500 | AV•84SS•••500 AV•126S•••500 |
| Nominal voltage | 75...240 Vac | |
| Maximum current | 0.2 A | 0.5 A |
| Switching rate range | 45...65 Hz | |
| Minimum switching capacity | 20 mA | |

Wiring Diagram Example

AV•84SS•••500 (CN9) SSR output:

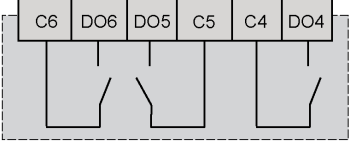
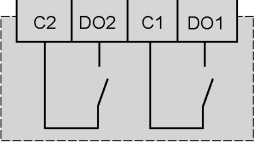


| Pitch of the terminal block |
|-----------------------------|
| 5.00 mm (0.197 in) |

For more information about the wiring, refer to [Best wiring practices](#), page 26.

Related Devices and Connectors

The table indicates the related devices and connectors:

| Related Device | Connector | | Label | Description |
|--------------------------------|-----------|---|---|---|
| AV•62SS••0500 | CN15 |  | C5 | Common for SSR output 5 Maximum current: 0.2 A |
| | | | C6 | Common for SSR output 6 Maximum current: 0.2 A |
| | | | DO5...DO6 | SSR Outputs 5...6 NOTE: DO4 is not an SSR output., page 74 |
| AV•84SS•••500 AV•126S•••500 | CN9 |  | C1 | Common for SSR output 1 Maximum current: 0.5 A |
| C2 | | | Common for SSR output 2 Maximum current: 0.5 A | |
| DO1...DO2 | | | SSR Outputs 1...2 | |

High voltage Relay SPDT Digital Output

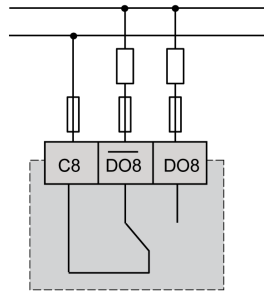
Characteristics

The table indicates the digital outputs characteristics:

| Characteristic | Value | |
|---|---|--|
| | | AV•30••••0500 AV•62••••0500 AV•84•••6I500 AV•126•••I500 AV•840005I500 AV•126005I500 |
| Maximum voltage | 250 Vac | 240 Vac |
| Maximum current | 3 A resistive load, NO contact: 2.2 FLA / 13.2 LRA | -20...55 °C (-4...131 °F): 3 A resistive load -20...60 °C (-4...140 °F): 1 A resistive load -20...65 °C (-4...149 °F): 1 A resistive load if DO8 is inactive |
| Minimum switching capacity | 300 mA, resistive load | 300 mA, resistive load |
| Electrical durability conforming to UL60730 | 100 000 cycles | 100 000 cycles |

Wiring Diagram Example

AV•84•••••500 / AV•126•••••500 (CN6) SPDT relay output:

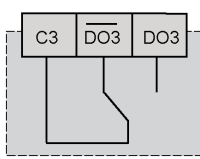
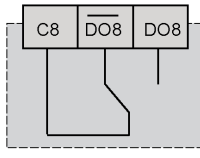
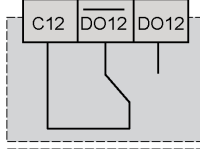


| |
|------------------------------------|
| Pitch of the terminal block |
| 5.00 mm (0.197 in) |

For more information about the wiring, refer to Best wiring practices, page 26.

Related Devices and Connectors

The table indicates the related devices and connectors:

| Related Device | Connector | | Label | Description |
|----------------------------------|-----------|---|-------|---|
| AV•30•••••0500 AV•62•••••0500 | CN6 |  | C3 | Common for output relay 3 Maximum current: 3 A |
| | | | DO3 | Output relay3 - Normally open |
| | | | DO3- | Output relay 3 - Normally closed |
| AV•84•••••500 AV•126•••••500 | CN6 |  | C8 | Common for output relay 8 Maximum current: 3 A ⁽¹⁾⁽²⁾ |
| | | | DO8 | Output relay 8 - Normally open |
| | | | DO8- | Output relay 8 - Normally closed |
| AV•126•••••500 | CN14 |  | C12 | Common for output relay 12 Maximum current: 3 A ⁽¹⁾ |
| | | | DO12 | Output relay 12 - Normally open |
| | | | DO12- | Output relay 12 - Normally closed |

(1) AV•84•••••60500 / AV•126•••••0500: The maximum current is limited to 1 A if the ambient temperature exceeds 55 °C (131 °F).
 (2) AV•84•••••60500 / AV•126•••••0500: The ambient temperature must not exceed 60 °C (140 °F) if DO8 is active.

Analog Inputs

Analog Inputs

This table presents the analog inputs of controllers and expansion modules:

| Description | AV-30***60500 | AV-62-0**0500 | AV-62SS**0500 | AV-8400***500 | AV-84SS***500 | AV-1260***500 | AV-126S***500 | EVE6000000500 | EVE1020000500 |
|--|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| Configurable analog inputs or digital input. | 2 | 8 | 8 | 8 | 8 | 12 | 12 | 4 | 10 |

Analog Inputs

Overview

Controllers analog inputs are identified as AI1...AIx.

The inputs are configurable in pairs, AI1- AI2 is the first pair, AI3-AI4 is the second pair, and so on, up to the last pair. Both AIs of a pair must be configured in order to belong to the same type group.

Using the parameter *Cfg_Aix*, an analog input AIx can be configured to acquire a signal by a physical resource (probe, digital input, voltage/current signal) as specified in the following table:

| Type group | Cfg_Aix | Description |
|--|---------|--|
| NTC resistive input, page 81 or Digital input, page 86 | 0 | NTC (NK103), 10 kΩ at 25 °C, BETA value 3977 |
| | 1 | Digital input |
| Current input, page 84 | 2 | NTC (103AT-2), 10 kΩ at 25 °C, BETA value 3435 |
| | 7 | hΩ (NTC) ⁽¹⁾ |
| Voltage input 0...10 Vdc, page 85 | 3 | 4...20 mA |
| | 11 | 0...20 mA |
| Voltage input 0...5 Vdc, page 85 | 4 | 0...10 Vdc |
| | 5 | 0...5 Vdc Ratiometric |
| Resistive input, page 82 | 10 | 0...5 Vdc |
| | 6 | Pt1000 |
| | 8 | daΩ (Pt1000) ⁽²⁾ |
| | 9 | PTC (KTY81-121) |

(1) Resistance value read, expressed in 0.1 kΩ, for a resistance applied to the input using the controller in NTC configuration, for example creating a divider with pull-up resistance of 10 kΩ. The resistance range for the hΩ(NTC) configuration is up to 150 kΩ.

(2) Resistance value read, expressed in 0.01 kΩ, for a resistance applied to the input using the controller in Pt1000 configuration, that is, creating a divider with pull-up resistance (1.5 kΩ for AV-30***60500 / AV-62***0500, 2 kΩ for other device references). The resistance range for the daΩ (Pt1000) configuration is up to 3 kΩ.

The analog inputs configured as digital inputs are not isolated.

NOTICE

INOPERABLE EQUIPMENT

Only use voltage free type inputs on analog inputs configured as digital inputs.

Failure to follow these instructions can result in equipment damage.

Compatibility in Pairs

Parameters by pair:

| Pairs | Parameter Set | |
|---------|---------------|----------|
| Pair #1 | Cfg_Ai1 | Cfg_Ai2 |
| Pair #2 | Cfg_Ai3 | Cfg_Ai4 |
| Pair #3 | Cfg_Ai5 | Cfg_Ai6 |
| Pair #4 | Cfg_Ai7 | Cfg_Ai8 |
| Pair #5 | Cfg_Ai9 | Cfg_Ai10 |
| Pair #6 | Cfg_Ai11 | Cfg_Ai12 |

NOTE: The all pairs are available for AV•126••••500. Depending on the analog inputs of the device, not all pairs are available, refer to the Related Devices and Connectors, page 80.

Compatibility table for a pair of AIs:

| Example for pair #1 | | | Cfg_Ai1 | | | | | | | | | | | |
|---------------------|----|-----------------------|-------------|---------------|---------------|-----------|------------|-----------------------|--------|----------|--------------|-----------------|-----------|-----------|
| | | | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 |
| | | | NTC (NK103) | Digital input | NTC (103AT-2) | 4...20 mA | 0...10 Vdc | 0...5 Vdc Ratiometric | Pt1000 | hΩ (NTC) | daΩ (Pt1000) | PTC (KTY81-121) | 0...5 Vdc | 0...20 mA |
| Cfg_Ai2 | 0 | NTC (NK103) | ✓ | ✓ | ✓ | - | - | - | - | ✓ | - | - | - | - |
| | 1 | Digital input | ✓ | ✓ | ✓ | - | - | - | - | ✓ | - | - | - | - |
| | 2 | NTC (103AT-2) | ✓ | ✓ | ✓ | - | - | - | - | ✓ | - | - | - | - |
| | 3 | 4...20 mA | - | - | - | ✓ | - | - | - | - | - | - | - | ✓ |
| | 4 | 0...10 Vdc | - | - | - | - | ✓ | - | - | - | - | - | - | - |
| | 5 | 0...5 Vdc Ratiometric | - | - | - | - | - | ✓ | - | - | - | - | ✓ | - |
| | 6 | Pt1000 | - | - | - | - | - | - | ✓ | - | ✓ | ✓ | - | - |
| | 7 | hΩ (NTC) | ✓ | ✓ | ✓ | - | - | - | - | ✓ | - | - | - | - |
| | 8 | daΩ (Pt1000) | - | - | - | - | - | - | ✓ | - | ✓ | ✓ | - | - |
| | 9 | PTC (KTY81-121) | - | - | - | - | - | - | ✓ | - | ✓ | ✓ | - | - |
| | 10 | 0...5 Vdc | - | - | - | - | - | ✓ | - | - | - | - | ✓ | - |
| | 11 | 0...20 mA | - | - | - | ✓ | - | - | - | - | - | - | - | ✓ |

Applying not allowed configuration produces the error number 8003_h on the field value of both probes (unsigned decimal: 32771 / signed decimal: -32765).

Voltage Analog Inputs or Current Analog Inputs Configuration

According to the physical resources wired (voltage signal or current signal), inputs must be configured using the related parameters.

Analog inputs type can be configured as specified in the following table:

| Parameter | Description | Range | Default value |
|-------------------------|---------------------------------------|---------------|---------------|
| <i>FullScaleMin_Alx</i> | Analog input Alx start of scale value | -9999...+9999 | 0 |
| <i>FullScaleMax_Alx</i> | Analog input Alx full scale value | -9999...+9999 | 1000 |
| <i>Calibration_Alx</i> | Analog input Alx differential | -1000...+1000 | 0 |

Note:

| Type of probe configured | Minimum full scale Alx | Maximum full scale Alx |
|-----------------------------|------------------------|------------------------|
| 0/4...20 mA current probe | 0/4 mA | 20 mA |
| 0...10 Vdc voltage probe | 0 Vdc | 10 Vdc |
| 0...5 Vdc ratiometric probe | 10 % (0.5 Vdc) | 90 % (4.5 Vdc) |
| 0...5 Vdc probe | 0 Vdc | 5 Vdc |

For details on the values and characteristics of parameters, refer to the Parameters, page 125.

Related Devices and Connectors

The table indicates the related devices and connectors:

| Related Device | Connector | Label | Description | | | | | | | | | | | | | | | | | | | |
|----------------------------------|--|--|-------------|----------|---------|----------|----------|---|----------|---|--------|--|-----------|---|-----------|--|------------|--|-----|-------------------|-----------|--|
| AV•30•••••0500 AV•62•••••0500 | CN5 | <table border="1"> <tr> <td>AI1</td> <td>AI2</td> <td>GND</td> <td>5 V out</td> <td>24 V out</td> </tr> </table> | AI1 | AI2 | GND | 5 V out | 24 V out | <table border="1"> <tr> <td>24 Vdc</td> <td>+24 Vdc power out for analog inputs, max current 100 mA</td> </tr> <tr> <td>5 Vdc</td> <td>+5 Vdc power out for ratiometric analog inputs, max current 40 mA</td> </tr> <tr> <td>GND</td> <td>0 V signal ground</td> </tr> <tr> <td>AI1...AI2</td> <td>Analog inputs 1... 2 or dry contact digital inputs</td> </tr> </table> | 24 Vdc | +24 Vdc power out for analog inputs, max current 100 mA | 5 Vdc | +5 Vdc power out for ratiometric analog inputs, max current 40 mA | GND | 0 V signal ground | AI1...AI2 | Analog inputs 1... 2 or dry contact digital inputs | | | | | | |
| AI1 | AI2 | GND | 5 V out | 24 V out | | | | | | | | | | | | | | | | | | |
| 24 Vdc | +24 Vdc power out for analog inputs, max current 100 mA | | | | | | | | | | | | | | | | | | | | | |
| 5 Vdc | +5 Vdc power out for ratiometric analog inputs, max current 40 mA | | | | | | | | | | | | | | | | | | | | | |
| GND | 0 V signal ground | | | | | | | | | | | | | | | | | | | | | |
| AI1...AI2 | Analog inputs 1... 2 or dry contact digital inputs | | | | | | | | | | | | | | | | | | | | | |
| AV•62•••••0500 | CN13 | <table border="1"> <tr> <td>AI3</td> <td>AI4</td> <td>AI5</td> <td>AI6</td> <td>AI7</td> <td>AI8</td> <td>GND</td> </tr> </table> | AI3 | AI4 | AI5 | AI6 | AI7 | AI8 | GND | <table border="1"> <tr> <td>GND</td> <td>0 V signal ground</td> </tr> <tr> <td>AI3...AI8</td> <td>Analog inputs 3... 8 or dry contact digital inputs</td> </tr> </table> | GND | 0 V signal ground | AI3...AI8 | Analog inputs 3... 8 or dry contact digital inputs | | | | | | | | |
| AI3 | AI4 | AI5 | AI6 | AI7 | AI8 | GND | | | | | | | | | | | | | | | | |
| GND | 0 V signal ground | | | | | | | | | | | | | | | | | | | | | |
| AI3...AI8 | Analog inputs 3... 8 or dry contact digital inputs | | | | | | | | | | | | | | | | | | | | | |
| AV•84•••••500 AV•126•••••500 | CN5 | <table border="1"> <tr> <td>AI1</td> <td>AI2</td> <td>AI3</td> <td>AI4</td> <td>AI5</td> <td>AI6</td> <td>AI7</td> <td>AI8</td> <td>GND</td> <td>5 V out</td> <td>24 V out</td> </tr> </table> | AI1 | AI2 | AI3 | AI4 | AI5 | AI6 | AI7 | AI8 | GND | 5 V out | 24 V out | <table border="1"> <tr> <td>24 Vdc</td> <td>+24 Vdc power out for analog inputs, max current 150 mA ⁽¹⁾</td> </tr> <tr> <td>5 Vdc</td> <td>+5 Vdc power out for ratiometric analog inputs, max current 50 mA ⁽¹⁾</td> </tr> <tr> <td>GND</td> <td>0 V signal ground</td> </tr> <tr> <td>AI1...AI8</td> <td>Analog inputs 1... 8 or dry contact digital inputs</td> </tr> </table> | 24 Vdc | +24 Vdc power out for analog inputs, max current 150 mA ⁽¹⁾ | 5 Vdc | +5 Vdc power out for ratiometric analog inputs, max current 50 mA ⁽¹⁾ | GND | 0 V signal ground | AI1...AI8 | Analog inputs 1... 8 or dry contact digital inputs |
| AI1 | AI2 | AI3 | AI4 | AI5 | AI6 | AI7 | AI8 | GND | 5 V out | 24 V out | | | | | | | | | | | | |
| 24 Vdc | +24 Vdc power out for analog inputs, max current 150 mA ⁽¹⁾ | | | | | | | | | | | | | | | | | | | | | |
| 5 Vdc | +5 Vdc power out for ratiometric analog inputs, max current 50 mA ⁽¹⁾ | | | | | | | | | | | | | | | | | | | | | |
| GND | 0 V signal ground | | | | | | | | | | | | | | | | | | | | | |
| AI1...AI8 | Analog inputs 1... 8 or dry contact digital inputs | | | | | | | | | | | | | | | | | | | | | |
| AV•126•••••500 | CN13 | <table border="1"> <tr> <td>AI9</td> <td>AI10</td> <td>AI11</td> <td>AI12</td> <td>GND</td> <td>5 V out</td> <td>24 V out</td> </tr> </table> | AI9 | AI10 | AI11 | AI12 | GND | 5 V out | 24 V out | <table border="1"> <tr> <td>24 Vdc</td> <td>+24 Vdc power out for analog inputs, max current 150 mA ⁽¹⁾</td> </tr> <tr> <td>5 Vdc</td> <td>+5 Vdc power out for ratiometric analog inputs, max current 50 mA ⁽¹⁾</td> </tr> <tr> <td>GND</td> <td>0 V signal ground</td> </tr> <tr> <td>AI9...AI12</td> <td>Analog inputs 9...12 for dry contact digital inputs</td> </tr> </table> | 24 Vdc | +24 Vdc power out for analog inputs, max current 150 mA ⁽¹⁾ | 5 Vdc | +5 Vdc power out for ratiometric analog inputs, max current 50 mA ⁽¹⁾ | GND | 0 V signal ground | AI9...AI12 | Analog inputs 9...12 for dry contact digital inputs | | | | |
| AI9 | AI10 | AI11 | AI12 | GND | 5 V out | 24 V out | | | | | | | | | | | | | | | | |
| 24 Vdc | +24 Vdc power out for analog inputs, max current 150 mA ⁽¹⁾ | | | | | | | | | | | | | | | | | | | | | |
| 5 Vdc | +5 Vdc power out for ratiometric analog inputs, max current 50 mA ⁽¹⁾ | | | | | | | | | | | | | | | | | | | | | |
| GND | 0 V signal ground | | | | | | | | | | | | | | | | | | | | | |
| AI9...AI12 | Analog inputs 9...12 for dry contact digital inputs | | | | | | | | | | | | | | | | | | | | | |
| EVE•••••0500 | CN3 | <table border="1"> <tr> <td>AI1</td> <td>AI2</td> <td>AI3</td> <td>AI4</td> <td>GND</td> <td>5 V out</td> <td>24 V out</td> </tr> </table> | AI1 | AI2 | AI3 | AI4 | GND | 5 V out | 24 V out | | | | | | | | | | | | | |
| AI1 | AI2 | AI3 | AI4 | GND | 5 V out | 24 V out | | | | | | | | | | | | | | | | |

| Related Device | Connector | Label | Description | | | | | | | | | |
|---|--|---|--|-----|-----|-----|------|-----|---------|----------|---------|----------|
| | | 24 Vdc | +24 Vdc power out for analog inputs, max current 125 mA ⁽¹⁾ | | | | | | | | | |
| | | 5 Vdc | +5 Vdc power out for ratiometric analog inputs, max current 50 mA ⁽¹⁾ | | | | | | | | | |
| | | GND | 0 V signal ground | | | | | | | | | |
| | | AI1...AI4 | Analog inputs 1...4 or dry contact digital inputs | | | | | | | | | |
| EV-E1020000500 | CN9 | <table border="1"> <tr> <td>AI5</td><td>AI6</td><td>AI7</td><td>AI8</td><td>AI9</td><td>AI10</td><td>GND</td><td>5 V out</td><td>24 V out</td> </tr> </table> | | AI5 | AI6 | AI7 | AI8 | AI9 | AI10 | GND | 5 V out | 24 V out |
| | | AI5 | AI6 | AI7 | AI8 | AI9 | AI10 | GND | 5 V out | 24 V out | | |
| | | 24 Vdc | +24 Vdc power out for analog inputs, max current 125mA ⁽¹⁾ | | | | | | | | | |
| | | 5 Vdc | +5 Vdc power out for ratiometric analog inputs, max current 50 mA ⁽¹⁾ | | | | | | | | | |
| | | GND | 0 V signal ground | | | | | | | | | |
| AI5...AI10 | Analog inputs 5...10 or dry contact digital inputs | | | | | | | | | | | |
| <p>(1) The maximum current value is the sum between the maximum currents supplied by the corresponding terminals in the base board connector and in the upper board connector.</p> | | | | | | | | | | | | |

AVP1•000W0500 Display Embedded Analog Inputs Parameters

The temperature and humidity sensors analog input are embedded in the display.

The parameters related to the analog inputs are listed in the following table:

| Parameter | Description | Range |
|------------------------|---------------------------------|-------------------------------------|
| <i>Temp_UM</i> | Unit of temperature measurement | Value 0: °C Value 1: °F |
| <i>Calibration_NTC</i> | NTC differential | -18.0...+18.0 Unit: 0.1 °C or °F |
| <i>Calibration_RH</i> | RH percentage differential | -1000...+1000 Unit: 0.1 %RH |

For details on the values and characteristics of parameters, refer to the Parameters, page 153.

NTC Analog Input

Characteristics

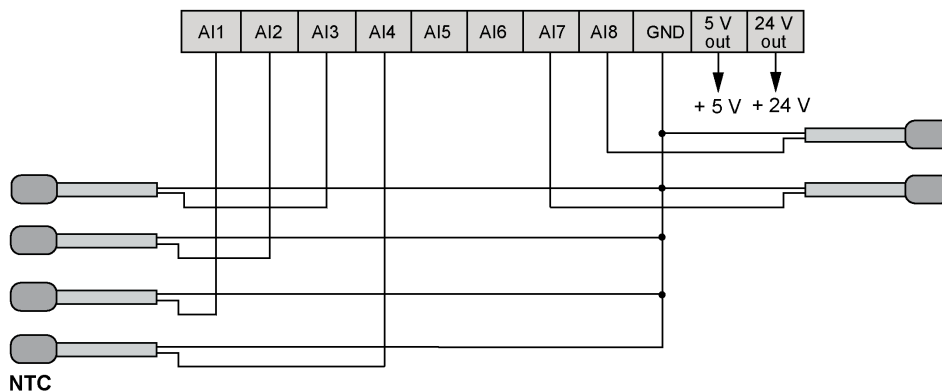
Using the parameter *Cfg_Aix*, an analog input AIx can be configured to acquire a signal by a physical resource (probe, digital input, voltage/current signal) as specified in the following table:

| <i>Cfg_Aix</i> | Description | Accuracy Range | Accuracy | Resolution | Input Impedance |
|----------------|--|--------------------------------------|---------------------------|---------------------|-----------------|
| 0 | NTC (NK103) 10 kΩ at 25 °C BETA value 3977 | -40...+137 °C (-40...+278.6 °F) | | | |
| | | -40...+110 °C (-40...+230 °F) | +/-1 °C (+/-1.8 °F) | 0.1 °C (0.18 °F) | 10 kΩ |
| | | +110...+137 °C (+230...+278.6 °F) | +/-1.9 °C (+/-3.42 °F) | | |
| 2 | NTC (103AT-2) 10 kΩ at 25 °C | -50...+110 °C (-58...+230 °F) | +/-1 °C (+/-1.8 °F) | 0.1 °C (0.18 °F) | 10 kΩ |

| <i>Cfg_Aix</i> | Description | Accuracy Range | Accuracy | Resolution | Input Impedance | |
|----------------|-----------------|----------------|------------|------------|-----------------|--|
| | BETA value 3435 | | | | | |
| 7 | hΩ (NTC) | 0...150 kΩ | | | | |
| | AV•30•••60500 | 0...75 kΩ | +/-0.85 kΩ | 0.1 kΩ | 10 kΩ | |
| | AV•62••••0500 | 75...150 kΩ | +/-2.4 kΩ | | | |
| | AV•84•••••500 | 0...150 kΩ | +/-0.85 kΩ | | | |
| | AV•126•••••500 | | | | | |
| | EVE•••••0500 | 0...70 kΩ | +/-1 kΩ | | | |
| | | 70...120 kΩ | +/-2.5 kΩ | | | |
| | | 120...150 kΩ | +/-6 kΩ | | | |

Wiring Diagram Example

AV•84•••••500 / AV•126•••••500 CN5 NTC input connection:



| Pitch of the terminal block | Cabling length |
|-----------------------------|------------------|
| 3.50 mm (0.14 in) | 10 m (32.808 ft) |

For more information about the wiring, refer to wiring best practices, page 26.

Resistive Analog Input

Characteristics

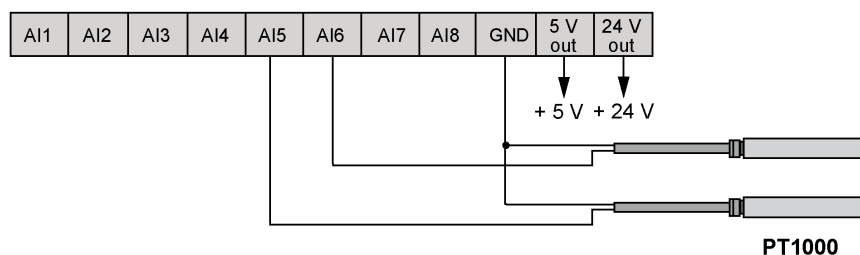
Using the parameter *Cfg_Aix*, an analog input AIx can be configured to acquire a signal by a physical resource (probe, digital input, voltage/current signal) as specified in the following table:

| <i>Cfg_Aix</i> | Description | Accuracy Range | Accuracy | Resolution | Input Impedance | |
|----------------|----------------|----------------------------------|--------------|------------------------|-----------------|--|
| 6 | Pt1000 | -200...+850 °C (-328...+1562 °F) | | | | |
| | AV•30•••60500 | -200...0 °C | +/-2.61 °C | 0.1 °C (+/-0.18 °F) | 1.5 kΩ | |
| | AV•62••••0500 | (-328...+32 °F) | (+/-4.70 °F) | | | |
| | AV•84•••••500 | 0...+80 °C | +/-3.3 °C | | 2 kΩ | |
| | AV•126•••••500 | (+32...+176 °F) | (+/-5.94 °F) | | | |
| | | +80...+150 °C | +/-3.9 °C | | | |
| | | (+176...+302 °F) | (+/-7.02 °F) | | | |

| Cfg_Aix | Description | Accuracy Range | Accuracy | Resolution | Input Impedance |
|--------------------------------------|------------------------|---|----------------------------------|---------------------------|---|
| | | +150...+400 °C (+302...+752 °F) | +/-7.6 °C (+/-13.68 °F) | | AV•84•••••500 AV•126•••••500 |
| | | +400...+850 °C (+752...+1562 °F) | +/-17.8 °C (+/-32.04 °F) | | |
| | EVE•••••0500 | -200...-100 °C (-328...-148 °F) | +/-5 °C (+/-9 °F) | 0.1 °C (+/-0.18 °F) | 2 kΩ |
| | | -100...-50 °C (-148...-58 °F) | +/-3 °C (+/-5.4 °F) | | |
| | | -50...+200 °C (-58...+392 °F) | +/-1.5 °C (+/-2.7 °F) | | |
| | | +200...+600 °C (+392...+1112 °F) | +/-15 °C (+/-27 °F) | | |
| +600...+850 °C (+1112...+1562 °F) | +/-30 °C (+/-54 °F) | | | | |
| 8 | daΩ (Pt1000) | 0...3 kΩ | +/-25 Ω | 10 Ω | 1.5 kΩ |
| | | | | | AV•30•••60500 AV•62••••0500 |
| | | | | | 2 kΩ |
| | | | | | AV•84•••••500 AV•126•••••500 EVE•••••0500 |
| 9 | PTC (KTY81-121) | -55...+150 °C (-67...+302 °F) | | | 1.5 kΩ |
| | | AV•30•••60500 AV•62••••0500 AV•84•••••500 AV•126•••••500 | -55...+150 °C (-67...+302 °F) | +/-1.1 °C (+/-1.98 °F) | |
| | EVE•••••0500 | -55...+135 °C (-67...+275 °F) | +/-1.1 °C (+/-1.98 °F) | 0.1 °C (0.18 °F) | 2 kΩ |
| | | +135...+150 °C (+275...+302 °F) | +/-3.1 °C (+/-5.58 °F) | | |

Wiring Diagram Example

AV•84•••••500 / AV•126•••••500 CN5 Pt1000 (AI5 and AI6) inputs connection:



| | |
|------------------------------------|-----------------------|
| Pitch of the terminal block | Cabling length |
| 3.50 mm (0.14 in) | 10 m (32.808 ft) |

For more information about the wiring, refer to [wiring best practices](#), page 26.

Current Analog Input

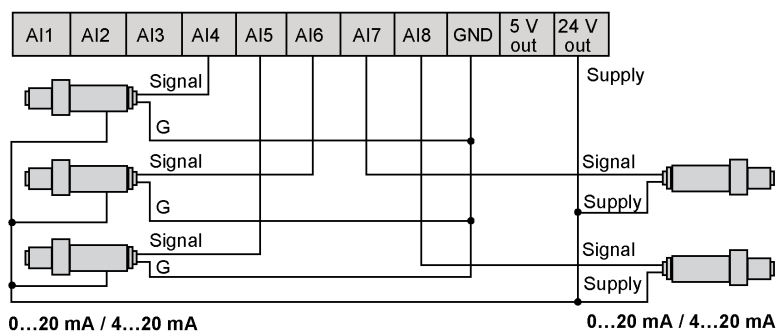
Characteristics

Using the parameter *Cfg_Aix*, an analog input AIx can be configured to acquire a signal by a physical resource (probe, digital input, voltage/current signal) as specified in the following table:

| <i>Cfg_Aix</i> | Description | Range | Accuracy Range | Resolution | Input Impedance |
|----------------|-------------|-----------------------------------|--|------------|-----------------|
| 3 | 4...20 mA | -9999...9999 Default: 0...1000 | 4...20 mA +/-1 % full range + 1 digit | 1 digit | <150 Ω |
| 11 | 0...20 mA | | 0...4 mA +/-2 % full range + 1 digit | | |
| | | | 4...20 mA +/-1 % full range + 1 digit | | |

Wiring Diagram Example

AV•84•••••500 / AV•126•••••500 (CN5) current input connection:



You can power the transducer from the FREE Advance (5 Vdc or 24 Vdc) or with an external supply.

For more information, refer to [transducer technical data sheet](#).

| | |
|------------------------------------|-----------------------|
| Pitch of the terminal block | Cabling length |
| 3.50 mm (0.14 in) | 10 m (32.808 ft) |

For more information about the wiring, refer to [wiring best practices](#), page 26.

Voltage Analog Input

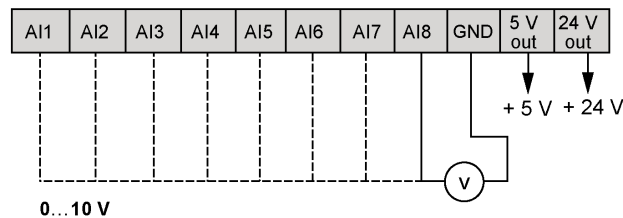
Characteristics

Using the parameter *Cfg_Aix*, an analog input *Aix* can be configured to acquire a signal by a physical resource (probe, digital input, voltage/current signal) as specified in the following table:

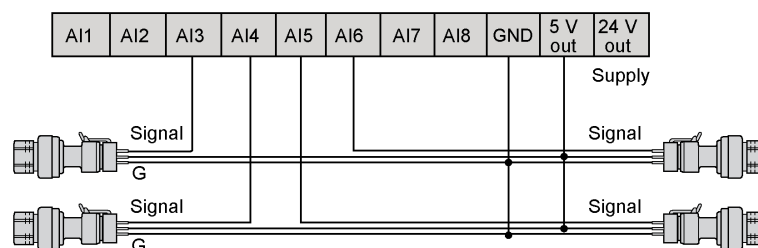
| <i>Cfg_Aix</i> | Description | Range | Accuracy Range | Resolution | Input Impedance |
|----------------|--------------------------|-----------------------------------|--|------------|---|
| 4 | 0...10 Vdc | -9999...9999 Default: 0...1000 | 0...10 Vdc +/-1 % full range + 1 digit | 1 digit | >10 kΩ |
| | | | | | AV•30••••0500 AV•62••••0500 AV•84••••500 AV•126••••500 |
| | | | | | >20 kΩ |
| | | | | | EVE•••••0500 |
| 10 | 0...5 Vdc | -9999...9999 Default: 0...1000 | 0...5 Vdc +/-1 % full range + 1 digit | 1 digit | >20 kΩ |
| | | | | | AV•30••••0500 AV•62••••0500 AV•84••~•500 AV•126••••500 |
| | | | | | >60 kΩ |
| | | | | | EVE•••••0500 |
| 5 | 0...5 Vdc Ratiometric | -9999...9999 Default: 0...1000 | 10 % 5 Vdc...90 % 5 Vdc +/-1 % full range + 1 digit | 1 digit | >20 kΩ |
| | | | | | AV•30~••••0500 AV•62~••••0500 AV•84~••••500 AV•126~••••500 |
| | | | | | >60 kΩ |
| | | | | | EVE•••••0500 |

Wiring Diagram Example

AV•84•••••500 / AV•126•••••500 (CN5) voltage input connection:



AV•84•••••500 / AV•126••~•500 (CN5) 0-5V ratiometric voltage input connection:



| | |
|------------------------------------|-----------------------|
| Pitch of the terminal block | Cabling length |
| 3.50 mm (0.14 in) | 10 m (32.808 ft) |

For more information about the wiring, refer to [wiring best practices](#), page 26.

Analog Input Used as Digital Input

Characteristics

Using the parameter *Cfg_Aix*, an analog input AIx can be configured to acquire a signal by a physical resource (probe, digital input, voltage/current signal) as specified in the following table:

| <i>Cfg_Aix</i> | Description | Range | Accuracy Range | Accuracy | Resolution | Input Impedance |
|----------------|------------------------------|-------|----------------|----------|------------|-----------------|
| 1 | Digital input ⁽¹⁾ | - | - | - | - | 10 kΩ |

(1) The analog inputs configured as digital inputs are not isolated.

The use of an external power supply with the dry contact digital inputs can result in equipment damage.

NOTICE

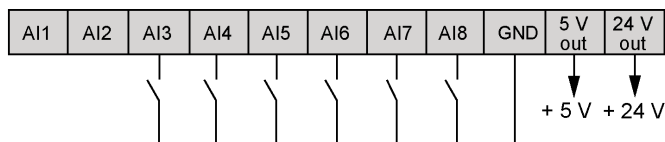
INOPERABLE EQUIPMENT

Do not apply external power supply to the dry contact digital inputs of the device.

Failure to follow these instructions can result in equipment damage.

Wiring Diagram Example

AV•84•••••500 / AV•126•••••500 (CN5) analog input used as digital input connection:



| | |
|------------------------------------|-----------------------|
| Pitch of the terminal block | Cabling length |
| 3.50 mm (0.14 in) | 10 m (32.808 ft) |

For more information about the wiring, refer to [wiring best practices](#), page 26.

Analog Outputs

Analog Outputs

This table presents the analog outputs of controllers and expansion modules:

| Description | AV•30••••60500 | AV•62•0••0500 | AV•62SS••0500 | AV•8400••••500 | AV•844S••••500 | AV•1260••••500 | AV•126S••••500 | EVE6000000500 | EVE10200000500 |
|---|----------------|---------------|---------------|----------------|----------------|----------------|----------------|---------------|----------------|
| Low voltage (SELV) analog outputs, or Open Collector PWM outputs | - | 2 | 2 | 2 | 2 | 2 | 2 | - | 2 |
| Low voltage (SELV) analog outputs | - | - | - | 2 | 2 | 4 | 4 | - | - |

Analog Outputs

Overview

Analog outputs are identified as AO1...AOx.

Analog outputs by device reference:

| Device references | Non-configurable analog outputs | Configurable analog outputs |
|-------------------|---------------------------------|-----------------------------|
| AV•62••••0500 | - | AO1, AO2 |
| AV•84••••500 | AO1, AO2 | AO3, AO4 |
| AV•126••••500 | AO1, AO2, AO5, and AO6 | |
| EVE1020000500 | - | AO1, AO2 |

Devices are equipped with low voltage analog output (SELV) 0...10 Vdc, page 89

Using the parameter *Cfg_AOx*, configurable analog outputs AOx can be configured to provide a signal to a physical resource as specified in the following table:

| Cfg_AOx | Description |
|---------|--|
| 0 | Current modulation 4...20 mA, page 90 |
| 1 | Current ON/OFF, page 90 |
| 2 | Voltage modulation 0...10 Vdc, page 89 |
| 3 | PWM open collector, page 88 |

Related Devices and Connectors

The table indicates the related devices and connectors:

| Related Device | Connector | Label | Description |
|-------------------------------|-----------|-----------|----------------------|
| AV•62••••0500 | CN11 | GND | 0 V signal ground |
| | | AO1...AO2 | Analog outputs 1...2 |
| AV•84••••500 AV•126••••500 | CN2 | GND | 0 V signal ground |
| | | AO1...AO4 | Analog outputs 1...4 |
| AV•126••••500 | CN11 | GND | 0 V signal ground |
| | | AO5...AO6 | Analog outputs 5...6 |
| EVE1020000500 | CN7 | GND | 0 V signal ground |
| | | AO1...AO2 | Analog outputs 1...2 |

PWM Open Collector Outputs

Characteristics

PWM open collector (configurable polarity) configurable analog output characteristics:

| Analog output | <ul style="list-style-type: none"> Frequency Duty cycle | | | Maximum Sink Current | Maximum Supplies Voltage |
|--|--|---|---|----------------------|--------------------------|
| | Range | Accuracy | Resolution | | |
| AO1, AO2 | <ul style="list-style-type: none"> 0...2000 Hz 0.0...100.0 % | <ul style="list-style-type: none"> 1 Hz 0.1 % | <ul style="list-style-type: none"> 1 Hz 0.1 % | 50 mA | 24 Vdc |
| AV•62••••0500 EVE1020000500 | | | | | |
| AO3, AO4 | | | | | |
| AV•84••••6I500 AV•126••••I500 AV•840005I500 AV•126005I500 | | | | | |
| AO3, AO4 | | | | 30 mA | |
| AV•84••••60500 AV•126••••0500 | | | | | |

Analog outputs in PWM mode can be configured as specified in the following table:

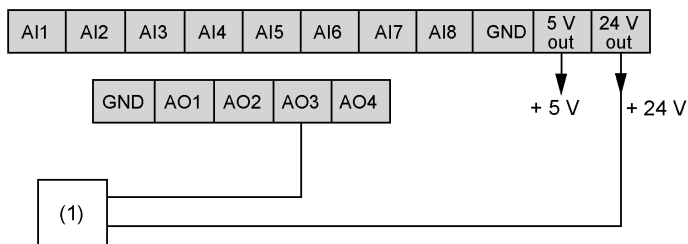
| Parameter | Description | Range |
|------------------------------|---------------|-------------|
| <i>PWM_frequency_AO1_AO2</i> | PWM Frequency | 0...2000 Hz |
| <i>PWM_frequency_AO3_AO4</i> | | |
| <i>PWM_polarity_AO1_AO2</i> | PWM Polarity | 0, 1 |
| <i>PWM_polarity_AO3_AO4</i> | | |

NOTE: The polarity and the frequency are common for the 2 configurable analog outputs of each device.

For details on the values and characteristics of the parameters, refer to Parameters, page 125.

Wiring Diagram Example

AV•84•••••500 / AV•126•••••500 (CN2) open collector PWM analog output (AO3) connection:



(1) Third-party actuator (for example: fan module) or external relay

| Pitch of the terminal block | Cabling length |
|-----------------------------|------------------|
| 3.50 mm (0.14 in) | 10 m (32.808 ft) |

For more information about the wiring, refer to wiring best practices, page 26.

Low Voltage (SELV) Analog Outputs

Characteristics

Voltage modulation 0...10 Vdc non-configurable analog output characteristics:

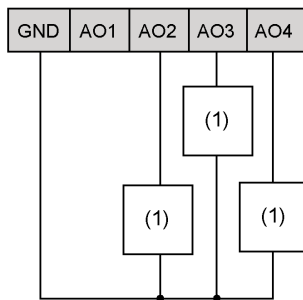
| Analog output | Range | Accuracy | Resolution | Load Impedance |
|------------------------|----------|-------------------|------------|----------------|
| AO1, AO2 | 0...1000 | +/-2 % full scale | 1 digit | > 700 Ω |
| AV•84•••••500 | | | | |
| AO1, AO2, AO5, and AO6 | | | | |
| AV•126•••••500 | | | | |

Voltage modulation 0...10 Vdc configurable analog output characteristics:

| Analog output | Range | Accuracy | Resolution | Load Impedance |
|---------------------------------|----------|-------------------|------------|----------------|
| AO1, AO2 | 0...1000 | +/-2 % full scale | 1 digit | ≥700 Ω |
| AV•62•••••0500 EVE1020000500 | | | | |
| AO3, AO4 | | | | |
| AV•84•••••500 AV•126•••••500 | | | | |

Wiring Diagram Example

AV•84•••••500 / AV•126•••••500 (CN2) Low voltage (SELV) analog outputs (AO2, AO3, and AO4) connection:



(1) Third-party actuator (for example: fan module)

| Pitch of the terminal block | Cabling length |
|-----------------------------|------------------|
| 3.50 mm (0.14 in) | 10 m (32.808 ft) |

For more information about the wiring, refer to wiring best practices, page 26.

Analog Current Output

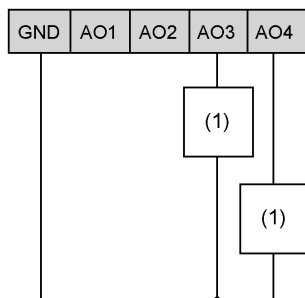
Characteristics

Current modulation 4...20 mA, page 90 configurable analog output characteristics:

| Analog output | Range | Accuracy | Resolution | Load Impedance |
|----------------|----------|-------------------|------------|----------------|
| AO1, AO2 | 0...1000 | +/-2 % full scale | 1 digit | ≤450 Ω |
| AV•62••••0500 | | | | |
| EVE1020000500 | | | | |
| AO3, AO4 | | | | |
| AV•84•••••500 | | | | |
| AV•126•••••500 | | | | |

Wiring Diagram Example

AV•84•••••500 / AV•126•••••500 (CN2) low voltage (SELV) analog outputs (AO3, and AO4) connection:



(1) Third-party actuator (for example: fan module)

| Pitch of the terminal block | Cabling length |
|-----------------------------|------------------|
| 3.50 mm (0.14 in) | 10 m (32.808 ft) |

For more information about the wiring, refer to wiring best practices, page 26.

Current ON/OFF Current Output

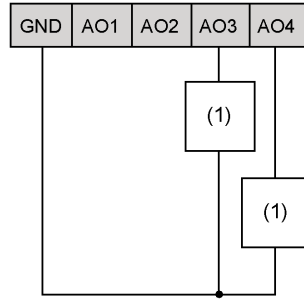
Characteristics

Current ON-OFF configurable analog output characteristics:

| Analog output | Current ON | Current OFF |
|----------------|------------|-------------|
| AO1, AO2 | | |
| AV•62••••0500 | 23 mA | 0 mA |
| EVE1020000500 | 20 mA | |
| AO3, AO4 | | |
| AV•84•••••500 | 23 mA | 0 mA |
| AV•126•••••500 | | |

Wiring Diagram Example

AV•84•••••500 / AV•126•••••500 (CN2) current ON/OFF analog output (AO3, and AO4) connection:



(1) Third-party actuator (for example: fan module)

| Pitch of the terminal block | Cabling length |
|-----------------------------|------------------|
| 3.50 mm (0.14 in) | 10 m (32.808 ft) |

For more information about the wiring, refer to wiring best practices, page 26.

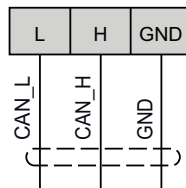
Communication

CAN Expansion Bus Port

Overview

The AV•••••6•500 / AV•••••5•500 controllers and EVE•••••0500 expansion modules can be connected through the CAN expansion bus.

Connector



| Pitch of the terminal block |
|-----------------------------|
| 3.50 mm (0.14 in) |

Wiring

Use a twisted pair shielded cable with two conductors with section 0.5 mm² (AWG 20), plus a sheath (characteristic impedance 120 Ω) with PVC sleeve, nominal capacity between conductors 36 pF/m, nominal capacity between conductor and shield 68 pF/m.

For laying wires, comply with the indications given in standard EN 50174 on information technology wiring. Extra care must be taken in separating data transmission circuits from power lines.

The network must have a bus daisy chain topology and must have 120 Ω 1/4 W termination resistances between the CAN_H and CAN_L terminals on each of the two ends of the bus or enable those embedded on the expansion modules.

The maximum cable length depends on the communication speed set in baud:

| Baud rate | Maximum network length using: | |
|-----------|-------------------------------|----------------------|
| | Embedded CAN | EVS00CA000000 module |
| 50 kBd | 1000 m (3280.83 ft) | 1000 m (3280.83 ft) |
| 125 kBd | 500 m (1640.41 ft) | 500 m (1640.41 ft) |
| 250 kBd | 200 m (656.17 ft) | 250 m (820.21 ft) |
| 500 kBd | 30 m (98.42 ft) | 60 m (196.85 ft) |

NOTICE

INOPERABLE EQUIPMENT

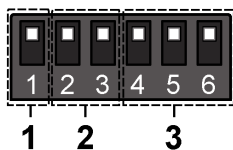
- Do not connect equipment that communicate using RS-485 serial to CAN Expansion Bus terminals.
- Do not connect equipment that communicate using CAN Expansion Bus to RS-485 terminals.

Failure to follow these instructions can result in equipment damage.

EVE.....0500 Port Configuration Using DIP Switch

The 6-position DIP switches on expansion modules is used to:

- Assert the 120 Ω termination (1)
- Set the CAN baud rate (2)
- Set the CAN address (3)



NOTE: The addressing comprises the sum of parameter *Addr_CAN_OB* (Default value: 1) plus the composite value of the 6-position DIP switches DIP4...DIP6 (8 addresses).

| DIP number | 1 | 2 | 3 | 4 | 5 | 6 | |
|---|-------|------|---|---------|---|---|--|
| | 120 Ω | Baud | | Address | | | |
| Disabled Default value | | - | | - | | | |
| Enabled | | | | | | | |
| 500 kBd Default value | - | | | | | | |
| 250 kBd | | | | | | | |
| 125 kBd | | | | | | | |
| 50 kBd | | | | | | | |
| Address <i>Addr_CAN_OB</i> Default value | - | | | | | | |
| Address <i>Addr_CAN_OB</i> + 1 | | | | | | | |

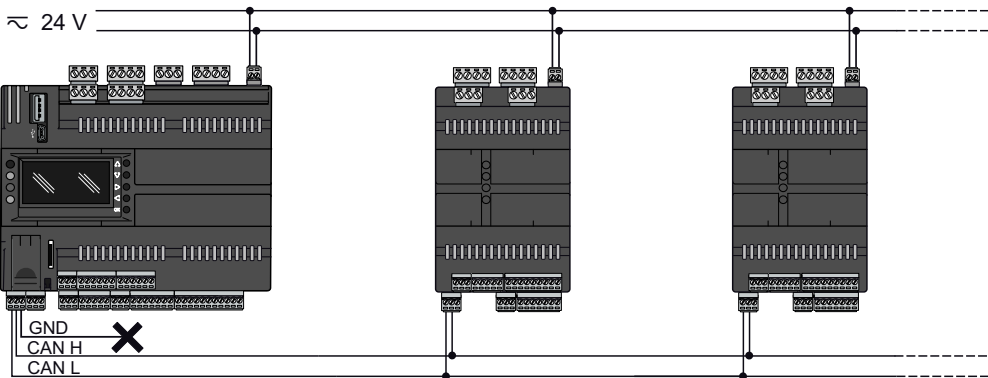
| DIP number | 1 | 2 | 3 | 4 | 5 | 6 |
|--------------------------------|-------|------|---|---------|---|---|
| | 120 Ω | Baud | | Address | | |
| Address <i>Addr_CAN_OB</i> + 2 | | | | | | |
| Address <i>Addr_CAN_OB</i> + 3 | | | | | | |
| Address <i>Addr_CAN_OB</i> + 4 | | | | | | |
| Address <i>Addr_CAN_OB</i> + 5 | | | | | | |
| Address <i>Addr_CAN_OB</i> + 6 | | | | | | |
| Address <i>Addr_CAN_OB</i> + 7 | | | | | | |

CAN Expansion Bus (Field) Network Connection Example

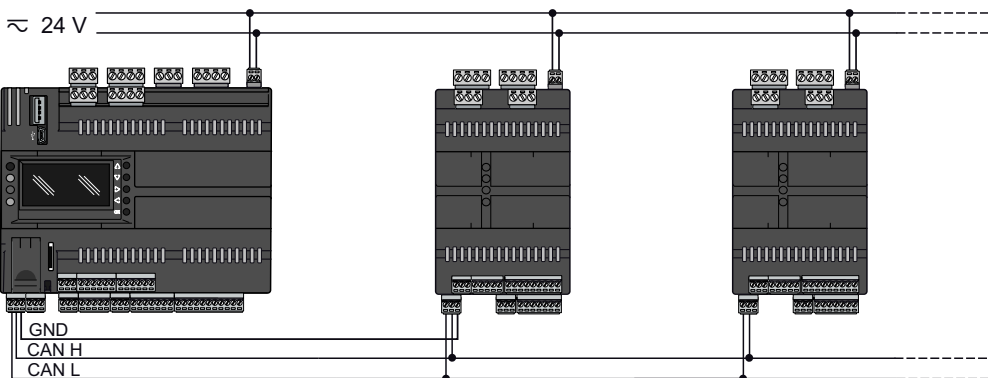
A CAN Expansion Bus (Field) network connection can be constituted by:

- Maximum 1 AV•••••6•500 / AV•••••5•500 functioning as master
- Maximum 12 EVE•••••0500 functioning as slaves. This number can be reduced, depending on the number of inputs and outputs that the master can control.

Non isolated power supply connection example using a AVD1260060500:



Isolated power supply connection example using a AVD126006I500:

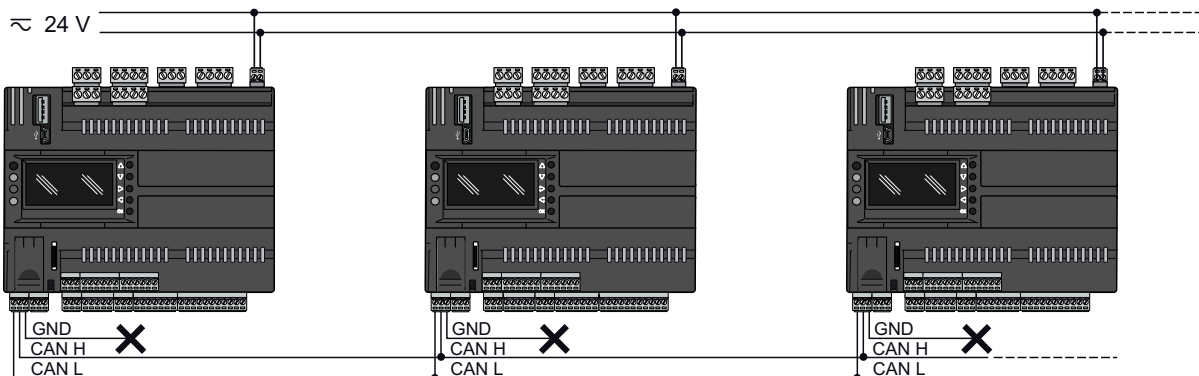


CAN Expansion Bus Connection (Network) Example

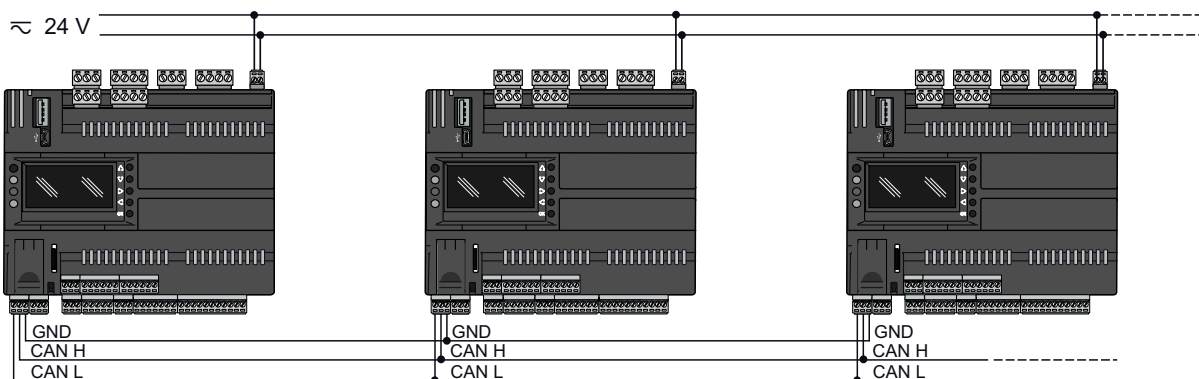
A CAN Expansion Bus (network) connection can be constituted by:

- Maximum 10 AV•••••6•500 / AV•••••5•500 connected in CAN binding. For more details on binding functionalities, refer to FREE Studio Plus - Operating Guide, page 9.

Non isolated power supply connection example using AVD1260060500:



Isolated power supply connection example using AVD1260061500:



Power Supply Restriction

If you connect the GND connection of the network across multiple devices with power supply inputs that are non-isolated (AV•84•••60500, AV•126•••0500, or EVE•••••0500), use separate, isolated power supplies. Alternatively, if you are interconnecting the equipment to a single power supply, do not connect the GND signal. Pay special attention when connecting serial lines. Miswiring may lead to inoperable equipment.

For more details, refer to Power Supply description, page 68.

RS-485 Serial Ports

Overview

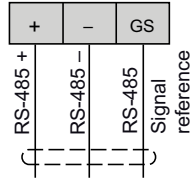
Each AV•••••6•500 / AV•••••5•500 controller is equipped with 2 RS-485 serial ports.

These ports permit user to communicate between the controller and a device via:

- A Modbus RTU connection when using **RS485-1**(slave) or **RS485-2** (master or slave) communication port
- A BACnet MS/TP (B-AAC profile certified BTL) connection

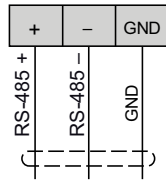
Connector of AV•••••6•500 / AV•••••5•500 Controllers

The AV•30•••••0500 / AV•62•••••0500 / AV•840005I500 / AV•126005I500 / AV•84•••••6I500 / AV•126•••••I500 controllers are equipped with 2 RS-485 terminals:



NOTE: GS of the **RS485-1** and **RS485-2** terminals are internally connected and are isolated from the GND of the device.

The AV•84•••••60500 / AV•126••~••0500 controllers are equipped with 2 RS-485 terminals:



NOTE: GND of the **RS485-1** and **RS485-2** terminals are internally connected to the GND of the device.

Cables

Use a shielded and "twisted pair" cable with two 0.5 mm² section conductors (AWG 20), plus braid (characteristic impedance 120 Ω) with PVC sleeve, nominal capacity between conductors 36 pF/m, nominal capacity between conductor and shielding 68 pF/m.

Alternatively use a shielded and "twisted pair" cable with two 0.5 mm² section conductors (AWG 20), plus braid with PVC sleeve, nominal capacity between conductors 89 pF/m, nominal capacity between conductor and shielding 161 pF/m. See EN 50174 standard on IT cabling for indications on how cables must be routed.

Always follow regulations applicable to the routing and connection of cables. Separate data transmission circuits from power lines.

RS-485 network up to 1200 m in length with a maximum of 32 devices can be connected directly to the controller. This length can be extended and the number of devices for each channel increased using appropriate repeater modules.

Single terminal strip with 3 conductors: use the 3 conductors ("+", "-" for the signal and "GND" for the braid).

Attach the 120 Ω 1/4 W resistors between the "+" and "-" terminals of the interface and the last controller in each branch of the network.

Maximum settable speed 115200 baud.

RS-485 physical layer can be used for Modbus SL, as well as for BACnet MS/TP communication. Concurrent communication of different protocols on the same serial port is not allowed.

NOTICE

INOPERABLE EQUIPMENT

Do not communicate through Modbus SL and BACnet MS/TP concurrently on the same serial port.

Failure to follow these instructions can result in equipment damage.

NOTICE

INOPERABLE EQUIPMENT

- Do not connect equipment that communicate using RS-485 serial to CAN Expansion Bus terminals.
- Do not connect equipment that communicate using CAN Expansion Bus to RS-485 terminals.

Failure to follow these instructions can result in equipment damage.

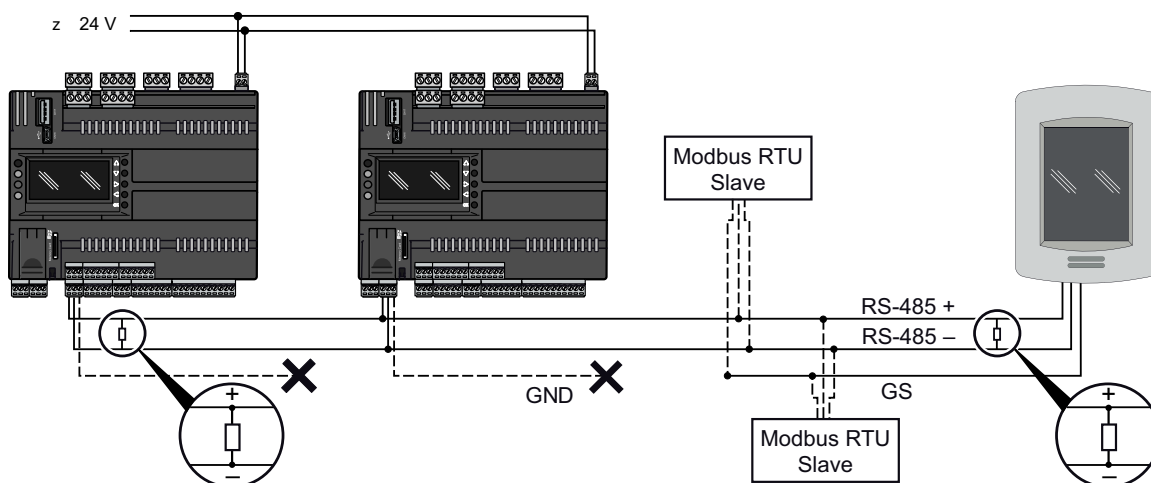
Power Supply Restriction

If you connect the GND connection of the RS-485 network across multiple devices with power supply inputs that are non-isolated (AV•84•••60500, or AV•126•••0500), use separate, isolated power supplies. Alternatively, if you are interconnecting the equipment to a single power supply, do not connect the RS-485 GND signal. Pay special attention when connecting serial lines. Miswiring may lead to inoperable equipment.

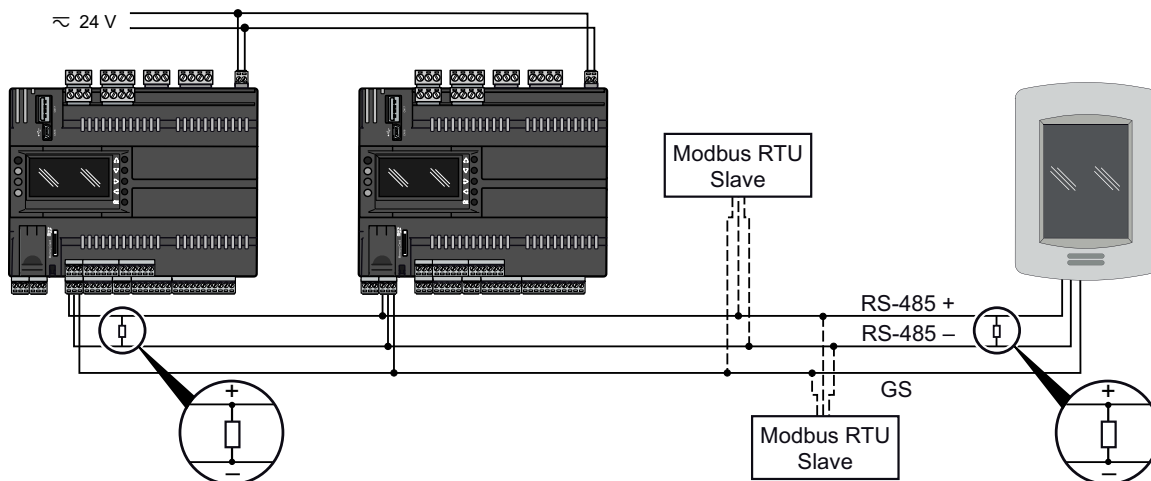
For more details, refer to Power Supply description, page 68.

Wiring Examples

The following diagram shows an RS-485 (field) architecture wiring example with non isolated controllers:



The following diagram shows an RS-485 (field) architecture wiring example with isolated controllers:



| Characteristic | Definition |
|--|---|
| Type of trunk cable | Shielded cable with one twisted pair and at least a third conductor |
| Maximum length of bus | 1000 m (3280.83 ft) at 19200 bps with a shielded and twisted cable (for example: TSXCSA***) |
| Maximum number of devices (without repeater) | 32 devices that are 31 slaves |
| Line terminators | 120 Ω 1/4 W resistors |

| Pitch of the terminal block | Cabling length |
|-----------------------------|---------------------|
| 3.50 mm (0.14 in) | 1000 m (3280.83 ft) |

USB Serial Ports

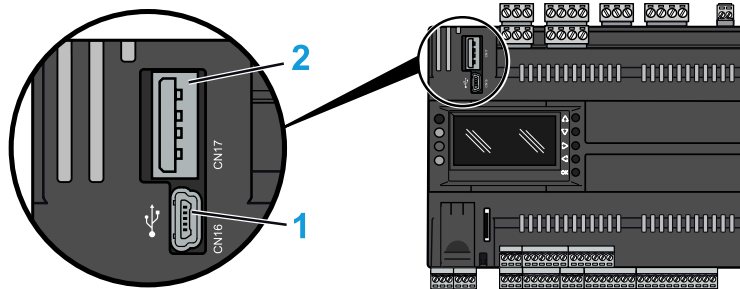
Overview

An USB type Mini-B (DEVICE) connector placed on the top-left side of the front view of the controller is used to connect the controller to a PC via Mini-B/A USB cable for debugging, commissioning, downloading, uploading with FREE Studio Plus.

For AV*****6•500, an additional USB type A (HOST) connector is used to connect a USB memory key when downloading the application.

For further information, refer to the commissioning part, page 160.

Connector of AV*****6•500 Controllers



- 1 USB type Mini-B
- 2 USB type A (AV*****6•500 only)

| Cabling length |
|-----------------|
| 30 cm (11.8 in) |

Connection

The cables required for AV*****6•500 / AV*****5•500 controllers USB Mini-B are TCSXCNAMUM3P or BMXXCAUSBH018.

The AV*****6•500 / AV*****5•500 controllers can also be supplied through the Mini-B USB cable with limited functionalities related to debugging, commissioning, downloading and uploading with FREE Studio Plus. For more information, see the FREE Studio Plus, Programming Guide.

NOTE: Do not apply voltage via 24 Vac/dc while the equipment is already connected to a PC via Mini-B USB cable.

Before applying power via 24 Vac/dc power supply connection:

| Step | Action |
|------|--|
| 1 | Disconnect the Mini-B USB cable. |
| 2 | Supply the FREE Advance controller via its 24 Vac/dc supply. |
| 3 | Reconnect the Mini-B USB cable. |

Compatibility

AV•••••6•500 / AV•••••5•500 controller is seen as a virtual COM. Serial communication is performed with a CDC profile (USB standard).

Following operating systems are compatible:

- Windows 8 / 8.1 64 bit
- Windows 10 64 bit

The driver is supplied with the FREE Studio Plus.

Ethernet Port

Overview

Each AV•••••6•500 controller is equipped by an RJ45 Ethernet port.

The RJ45 Ethernet port is available as an option for AV•••••5•500 controller, by adding a Ethernet, Modbus TCP, and BACnet/IP or a Ethernet, Modbus TCP, BACnet/IP, Modbus SL, and BACnet MS/TP communication module, page 18

Description

The Ethernet port permits user to connect the device to:

- Different controllers and/or applications exchanging variables and/or parameters (network).
- A supervision system using Modbus TCP/IP protocol.
- An IEC 61131-3 FREE Studio Plus development system.
- A BACnet/IP network, with B-AAC profile.

Concurrent communication of different protocols using the same Ethernet port is allowed (use of a web browser in addition to another Ethernet Fieldbus connection for example).

Web Functionalities

The AV•••••6•500 also features Web functionalities, offering makers of machinery and systems integrators remote access. Having a web-based connection in machines reduces support and maintenance by minimizing call-out charges. End users also benefit, as they can monitor their own systems both locally and from distance, using the graphics interface of any browser.

Main Web functionalities:

- Web-based access.
- Remote reading and support.
- Local and remote system control, including alarms management.
- Preventive and predictive maintenance.
- Email alarm alerts.

Care must be taken and provisions made for use of this product as a control device to avoid inadvertent consequences of commanded machine operation,

controller state changes, or alteration of data memory or machine operating parameters.

| |
|---|
| ⚠ WARNING |
| <p>UNINTENDED EQUIPMENT OPERATION</p> <ul style="list-style-type: none"> • Configure and install the mechanism that enables the remote HMI local to the machine so that local control over the machine can be maintained regardless of the remote commands sent to the application. • You must have a complete understanding of the application and the machine before attempting to control the application remotely. • Take the precautions necessary to assure that you are operating remotely on the intended machine by having clear, identifying documentation within the application and its remote connection. <p>Failure to follow these instructions can result in death, serious injury, or equipment damage.</p> |

Bridge

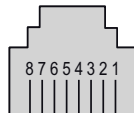
FREE Studio Plus allows monitoring of Modbus/RTU slaves, where AV.....6•500 controller is the master Modbus/RTU.

In a FREE Studio Plus project, AV.....6•500 controller is used as a Modbus TCP to Modbus/RTU protocol conversion element for Modbus 03_h and 10_h commands.

From FREE Studio Plus, set the connection with the device as Modbus TCP, inserting the AV.....6•500 controller IP address and the Modbus/RTU address of the device slave.

Connector

RJ45 Ethernet pin assignment



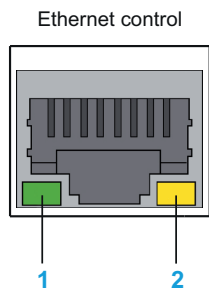
| Pin number | Signal |
|------------|--------|
| 1 | TD+ |
| 2 | TD- |
| 3 | RD+ |
| 4 | - |
| 5 | - |
| 6 | RD- |
| 7 | - |
| 8 | - |

NOTE: The controller supports the MDI/MDIX auto-crossover cable function. It is not necessary to use special Ethernet crossover cables to connect devices directly to this port (connections without an Ethernet hub or switch).

| |
|-----------------------|
| Cabling length |
| 100 m (328 ft) |

Status LED

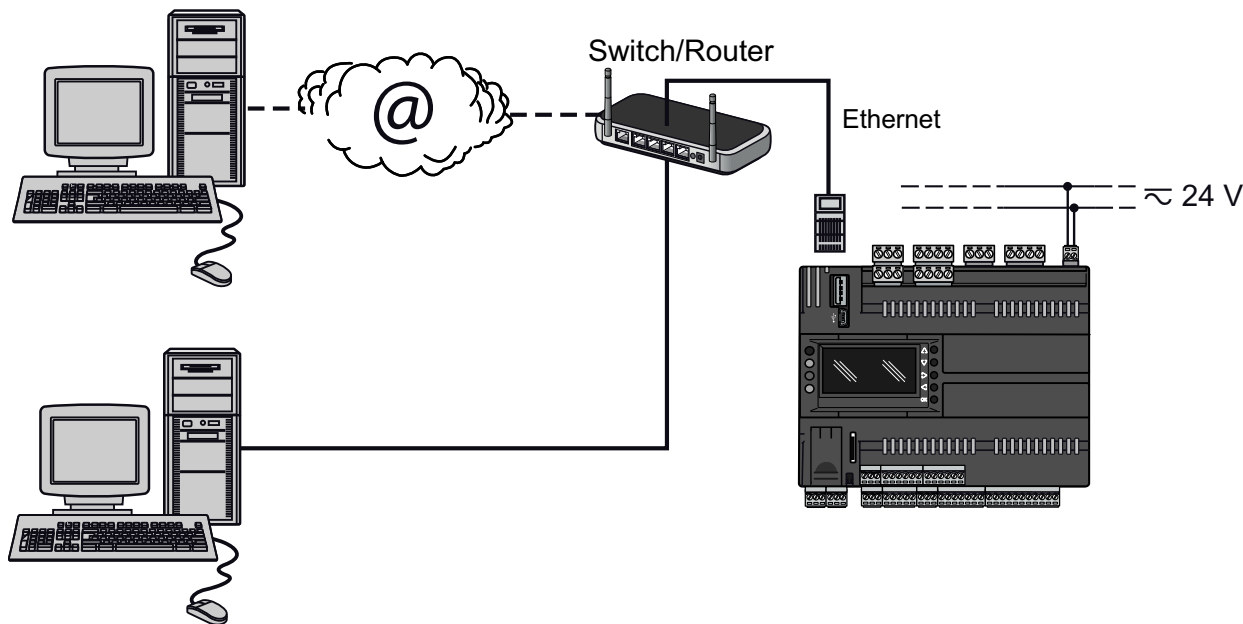
RJ45 Ethernet status LED



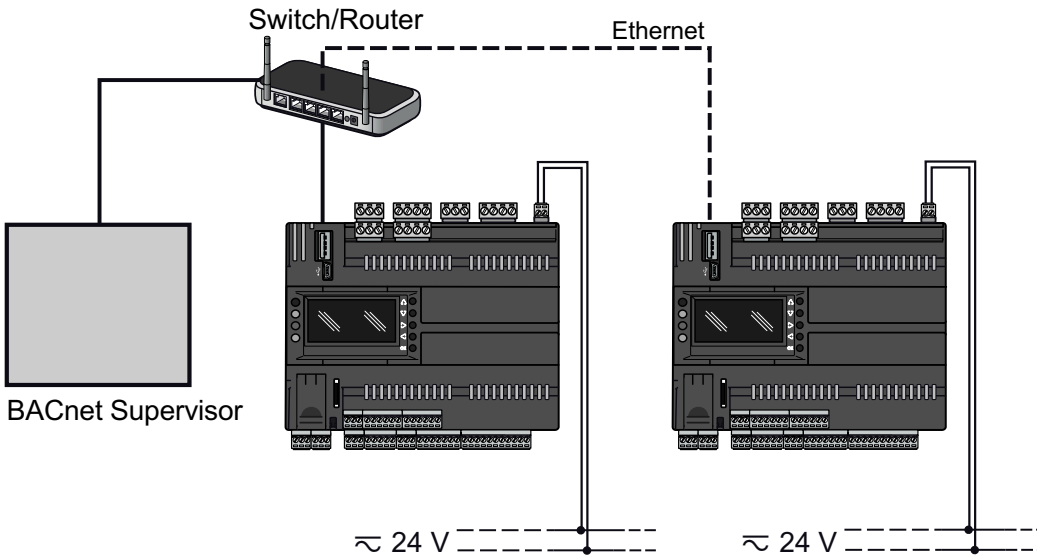
| Label | Signal | LED | | |
|-------|-------------------|--------------|-----------|----------------|
| | | Color | Status | Description |
| 1 | Ethernet link | Green/Yellow | Off | No link |
| | | | Yellow On | Link at 10 Mb |
| | | | Green On | Link at 100 Mb |
| 2 | Ethernet activity | Green | Off | No activity |
| | | | Flashing | Activity |

Architecture Wiring Examples

The following diagram shows an Ethernet architecture wiring example:



The following diagram shows a BACnet/IP architecture wiring example:



Memory

Memory

Overview

The FREE Advance Logic Controller has two different ways for data storing:

- Internal memory
- External memory (through a slot to insert external memory card, AV•••••6•500 only)

Internal Memory

The FREE Advance Logic Controller has the following memory capacities:

| Capacity | Type | Description |
|--|-----------|----------------------------|
| 512 Kb | Flash | BIOS |
| 96 Kb | RAM | BIOS and retain variables |
| 8 Mb | NOR Flash | File System and BIOS |
| AV•30•••60500 / AV•62•••60500: 16 Mb AV•84•••6•500 / AV•84•••6•500: 32 Mb | SDRAM | Application, HMI, and BIOS |

NOTE: A RAM datablock (32 bit DWORD), referred to as retain memory can be addressed through FREE Studio Plus at address `%MD102.0`, and allows data to be permanently stored, as it is with the Flash memory, as long as the RTC battery is active, page 103. There is no limitation in the amount of read and write operations on this block.

External Memory

The FREE Advance Logic Controller (AV•••••6•500) has a Memory Card slot for micro SD cards to, in certain cases, extend internal memory for the File System, page 142.

- Ultra High-Speed Class 1 (UHS-I) compatibility has been tested and validated with a 16 GB memory card.
- Ultra High-Speed Class 2 (UHS-II) memory cards are not supported.

Micro SD card slot characteristics:

| Topic | Characteristics | Description |
|---------------------|-------------------------|--------------------------|
| Supported type | Standard Capacity | Micro SD |
| | High Capacity | Micro SDHC |
| Global memory | Maximum capacity | 32 GB |
| Speed | Supported classes | 4, 6, and 10 |
| | | Ultra high-speed class 1 |
| Memory organization | Maximum size for files | 4 GB |
| | Maximum number of files | 512 |

When handling the micro SD card, follow the instructions below to help prevent internal data on the micro SD card from being corrupted or lost or a micro SD card malfunction from occurring:

NOTICE

INOPERABLE EQUIPMENT

- Do not store the micro SD card where there is static electricity or probable electromagnetic fields.
- Do not store the micro SD card in direct sunlight, near a heater, or other locations where high temperatures can occur.
- Do not bend the micro SD card.
- Do not drop or strike the micro SD card against another object.
- Keep the micro SD card dry.
- Do not touch the micro SD card connectors.
- Do not disassemble or modify the micro SD card.
- Use only micro SD card formatted using FAT32.

Failure to follow these instructions can result in equipment damage.

The AV•••••6•500 controller does not recognize NTFS formatted micro SD cards. Format the micro SD card on your computer using FAT32.

When using the AV•••••6•500 controller and a micro SD card, observe the following to avoid losing valuable data:

- Accidental data loss can occur at any time. Once data is lost, it cannot be recovered.
- If you forcibly extract the micro SD card, data on the micro SD card may become corrupted.
- Removing a micro SD card that is being accessed could damage the micro SD card, or corrupt its data.
- If the micro SD card is not positioned correctly when inserted into the controller, the data on the card and the controller could become damaged.

NOTICE**LOSS OF APPLICATION DATA**

- Backup micro SD card data regularly.
- Do not remove power or reset the controller, and do not insert or remove the micro SD card while it is being accessed.
- Become familiar with the proper orientation of the micro SD card when inserting it into the controller.

Failure to follow these instructions can result in equipment damage.

RTC (Real-Time Clock)

RTC (Real-Time Clock)

RTC Description

The table indicates the functions of the RTC:

| Function | Description |
|--|-----------------------|
| RTC data retention time in the event of a power outage | 10 years |
| Drift value | ≤ 30 s/month at 25 °C |

Battery

The FREE Advance Logic Controller has a removable flap placed in the lower-left side of the front view. Behind the service door, there is a battery compartment and a 5-pole male connector (reserved). However, to replace the internal battery, contact your local Eliwell representative.

▲ WARNING**NON USER SERVICABLE COMPONENT**

Do not attempt to replace the battery.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

User Interface

What's in This Chapter

AVD.....6•500 / AVD.....5•500 User Interface 104
 EVE.....0500 Expansion Modules User Interface 105

AVD.....6•500 / AVD.....5•500 User Interface

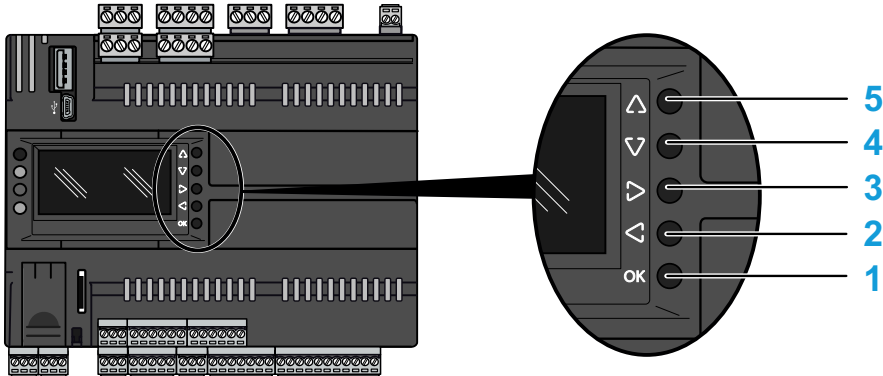
Overview

The user interface of the AVD.....6•500 / AVD.....5•500 controllers has 5 keys and 4 LEDs.

The AVC.....6•500 / AVC.....5•500 logic controllers have no display. A AVP1•0...0500 remote display can be used.

Keys

The following indications refer to the AVD.....6•500 / AVD.....5•500 user interface.

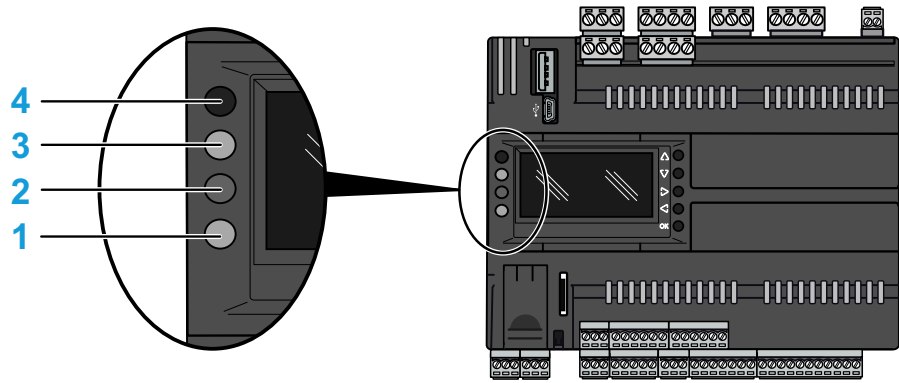


The keys can be programmed from the controller application. The following table describes the keys default setting in Edit Mode (keys are programmable from the controller application).

Description of keys actions:

| Number | Key | Press once (press and release) | Press and hold |
|--------|-------|--|---|
| 1 | OK | <ul style="list-style-type: none"> Enter/exit Edit mode Confirm operation in Edit Mode | - |
| 2 | LEFT | <ul style="list-style-type: none"> Move cursor to left in Edit Mode | <ul style="list-style-type: none"> Exit Edit Mode without saving |
| 3 | RIGHT | <ul style="list-style-type: none"> Move cursor to right in Edit Mode | - |
| 4 | DOWN | <ul style="list-style-type: none"> Decrease a value in Edit Mode | - |
| 5 | UP | <ul style="list-style-type: none"> Increase a value in Edit Mode | - |

LEDs and Display



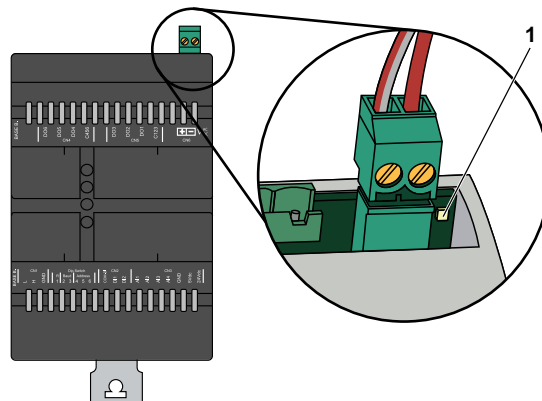
| Number | LED | Color | Function |
|--------|-----|--------|--|
| 1 | C | Green | Programmable from the controller application |
| 2 | B | Yellow | |
| 3 | A | Red | |
| 4 | P | Green | ON when the controller is powered |

NOTE: By default, A, B, C LEDs are used for USB management.

EVE•••••0500 Expansion Modules User Interface

User Interface

The EVE•••••0500 expansion modules have an advanced LED:



1: EVE•••••0500 Expansion Module status LED.

| LED State | Description |
|---------------|---|
| OFF | There is no power or the device CPU is not working |
| ON | The EVE•••••0500 Expansion Module is powered and device CPU is running. |
| Flashing | The EVE••~••0500 Expansion Module is powered and Operational. In this state, the transmission of process data via process data objects (PDOs) is possible. |
| Fast flashing | During a firmware upgrade. NOTE: At power-on/reset, the LED first flashing for a while and then stay ON. |

Remote Display

What's in This Part

| | |
|--|-----|
| Environmental Characteristics | 107 |
| Remote Display Description | 109 |
| Electrical Characteristics and Wiring Diagrams | 113 |
| Display User Interface | 118 |

Environmental Characteristics

What's in This Chapter

Environmental Characteristics 107

Environmental Characteristics

Environmental Characteristics

| Characteristics | Specification | AVP1-000W0500 | AVP100-0P0500 | AVK1000000500 |
|--|---|---------------|---------------|---------------|
| The product complies with the following harmonized regulations | EN60950-1:2006+A2:2013 EN55024:2010 EN55022:2010/AC2011 | ✓ | - | - |
| | EN60730-1 EN60730-2-9 | - | ✓ | ✓ |
| Temperature for ball pressure test | 125 °C (257 °F) | - | ✓ | - |
| Product certifications | CAN/CSA C22.2 No. 24-1993-06 UL 873:2007-11 | ✓ | - | - |
| Environmental front panel rating | Type 1 enclosure | - | ✓ | ✓ |
| Degree of protection by enclosure | IP20 | ✓ | ✓ | ✓ |
| | IP65 on front panel | - | ✓ | ✓ |
| Construction of control | Electronic automatic Incorporated Control | - | ✓ | ✓ |
| Purpose of control | Operating control (not safety) | ✓ | ✓ | ✓ |
| Mounting | Vertical surface | ✓ | ✓ | ✓ |
| | Flush | - | ✓ | ✓ |
| | Top Hat (DIN rail) | - | ✓ | - |
| Type of action | 1 | - | ✓ | ✓ |
| Pollution degree | 2 (normal) | - | ✓ | ✓ |
| Insulation material group | IIIa | - | ✓ | ✓ |
| Over-voltage category | I | - | - | ✓ |
| | II | - | ✓ | - |
| Rated impulse voltage | 330 V | - | ✓ | ✓ |
| Period of electric stress on the insulating parts | N/A | - | - | - |
| Ambient operating temperature | 0...50 °C (32...122 °F) | ✓ | - | - |
| | -20...60 °C (-4...140 °F) | - | ✓ | - |
| | -20...55 °C (-4...131 °F) | - | - | ✓ |
| Ambient operating humidity (non-condensing) | 0...75 % | ✓ | ✓ | - |
| | 5...95 % | - | - | ✓ |
| Ambient storage temperature | -30...50 °C (-22...122 °F) | ✓ | - | - |
| | -30...60 °C (-22...140 °F) | - | ✓ | - |
| | -30...70 °C (-22...158 °F) | - | - | ✓ |

| Characteristics | Specification | AVP1-000W0500 | AVP100-0P0500 | AVK1000000500 |
|--|-------------------------|---------------|---------------|---------------|
| | | | | |
| Ambient storage humidity (non-condensing) | 0...75 % | ✓ | ✓ | - |
| | 5...95 % | - | - | ✓ |
| Power supply | 24 Vac +/-15 % 50/60 Hz | ✓ | ✓ | ✓ |
| | 24 Vdc +/-10 % | | | |
| Power consumption | 3.2 VA 1.3 W max | ✓ | ✓ | - |
| | 3 VA 2 W | - | - | ✓ |
| Insulation class | III | - | ✓ | ✓ |
| Fire-resistance category | D | - | ✓ | - |
| Software class and structure | A | - | ✓ | ✓ |
| Type of disconnection or suspension for each circuit | N/A | - | - | - |

Remote Display Description

What's in This Chapter

| | |
|---------------------|-----|
| AVP1•000W0500 | 109 |
| AVP100•0P0500 | 110 |
| AVK1000000500 | 111 |

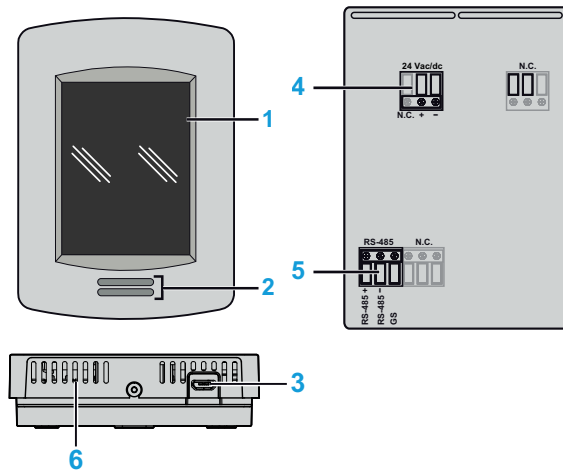
AVP1•000W0500

Overview

| Reference | Description |
|---------------|---|
| AVP11000W0500 | FREE_AVP Color Touchscreen remote display vertical mounting with built-in temperature sensor |
| AVP12000W0500 | FREE_AVP Color Touchscreen remote display vertical mounting with built-in temperature and humidity sensors |
| AVP13000W0500 | FREE_AVP Color Touchscreen remote display vertical mounting with built-in temperature, humidity, and presence (PIR) sensors |

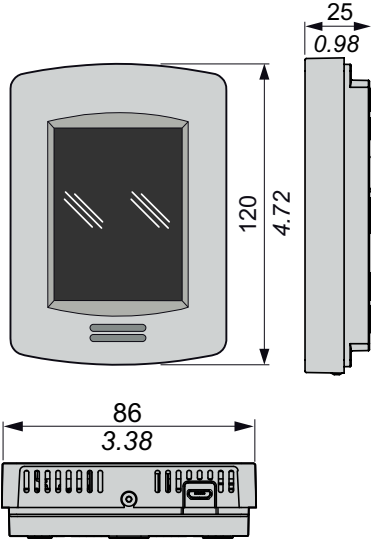
Physical Description

The following illustrations present a AVP1•000W0500 remote display:



| Number | Description |
|--------|-----------------------------------|
| 1 | Touchscreen |
| 2 | Holes for PIR detection |
| 3 | USB Micro-B port |
| 4 | Power supply connector |
| 5 | RS-485 Modbus SL connector |
| 6 | Holes for temperature measurement |

Dimensions



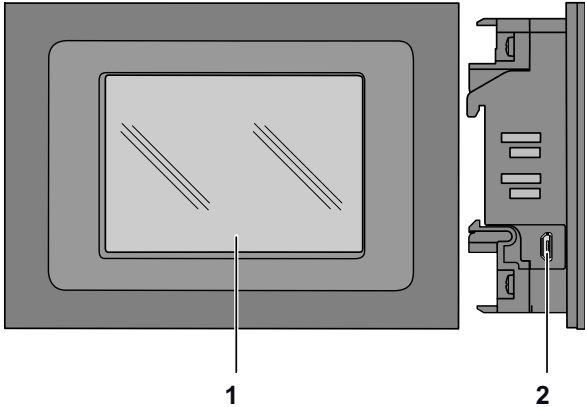
AVP100•0P0500

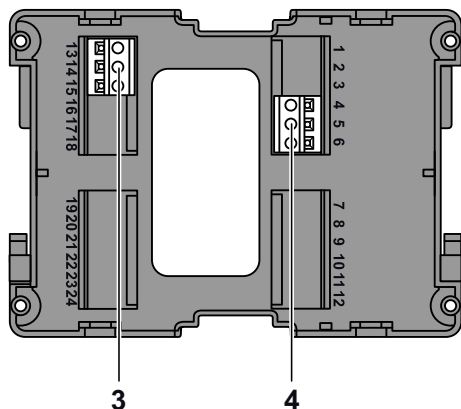
Overview

| Reference | Description |
|---------------|--|
| AVP100W0P0500 | FREE_AVP Color Touchscreen remote display flush mounting gray |
| AVP100G0P0500 | FREE_AVP Color Touchscreen remote display flush mounting white |

Physical Description

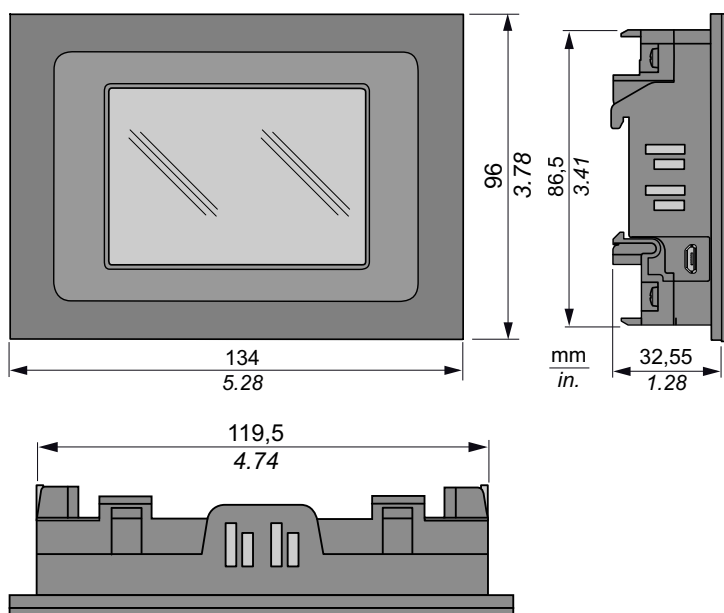
The following illustrations present a AVP100•0P0500 remote display:





| Number | Description |
|--------|----------------------------|
| 1 | Touchscreen |
| 2 | USB Micro-B port |
| 3 | RS-485 Modbus SL connector |
| 4 | Power supply connector |

Dimensions



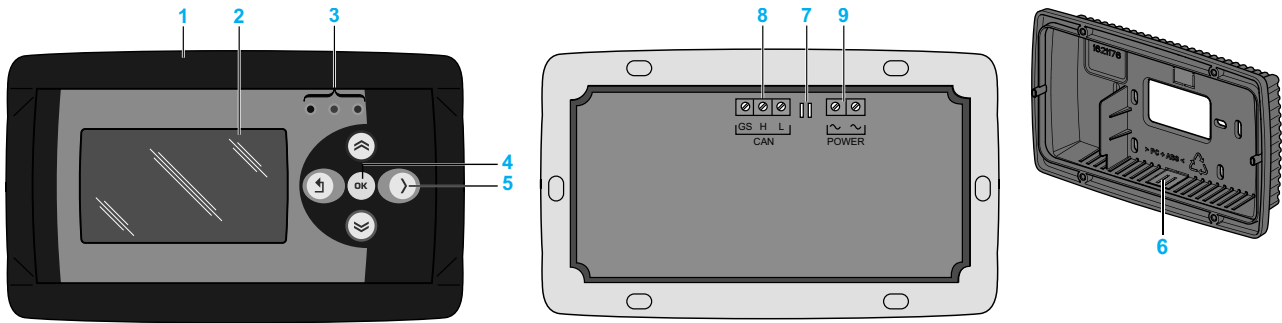
AVK1000000500

Overview

| Reference | Description |
|---------------|-------------------------------------|
| AVK1000000500 | FREE AVK monochrome display graphic |

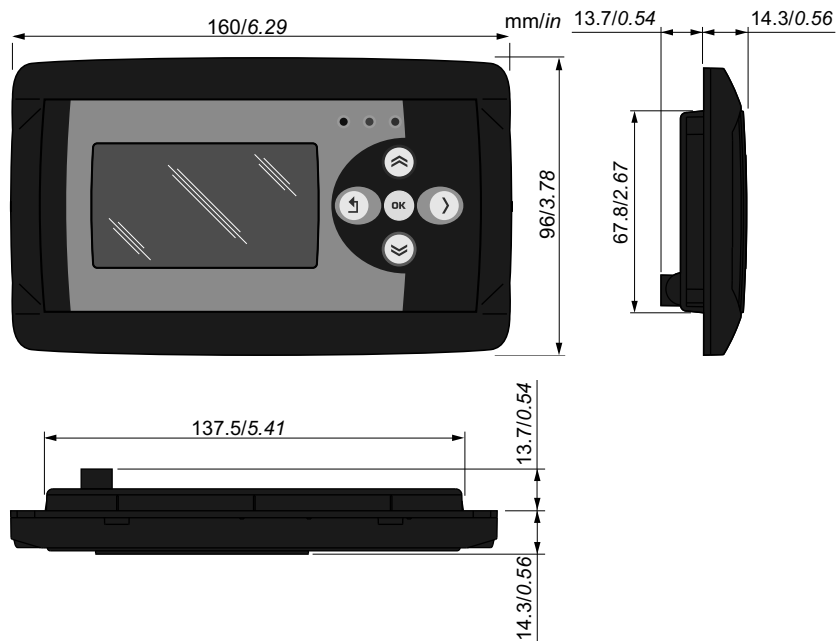
Physical Description

The following illustrations present a AVK1000000500 remote display:



| Number | Description |
|--------|--------------------------------|
| 1 | Front frame |
| 2 | Display |
| 3 | Status LEDs |
| 4 | Enter key |
| 5 | 4 navigation keys |
| 6 | Cables access of AVA00WMRC000• |
| 7 | CAN termination resistors |
| 8 | CAN Expansion bus port |
| 9 | Power supply |

Dimensions



Electrical Characteristics and Wiring Diagrams

What's in This Chapter

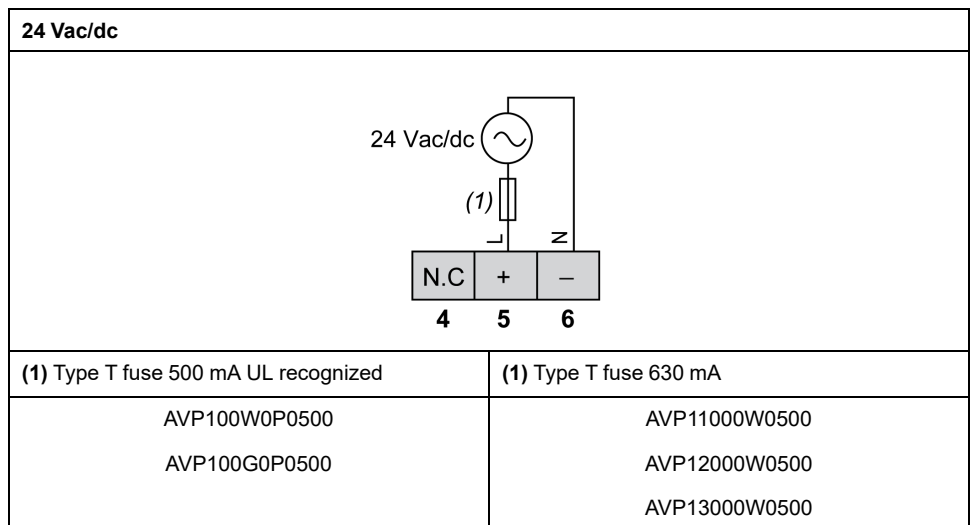
| | |
|--|-----|
| Power Supply..... | 113 |
| Embedded Sensors..... | 115 |
| AVP1•0•••0500 RS-485 Modbus Serial Port..... | 116 |
| AVK1000000500 CAN port..... | 116 |

Power Supply

AVP1•0•••0500 Power Supply

| References | Power supply characteristics |
|---------------|---|
| AVP11000W0500 | 24 Vac (+/- 15 %) non-isolated - 50/60 Hz |
| AVP12000W0500 | 24 Vdc (+/- 10 %) non-isolated |
| AVP13000W0500 | 3.2 VA / 1.3 W maximum power consumption |
| AVP100W0P0500 | |
| AVP100G0P0500 | |

Power supply wiring diagram:



| | |
|------------------------------------|-----------------------|
| Pitch of the terminal block | Cabling length |
| 5.00 mm (0.197 in.) | 10 m (32.808 ft) |

NOTICE

INOPERABLE EQUIPMENT

Do not connect a power cable longer than 10 m (32.8 ft).

Failure to follow these instructions can result in equipment damage.

For more information about the wiring, refer to Best wiring practices, page 26.

The power supplies for the AVP1•0•••0500 must be rated Safety Extra Low Voltage (SELV) according to IEC 61140. These sources of power are isolated between the electrical input and output circuits of the power supply as well as simple separation from ground (earth), PELV, and other SELV systems.

⚠ DANGER**GROUND LOOP CAUSING ELECTRIC SHOCK AND/OR INOPERABLE EQUIPMENT**

Do not connect the 0 V power supply/transformer connection supplying this equipment to any external ground (earth) connection.

Failure to follow these instructions will result in death or serious injury.

In all cases, if the specified voltage range is not maintained, the products may not function as intended. Use appropriate safety interlocks and voltage monitoring circuits.

⚠ WARNING**POTENTIAL OF OVERHEATING AND FIRE**

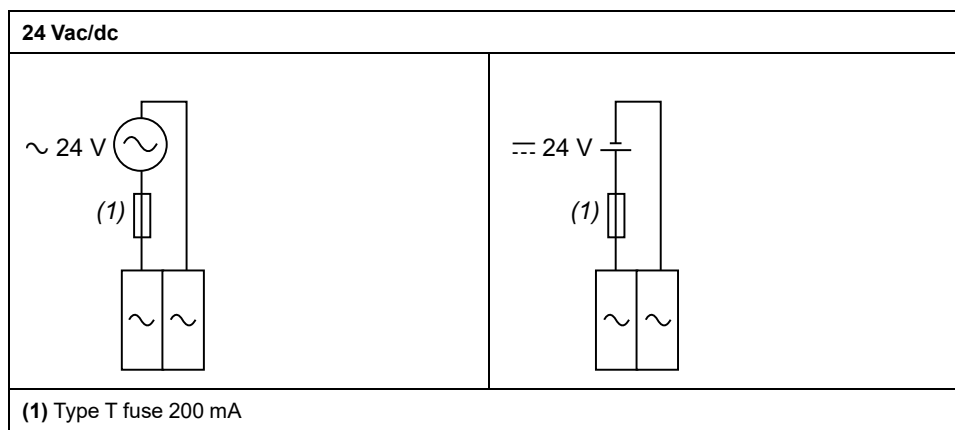
- Do not connect the equipment directly to line voltage.
- Use only isolating SELV, Class 2 power supplies / transformers to supply power to this equipment.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

AVK1000000500 Power Supply

| References | Power supply characteristics |
|---------------|---|
| AVK1000000500 | 24 Vac (+/- 15 %) - 50/60 Hz 24 Vdc (+/- 10 %) 3 VA / 2 W maximum power consumption |

Power supply wiring diagram:



| Pitch of the terminal block | Cabling length |
|-----------------------------|------------------|
| 3.81 mm (0.15 in.) | 10 m (32.808 ft) |

NOTICE**INOPERABLE EQUIPMENT**

Do not connect a power cable longer than 10 m (32.8 ft).

Failure to follow these instructions can result in equipment damage.

For more information about the wiring, refer to Best wiring practices, page 26.

⚠ DANGER

GROUND LOOP CAUSING ELECTRIC SHOCK AND/OR INOPERABLE EQUIPMENT

Do not connect the 0 V power supply/transformer connection supplying this equipment to any external ground (earth) connection.

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In all cases, if the specified voltage range is not maintained, the products may not function as intended. Use appropriate safety interlocks and voltage monitoring circuits.

⚠ WARNING

POTENTIAL OF OVERHEATING AND FIRE

- Do not connect the equipment directly to line voltage.
- Use only isolating SELV, Class 2 power supplies / transformers to supply power to this equipment.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Embedded Sensors

AVP1•000W0500 Embedded Temperature Sensor Characteristics

| Characteristic | Value |
|-------------------|--|
| Type | 10 k NTC type 2 thermistor |
| Resolution | +/- 0.1 °C (+/- 0.2 °F) |
| Measurement range | -40...+50 °C (-40...+122 °F) |
| Accuracy | +/- 0.5 °C (+/- 0.9 °F) at 21 °C (70 °F) typical calibration |

AVP12-AVP13000W0500 Embedded Humidity Sensors Characteristics

| Characteristic | Value |
|----------------------|--|
| Type and calibration | Single point calibrated bulk polymer |
| Precision | Reading range from 10...90 % R.H. non-condensing 10...20 % precision: 10 % 20...80 % precision: 5 % 80...90 % precision: 10 % |
| Stability | Less than 1.0 % yearly (typical drift) |

AVP1•0•••0500 RS-485 Modbus Serial Port

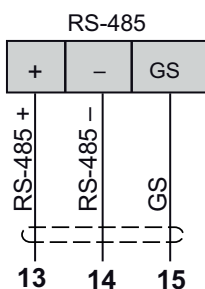
Overview

The AVP1•0•••0500 can be connected to the controller through the RS-485 Modbus.

For details, refer to RS-485 Serial port description of the controller, page 94.

Connector

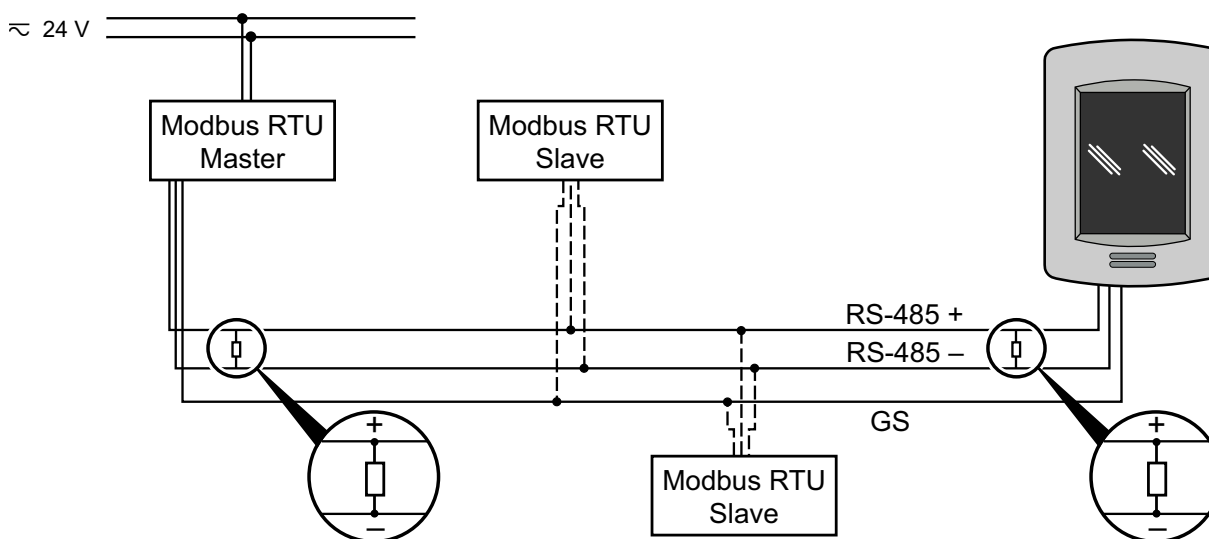
RS-485 connector (CN3):



NOTE: GS of the RS-485 terminal is not internally connected to the “-” of the power supply terminal of the device.

Architecture Wiring Examples

The following diagram shows an RS-485 (field) architecture wiring example:



AVK100000500 CAN port

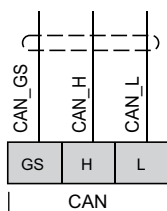
Overview

The AVK100000500 can be connected to the controller through the CAN port.

For details, refer to CAN port description of the controller, page 91.

Connector

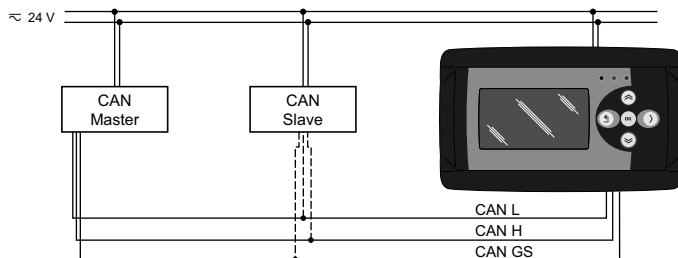
CAN connector :



NOTE: The terminals of power supply connection and the signal reference for CAN Expansion Bus (indicated as GS) are not internally connected. FUNCTIONAL isolation between them.

Architecture Wiring Examples

The following diagram shows a CAN architecture wiring example:



NOTE: Both ends of the CAN expansion bus must be terminated. In AVK100000500, this is possible via its termination jumpers.

Display User Interface

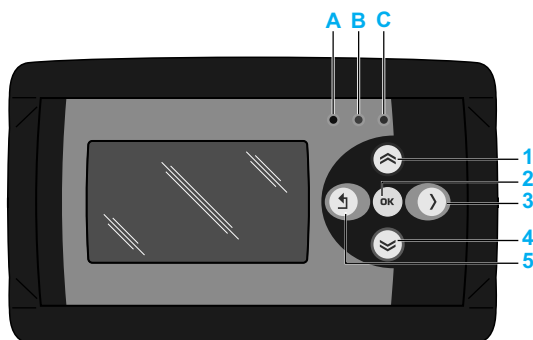
What's in This Chapter

AVK100000500 User Interface 118
 Diagnostic Menu 120
 AVK100000500 Troubleshooting 124

AVK100000500 User Interface

Overview

The user interface of the AVK100000500 remote display has 5 keys and 3 LEDs:



AVK100000500 remote display can be used with:

- AVD.....6•500 / AVD.....5•500 logic controllers that have an embedded display
- AVC.....6•500 / AVC.....5•500 logic controllers that have no embedded display

Keys

The following table describes the keys default setting in Edit Mode (keys are programmable from the controller application).

Description of keys actions:

| Number | Key | Press once (press and release) | Press and hold |
|--------|--------------|---|----------------|
| 1 | UP | <ul style="list-style-type: none"> • Scroll up • Return to previous page • Increase / modify a value in Edit Mode • Go to next label | - |
| 2 | OK | <ul style="list-style-type: none"> • Scroll down • Move to next level/menu (open folder, subfolder, parameter, value) • Enter/exit Edit mode • Confirm operation in Edit Mode | - |
| 3 | RIGHT | <ul style="list-style-type: none"> • Move cursor to right in Edit Mode | - |

| Number | Key | Press once (press and release) | Press and hold |
|--------|------------------|--|---|
| 4 | DOWN | <ul style="list-style-type: none"> • Scroll down • Move to the next page • Decrease / modify a value in Edit Mode • Go to previous label | - |
| 5 | LEFT/EXIT | <ul style="list-style-type: none"> • Exit menu page / go back to previous menu • Move cursor to left in Edit Mode | <ul style="list-style-type: none"> • Exit Edit Mode without saving |

LEDs and Display

| LED | Color | Function |
|-----|--------|--|
| C | Green | Programmable from the controller application |
| B | Yellow | |
| A | Red | |

Diagnostic Menu


AVK1000000500 is factory-configured with a default Diagnostic menu that appears when the equipment is powered on.

After uploading an HMI menu from AV•••••6•500 controller, the display consist of this menu. This HMI menu was created with the software FREE Studio Plus and stored in the filesystem of the AV•••••6•500 controller .

In this case, to open the Diagnostic menu, proceed as follows:

| Number | Key combination | Press and hold for 3 seconds |
|--------|-----------------|------------------------------|
| 4 + 5 | LEFT+DOWN | Open Diagnostic menu |

To return to the HMI menu of the controller application, open the “HMI

Management” page, move the cursor onto the  symbol and press the **OK** key.

First Power On

When the remote display is powered-on for the first time, SYSTEM INFO pages are displayed showing system status.

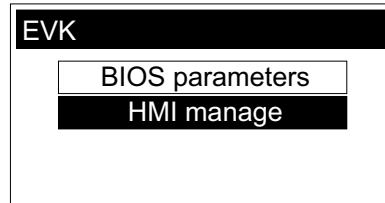
| SYSTEM INFO |
|------------------|
| HW : version 1.0 |
| BIOS : Msk476_18 |
| DATE : 04/08/17 |
| BOOT : Msk450_07 |

If present, the HMI menu from the controller application is displayed. If not present, the diagnostic menu is displayed.

Diagnostic Menu

Overview

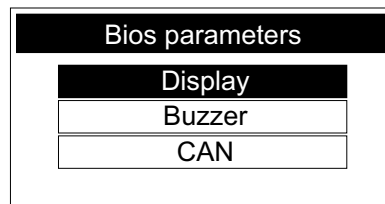
The Diagnostic menu of the AVK1000000500 remote display allows you to manage system parameters (BIOS parameters) and the interface (HMI Management).



The Diagnostic menu is composed by 2 sub-menus:

- BIOS parameters, page 120
- HMI Management, page 121

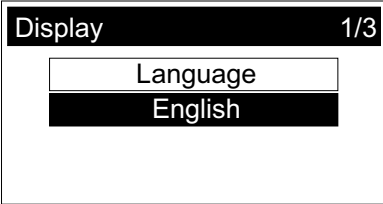
BIOS Parameters



The BIOS parameters menu permits you to:

- configure the display:
 - the language of the Diagnostic menu (Page 1/3),
 - the LCD contrast (Page 2/3),
 - the backlight time (Page 3/3)
- configure the buzzer activation on key press
- configure the CAN settings of the remote display:
 - CAN address (Page 1/2),
 - CAN baud rate (Page 2/2),

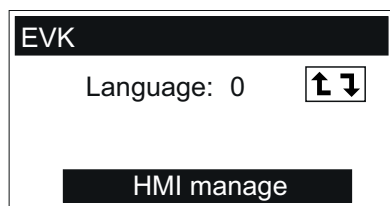
To change the language of the Diagnostic menu:

| Step | Action |
|------|--|
| 1 | From BIOS parameters page, select Display and press OK key. |
| 2 | In Display page (1/3) , press OK key:  Language is in edit mode. |
| 3 | Press UP/DOWN keys to select the new language. The Diagnostic menu can be displayed in 5 languages: Italian, English, French, German, and Spanish. |
| 4 | Press OK key to validate the new language. |
| 5 | Press EXIT key to return to BIOS parameters menu. |

See parameter HMI Management/Hmi_Language, page 158.

HMI Management


The first HMI Management page shows:



The first HMI Management page permits you to:




- Change the language of the HMI menu:

| Step | Action |
|------|--|
| 1 | Select the language number and press OK key. |
| 2 | Press UP/DOWN keys to select the new language. The Diagnostic menu can be displayed in 5 languages: 0 = Italian, 1 = English, 2 = French, 3 = German, and 4 = Spanish. |
| 3 | Press OK key to validate the new language. |


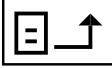

- : Relaunch the HMI menu in the new selected language, page 122.
- **HMI manage**: Go to the Advanced HMI Management page, page 121.

Advanced HMI Management

The Advanced HMI Management page shows the configuration of the remote display:

| EVK | |
|-------------------|--|
| File : HMIREM.KBD |  |
| Id : 0 | |
| Addr : 124 | HMI  |
| | BIOS  |

The Advanced HMI Management page permits you to:

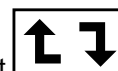
| | |
|--|---|
| File :  | Launch the HMI menu stored in the remote display, if present, page 122. |
| HMI :  | Upload HMI menu from the controller, page 123. |
| BIOS :  | Upload BIOS from the controller, page 123. |

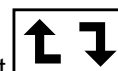
NOTE: If the symbol

 CanOpen

appears at the bottom left of the screen, refer to AVK1000000500 Troubleshooting description, page 124.

How to launch the HMI Menu



To launch the HMI menu stored in the remote display, select  and press **OK** in one of the following page:


- First HMI Management, page 121
- Advanced HMI Management, page 121

Result: The remote display shows the starting page of the HMI menu (previously uploaded).

NOTE: If the controller is not in RUN state, the variable fields only display “???”.


How to Upload HMI menu from the Controller

To upload HMI menu from the controller:

| Step | Action |
|------|--|
| 1 | From Advanced HMI Management page, select File and press OK key to toggle between: <ul style="list-style-type: none"> • HMIREM.KBD: different HMI menu in remote display and controller • HMIIEC.COD: same HMI menu in remote display and controller |
| 2 | Select HMI :  icon and press OK key. |
| 3 | <div style="border: 1px solid black; padding: 5px; width: fit-content; margin: 0 auto;"> <p>Upload Remote page</p> <p>Upload page?</p> <p>The process will not be suspended</p> <p>Cancel OK</p> </div> <p>Press UP/DOWN keys to select OK and. press OK key to validate.</p> |
| 4 | <p>Wait during the upload.</p> <div style="border: 1px solid black; padding: 5px; width: fit-content; margin: 0 auto;"> <p>Upload Remote page</p> <p>In progress...</p> <div style="border: 1px solid black; width: 100px; height: 10px; margin: 5px 0;"> <div style="background-color: black; width: 10%;"></div> </div> <p style="text-align: center;">10%</p> </div> |
| 5 | <p>If no error is detected, a confirmation message appears:</p> <div style="border: 1px solid black; padding: 5px; width: fit-content; margin: 0 auto;"> <p>Upload Remote page</p> <p>Success...</p> <p>Press OK</p> </div> <p>Press OK key to validate and return to HMI Management page.</p> |

How to Upload BIOS from the controller

To upload BIOS from the controller:

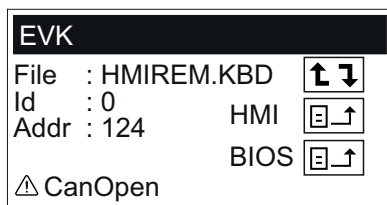
| Step | Action |
|------|---|
| 1 | From HMI Management page, select BIOS :  icon and press OK key. |
| 2 | Press UP/DOWN keys to select OK and press OK key to validate. |
| 3 | Wait during the upload. |
| 4 | <p>If no error are detected, a confirmation message appears.</p> <p>Press OK key to validate and return to HMI Management page.</p> |

AVK100000500 Troubleshooting

Troubleshooting

In the Diagnostic menu, the HMI Management page shows the configuration of the AVK100000500 remote display.

If a CAN communication error is detected, a symbol is displayed at the bottom left of the screen:



If occurs, check the communication configuration of the remote display, page 120 and the communication wiring, page 116.

Parameters

What's in This Part

| | |
|---|-----|
| Overview | 126 |
| Controller Parameter Table | 128 |
| Expansion Module Parameters Table..... | 144 |
| Display Color Touchscreen Parameters Table..... | 153 |
| AVK1000000500 Parameters Table | 157 |

Overview

Overview

Parameters are used to configure a FREE Advance Logic Controller.

They can be modified with:

- Keys on:
 - AVD•••••500 front panel
 - AVP1•0•••0500 remote displays
- PC with FREE Studio Plus
- Modbus SL communication

⚠ WARNING

UNINTENDED EQUIPMENT OPERATION

After any BIOS parameter modification, power cycle the device.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Modbus Commands and Data Areas

The following commands are implemented:

| Modbus command | Description |
|-----------------------|---|
| 3 (3 _h) | Read multiple registers on Client side |
| 6 (6 _h) | Write single register on Client side |
| 16 (10 _h) | Write multiple registers on Client side |
| 43 (2B _h) | Read Device Identification: <ul style="list-style-type: none"> • Vendor name • Product code • Major/minor revision |

Parameters Tables

The three following tables list all information required to read, write, and decode all accessible resources in the device.

- Controller Parameter table, page 128
- Expansion Module Parameters table, page 144
- Display Parameter table, page 153

Description of columns:

| Column | Description |
|-------------|--|
| LABEL | Indicates the label used to display the parameters in the device menu. |
| ADDRESS | Indicates the address of the Modbus register containing the resource to access. |
| DATA TYPE | Indicates the size of the data in bits. |
| CPL | <p>When the field indicates "-1", the value read by the register requires conversion because the value represents a number with a sign. In the other cases, the value is always positive or null.</p> <p>To carry out the conversion, proceed as follows:</p> <ul style="list-style-type: none"> • If the value in the register is from 0 to 32767, the result is the value itself (zero and positive values). • If the value in the register is from 32768 to 65535, the result is the value of the register - 65536 (negative values). |
| RESET | <p>Indicates whether the controller must be rebooted after the parameter has been modified.</p> <ul style="list-style-type: none"> • Y = the controller must be rebooted to modify the parameter. • Empty "-" = the controller does not need to be rebooted to modify the parameter. |
| DESCRIPTION | Description of the parameter usage. |
| RANGE | Describes the interval of values that can be assigned to the parameter. It can be correlated with other equipment parameters (indicated in the parameter label). |
| DEFAULT | Indicates the factory setting for the reference of the device. |
| U.M. | Indicates the unit of measurement for values converted according to the rules indicated in the CPL column. The unit of measurement shown is for example purposes only, as it may change depending on the application (for example, parameters with a U.M. in °C/bar could also have %RH.) |

Controller Parameter Table

Folders

NOTE: Not all parameters listed are available depending on the accessible resources in the device.

The following tables present the controller parameters, divided into categories (folders):

| Folder label |
|---|
| Acknowledgment, page 128 |
| AI Calibration, page 129 |
| AO Calibration, page 128 |
| Analog Inputs - Base Board, page 134 |
| Analog Inputs - Upper Board, page 136 |
| ON Board RS485-1 , page 137 |
| ON Board RS485-2 , page 138 |
| ON Board CAN Expansion bus, page 139 |
| RS-485 Passive Communication Module, page 139 |
| CAN Expansion bus Passive Communication Module , page 140 |
| RS-232 Passive Communication Module, page 140 |
| Ethernet, page 141 |
| Display, page 142 |
| BACnet, page 142 |
| FileSystem, page 142 |
| Miscellaneous, page 143 |

Acknowledgment Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------|---------|-----------|-----|-------|---|-----------|---------|------|
| <i>Par_TAB</i> | 15716 | WORD | - | Y | Map code NOTE: RW parameter | 0...65535 | 0 | Num |
| <i>Par_POLI</i> | 15717 | WORD | - | Y | Model code NOTE: RW parameter | 0...65535 | 1025 | Num |
| <i>Par_PARMOD</i> | 15719 | BOOL | - | - | Parameter modified Flag indicating change to default setting: <ul style="list-style-type: none"> 0 (false): map not modified 1 (true): at least one parameter has been modified with respect to the original configuration | 0, 1 | 0 | Num |

AI Calibration Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|----------------------|---------|-----------|-----|-------|--|-----------|---------|------|
| <i>Gain_10V_AI1</i> | 15527 | WORD | - | - | 0...10 V Calibration gain AI1 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI10</i> | 15590 | WORD | - | - | 0...10 V Calibration gain AI10 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI11</i> | 15597 | WORD | - | - | 0...10 V Calibration gain AI11 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI12</i> | 15604 | WORD | - | - | 0...10 V Calibration gain AI12 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI2</i> | 15534 | WORD | - | - | 0...10 V Calibration gain AI2 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI3</i> | 15541 | WORD | - | - | 0...10 V Calibration gain AI3 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI4</i> | 15548 | WORD | - | - | 0...10 V Calibration gain AI4 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI5</i> | 15555 | WORD | - | - | 0...10 V Calibration gain AI5 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI6</i> | 15562 | WORD | - | - | 0...10 V Calibration gain AI6 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI7</i> | 15569 | WORD | - | - | 0...10 V Calibration gain AI7 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI8</i> | 15576 | WORD | - | - | 0...10 V Calibration gain AI8 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI9</i> | 15583 | WORD | - | - | 0...10 V Calibration gain AI9 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI1</i> | 15526 | WORD | - | - | 0...5 V Calibration gain AI1 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI1</i> | 15529 | WORD | - | - | 0...5 V _{ratiometric} Calibration gain AI1 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI10</i> | 15589 | WORD | - | - | 0...5 V Calibration gain AI10 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI10</i> | 15592 | WORD | - | - | 0...5 V _{ratiometric} Calibration gain AI10 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI11</i> | 15596 | WORD | - | - | 0...5 V Calibration gain AI11 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI11</i> | 15599 | WORD | - | - | 0...5 V _{ratiometric} Calibration gain AI11 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI12</i> | 15603 | WORD | - | - | 0...5 V Calibration gain AI12 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI12</i> | 15606 | WORD | - | - | 0...5 V _{ratiometric} Calibration gain AI12 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI2</i> | 15533 | WORD | - | - | 0...5 V Calibration gain AI2 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI2</i> | 15536 | WORD | - | - | 0...5 V _{ratiometric} Calibration gain AI2 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI3</i> | 15540 | WORD | - | - | 0...5 V Calibration gain AI3 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI3</i> | 15543 | WORD | - | - | 0...5 V _{ratiometric} Calibration gain AI3 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI4</i> | 15547 | WORD | - | - | 0...5 V Calibration gain AI4 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI4</i> | 15550 | WORD | - | - | 0...5 V _{ratiometric} Calibration gain AI4 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI5</i> | 15554 | WORD | - | - | 0...5 V Calibration gain AI5 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI5</i> | 15557 | WORD | - | - | 0...5 V _{ratiometric} Calibration gain AI5 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI6</i> | 15561 | WORD | - | - | 0...5 V Calibration gain AI6 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI6</i> | 15564 | WORD | - | - | 0...5 V _{ratiometric} Calibration gain AI6 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI7</i> | 15568 | WORD | - | - | 0...5 V Calibration gain AI7 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI7</i> | 15571 | WORD | - | - | 0...5 V _{ratiometric} Calibration gain AI7 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI8</i> | 15575 | WORD | - | - | 0...5 V Calibration gain AI8 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI8</i> | 15578 | WORD | - | - | 0...5 V _{ratiometric} Calibration gain AI8 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI9</i> | 15582 | WORD | - | - | 0...5 V Calibration gain AI9 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI9</i> | 15585 | WORD | - | - | 0...5 V _{ratiometric} Calibration gain AI9 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AI1</i> | 15528 | WORD | - | - | 0/4...20 mA Calibration gain AI1 | 0...65535 | 32768 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|------------------|---------|-----------|-----|-------|-----------------------------------|-----------|---------|------|
| Gain_mA_AI10 | 15591 | WORD | - | - | 0/4...20 mA Calibration gain AI10 | 0...65535 | 32768 | Num |
| Gain_mA_AI11 | 15598 | WORD | - | - | 0/4...20 mA Calibration gain AI11 | 0...65535 | 32768 | Num |
| Gain_mA_AI12 | 15605 | WORD | - | - | 0/4...20 mA Calibration gain AI12 | 0...65535 | 32768 | Num |
| Gain_mA_AI2 | 15535 | WORD | - | - | 0/4...20 mA Calibration gain AI2 | 0...65535 | 32768 | Num |
| Gain_mA_AI3 | 15542 | WORD | - | - | 0/4...20 mA Calibration gain AI3 | 0...65535 | 32768 | Num |
| Gain_mA_AI4 | 15549 | WORD | - | - | 0/4...20 mA Calibration gain AI4 | 0...65535 | 32768 | Num |
| Gain_mA_AI5 | 15556 | WORD | - | - | 0/4...20 mA Calibration gain AI5 | 0...65535 | 32768 | Num |
| Gain_mA_AI6 | 15563 | WORD | - | - | 0/4...20 mA Calibration gain AI6 | 0...65535 | 32768 | Num |
| Gain_mA_AI7 | 15570 | WORD | - | - | 0/4...20 mA Calibration gain AI7 | 0...65535 | 32768 | Num |
| Gain_mA_AI8 | 15577 | WORD | - | - | 0/4...20 mA Calibration gain AI8 | 0...65535 | 32768 | Num |
| Gain_mA_AI9 | 15584 | WORD | - | - | 0/4...20 mA Calibration gain AI9 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI1 | 15524 | WORD | - | - | NTC Calibration gain AI1 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI10 | 15587 | WORD | - | - | NTC Calibration gain AI10 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI11 | 15594 | WORD | - | - | NTC Calibration gain AI11 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI12 | 15601 | WORD | - | - | NTC Calibration gain AI12 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI2 | 15531 | WORD | - | - | NTC Calibration gain AI2 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI3 | 15538 | WORD | - | - | NTC Calibration gain AI3 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI4 | 15545 | WORD | - | - | NTC Calibration gain AI4 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI5 | 15552 | WORD | - | - | NTC Calibration gain AI5 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI6 | 15559 | WORD | - | - | NTC Calibration gain AI6 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI7 | 15566 | WORD | - | - | NTC Calibration gain AI7 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI8 | 15573 | WORD | - | - | NTC Calibration gain AI8 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI9 | 15580 | WORD | - | - | NTC Calibration gain AI9 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI1 | 15525 | WORD | - | - | Pt1000 Calibration gain AI1 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI10 | 15588 | WORD | - | - | Pt1000 Calibration gain AI10 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI11 | 15595 | WORD | - | - | Pt1000 Calibration gain AI11 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI12 | 15602 | WORD | - | - | Pt1000 Calibration gain AI12 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI2 | 15532 | WORD | - | - | Pt1000 Calibration gain AI2 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI3 | 15539 | WORD | - | - | Pt1000 Calibration gain AI3 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI4 | 15546 | WORD | - | - | Pt1000 Calibration gain AI4 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI5 | 15553 | WORD | - | - | Pt1000 Calibration gain AI5 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI6 | 15560 | WORD | - | - | Pt1000 Calibration gain AI6 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI7 | 15567 | WORD | - | - | Pt1000 Calibration gain AI7 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI8 | 15574 | WORD | - | - | Pt1000 Calibration gain AI8 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI9 | 15581 | WORD | - | - | Pt1000 Calibration gain AI9 | 0...65535 | 32768 | Num |
| Gain_PTC_AI1 | 15530 | WORD | - | - | PTC Calibration gain AI1 | 0...65535 | 32768 | Num |
| Gain_PTC_AI10 | 15593 | WORD | - | - | PTC Calibration gain AI10 | 0...65535 | 32768 | Num |
| Gain_PTC_AI11 | 15600 | WORD | - | - | PTC Calibration gain AI11 | 0...65535 | 32768 | Num |
| Gain_PTC_AI12 | 15607 | WORD | - | - | PTC Calibration gain AI12 | 0...65535 | 32768 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|------------------------|---------|-----------|-----|-------|---|----------------|---------|------|
| <i>Gain_PTC_AI2</i> | 15537 | WORD | - | - | PTC Calibration gain AI2 | 0...65535 | 32768 | Num |
| <i>Gain_PTC_AI3</i> | 15544 | WORD | - | - | PTC Calibration gain AI3 | 0...65535 | 32768 | Num |
| <i>Gain_PTC_AI4</i> | 15551 | WORD | - | - | PTC Calibration gain AI4 | 0...65535 | 32768 | Num |
| <i>Gain_PTC_AI5</i> | 15558 | WORD | - | - | PTC Calibration gain AI5 | 0...65535 | 32768 | Num |
| <i>Gain_PTC_AI6</i> | 15565 | WORD | - | - | PTC Calibration gain AI6 | 0...65535 | 32768 | Num |
| <i>Gain_PTC_AI7</i> | 15572 | WORD | - | - | PTC Calibration gain AI7 | 0...65535 | 32768 | Num |
| <i>Gain_PTC_AI8</i> | 15579 | WORD | - | - | PTC Calibration gain AI8 | 0...65535 | 32768 | Num |
| <i>Gain_PTC_AI9</i> | 15586 | WORD | - | - | PTC Calibration gain AI9 | 0...65535 | 32768 | Num |
| <i>Offs_Ntc_AI1</i> | 15608 | WORD | -1 | - | NTC Calibration offset AI1 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI1</i> | 15609 | WORD | -1 | - | Pt1000 Calibration offset AI1 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI1</i> | 15610 | WORD | -1 | - | 0...5 V Calibration offset AI1 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI1</i> | 15611 | WORD | -1 | - | 0...10 V Calibration offset AI1 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI1</i> | 15612 | WORD | -1 | - | 0/4...20 mA Calibration offset AI1 | -32768...32767 | 0 | Num |
| <i>Offs_5Vr_AI1</i> | 15613 | WORD | -1 | - | 0...5 V _{ratiometric} Calibration offset AI1 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI1</i> | 15614 | WORD | -1 | - | PTC Calibration offset AI1 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI2</i> | 15615 | WORD | -1 | - | NTC Calibration offset AI2 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI2</i> | 15616 | WORD | -1 | - | Pt1000 Calibration offset AI2 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI2</i> | 15617 | WORD | -1 | - | 0...5 V Calibration offset AI2 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI2</i> | 15618 | WORD | -1 | - | 0...10 V Calibration offset AI2 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI2</i> | 15619 | WORD | -1 | - | 0/4...20 mA Calibration offset AI2 | -32768...32767 | 0 | Num |
| <i>Offs_5Vr_AI2</i> | 15620 | WORD | -1 | - | 0...5 V _{ratiometric} Calibration offset AI2 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI2</i> | 15621 | WORD | -1 | - | PTC Calibration offset AI2 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI3</i> | 15622 | WORD | -1 | - | NTC Calibration offset AI3 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI3</i> | 15623 | WORD | -1 | - | Pt1000 Calibration offset AI3 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI3</i> | 15624 | WORD | -1 | - | 0...5 V Calibration offset AI3 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI3</i> | 15625 | WORD | -1 | - | 0...10 V Calibration offset AI3 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI3</i> | 15626 | WORD | -1 | - | 0/4...20 mA Calibration offset AI3 | -32768...32767 | 0 | Num |
| <i>Offs_5Vr_AI3</i> | 15627 | WORD | -1 | - | 0...5 V _{ratiometric} Calibration offset AI3 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI3</i> | 15628 | WORD | -1 | - | PTC Calibration offset AI3 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI4</i> | 15629 | WORD | -1 | - | NTC Calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI4</i> | 15630 | WORD | -1 | - | Pt1000 Calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI4</i> | 15631 | WORD | -1 | - | 0...5 V Calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI4</i> | 15632 | WORD | -1 | - | 0...10 V Calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI4</i> | 15633 | WORD | -1 | - | 0/4...20 mA Calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_5Vr_AI4</i> | 15634 | WORD | -1 | - | 0...5 V _{ratiometric} Calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI4</i> | 15635 | WORD | -1 | - | PTC Calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI5</i> | 15636 | WORD | -1 | - | NTC Calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI5</i> | 15637 | WORD | -1 | - | Pt1000 Calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI5</i> | 15638 | WORD | -1 | - | 0...5 V Calibration offset AI5 | -32768...32767 | 0 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------------|---------|-----------|-----|-------|--|----------------|---------|------|
| <i>Offs_10V_AI5</i> | 15639 | WORD | -1 | - | 0...10 V Calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI5</i> | 15640 | WORD | -1 | - | 0/4...20 mA Calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_5Vr_AI5</i> | 15641 | WORD | -1 | - | 0...5 V _{ratiometric} Calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI5</i> | 15642 | WORD | -1 | - | PTC Calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI6</i> | 15643 | WORD | -1 | - | NTC Calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI6</i> | 15644 | WORD | -1 | - | Pt1000 Calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI6</i> | 15645 | WORD | -1 | - | 0...5 V Calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI6</i> | 15646 | WORD | -1 | - | 0...10 V Calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI6</i> | 15647 | WORD | -1 | - | 0/4...20 mA Calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_5Vr_AI6</i> | 15648 | WORD | -1 | - | 0...5 V _{ratiometric} Calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI6</i> | 15649 | WORD | -1 | - | PTC Calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI7</i> | 15650 | WORD | -1 | - | NTC Calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI7</i> | 15651 | WORD | -1 | - | Pt1000 Calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI7</i> | 15652 | WORD | -1 | - | 0...5 V Calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI7</i> | 15653 | WORD | -1 | - | 0...10 V Calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI7</i> | 15654 | WORD | -1 | - | 0/4...20 mA Calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_5Vr_AI7</i> | 15655 | WORD | -1 | - | 0...5 V _{ratiometric} Calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI7</i> | 15656 | WORD | -1 | - | PTC Calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI8</i> | 15657 | WORD | -1 | - | NTC Calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI8</i> | 15658 | WORD | -1 | - | Pt1000 Calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI8</i> | 15659 | WORD | -1 | - | 0...5 V Calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI8</i> | 15660 | WORD | -1 | - | 0...10 V Calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI8</i> | 15661 | WORD | -1 | - | 0/4...20 mA Calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_5Vr_AI8</i> | 15662 | WORD | -1 | - | 0...5 V _{ratiometric} Calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI8</i> | 15663 | WORD | -1 | - | PTC Calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI9</i> | 15664 | WORD | -1 | - | NTC Calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI9</i> | 15665 | WORD | -1 | - | Pt1000 Calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI9</i> | 15666 | WORD | -1 | - | 0...5 V Calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI9</i> | 15667 | WORD | -1 | - | 0...10 V Calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI9</i> | 15668 | WORD | -1 | - | 0/4...20 mA Calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_5Vr_AI9</i> | 15669 | WORD | -1 | - | 0...5 V _{ratiometric} Calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI9</i> | 15670 | WORD | -1 | - | PTC Calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI10</i> | 15671 | WORD | -1 | - | NTC Calibration offset AI10 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI10</i> | 15672 | WORD | -1 | - | Pt1000 Calibration offset AI10 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI10</i> | 15673 | WORD | -1 | - | 0...5 V Calibration offset AI10 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI10</i> | 15674 | WORD | -1 | - | 0...10 V Calibration offset AI10 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI10</i> | 15675 | WORD | -1 | - | 0/4...20 mA Calibration offset AI10 | -32768...32767 | 0 | Num |
| <i>Offs_5Vr_AI10</i> | 15676 | WORD | -1 | - | 0...5 V _{ratiometric} Calibration offset AI10 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI10</i> | 15677 | WORD | -1 | - | PTC Calibration offset AI10 | -32768...32767 | 0 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------------|---------|-----------|-----|-------|--|----------------|---------|------|
| <i>Offs_Ntc_AI11</i> | 15678 | WORD | -1 | - | NTC Calibration offset AI11 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI11</i> | 15679 | WORD | -1 | - | Pt1000 Calibration offset AI11 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI11</i> | 15680 | WORD | -1 | - | 0...5 V Calibration offset AI11 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI11</i> | 15681 | WORD | -1 | - | 0...10 V Calibration offset AI11 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI11</i> | 15682 | WORD | -1 | - | 0/4...20 mA Calibration offset AI11 | -32768...32767 | 0 | Num |
| <i>Offs_5Vr_AI11</i> | 15683 | WORD | -1 | - | 0...5 V _{ratiometric} Calibration offset AI11 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI11</i> | 15684 | WORD | -1 | - | PTC Calibration offset AI11 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI12</i> | 15685 | WORD | -1 | - | NTC Calibration offset AI12 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI12</i> | 15686 | WORD | -1 | - | Pt1000 Calibration offset AI12 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI12</i> | 15687 | WORD | -1 | - | 0...5 V Calibration offset AI12 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI12</i> | 15688 | WORD | -1 | - | 0...10 V Calibration offset AI12 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI12</i> | 15689 | WORD | -1 | - | 0/4...20 mA Calibration offset AI12 | -32768...32767 | 0 | Num |
| <i>Offs_5Vr_AI12</i> | 15690 | WORD | -1 | - | 0...5 V _{ratiometric} Calibration offset AI12 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI12</i> | 15691 | WORD | -1 | - | PTC Calibration offset AI12 | -32768...32767 | 0 | Num |

AO Calibration Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|---------------------|---------|-----------|-----|-------|------------------------------------|----------------|---------|------|
| <i>Gain_10V_AO1</i> | 15692 | WORD | - | - | 0...10 V Calibration gain AO1 | 0...65535 | 3276-8 | Num |
| <i>Gain_10V_AO2</i> | 15694 | WORD | - | - | 0...10 V Calibration gain AO2 | 0...65535 | 3276-8 | Num |
| <i>Gain_10V_AO3</i> | 15696 | WORD | - | - | 0...10 V Calibration gain AO3 | 0...65535 | 3276-8 | Num |
| <i>Gain_10V_AO4</i> | 15698 | WORD | - | - | 0...10 V Calibration gain AO4 | 0...65535 | 3276-8 | Num |
| <i>Gain_10V_AO5</i> | 15700 | WORD | - | - | 0...10 V Calibration gain AO5 | 0...65535 | 3276-8 | Num |
| <i>Gain_10V_AO6</i> | 15702 | WORD | - | - | 0...10 V Calibration gain AO6 | 0...65535 | 3276-8 | Num |
| <i>Gain_mA_AO1</i> | - | - | - | - | Not used | - | - | - |
| <i>Gain_mA_AO2</i> | - | - | - | - | Not used | - | - | - |
| <i>Gain_mA_AO3</i> | 15697 | WORD | - | - | 0/4...20 mA Calibration gain AO3 | 0...65535 | 3276-8 | Num |
| <i>Gain_mA_AO4</i> | 15699 | WORD | - | - | 0/4...20 mA Calibration gain AO4 | 0...65535 | 3276-8 | Num |
| <i>Gain_mA_AO5</i> | - | - | - | - | Not used | - | - | - |
| <i>Gain_mA_AO6</i> | - | - | - | - | Not used | - | - | - |
| <i>Offs_10V_AO1</i> | 15704 | WORD | -1 | - | 0...10 V Calibration offset AO1 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AO1</i> | 15705 | WORD | -1 | - | 0/4...20 mA Calibration offset AO1 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AO2</i> | 15706 | WORD | -1 | - | 0...10 V Calibration offset AO2 | -32768...32767 | 0 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|---------------------|---------|-----------|-----|-------|------------------------------------|----------------|---------|------|
| <i>Offs_mA_AO2</i> | 15707 | WORD | -1 | - | 0/4...20 mA Calibration offset AO2 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AO3</i> | 15708 | WORD | -1 | - | 0...10 V Calibration offset AO3 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AO3</i> | 15709 | WORD | -1 | - | 0/4...20 mA Calibration offset AO3 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AO4</i> | 15710 | WORD | -1 | - | 0...10 V Calibration offset AO4 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AO4</i> | 15711 | WORD | -1 | - | 0/4...20 mA Calibration offset AO4 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AO5</i> | 15712 | WORD | -1 | - | 0...10 V Calibration offset AO5 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AO5</i> | 15713 | WORD | -1 | - | 0/4...20mA Calibration offset AO5 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AO6</i> | 15714 | WORD | -1 | - | 0...10V Calibration offset AO6 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AO6</i> | 15715 | WORD | -1 | - | 0/4...20mA Calibration offset AO6 | -32768...32767 | 0 | Num |

Analog Inputs - Base Board Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|----------------|---------|-----------|-----|-------|--|--------|---------|------|
| <i>Temp_UM</i> | 15725 | WORD | - | - | Temperature unit of measurement <ul style="list-style-type: none"> 0 = °C 1 = °F | 0, 1 | 0 | Num |
| <i>Cfg_Ai1</i> | 15726 | UINT | - | - | Type of analog input Ai1 <ul style="list-style-type: none"> 0 = NTC (NK103) 1 = DI Input 2 = NTC (103AT) 3 = 4...20 mA 4 = 0...10 V 5 = 0...5 V (Ratiometric) 6 = Pt1000 7 = hΩ (NTC) 8 = daΩ (Pt1000) 9 = PTC 10 = 0...5 V 11 = 0...20 mA | 0...11 | 2 | Num |
| <i>Cfg_Ai2</i> | 15727 | UINT | - | - | Type of analog input Ai2 See <i>Cfg_Ai1</i> | 0...11 | 2 | Num |
| <i>Cfg_Ai3</i> | 15728 | UINT | - | - | Type of analog input Ai3 See <i>Cfg_Ai1</i> | 0...11 | 2 | Num |
| <i>Cfg_Ai4</i> | 15729 | UINT | - | - | Type of analog input Ai4 See <i>Cfg_Ai1</i> | 0...11 | 2 | Num |
| <i>Cfg_Ai5</i> | 15730 | UINT | - | - | Type of analog input Ai5 See <i>Cfg_Ai1</i> | 0...11 | 2 | Num |
| <i>Cfg_Ai6</i> | 15731 | UINT | - | - | Type of analog input Ai6 See <i>Cfg_Ai1</i> | 0...11 | 2 | Num |
| <i>Cfg_Ai7</i> | 16100 | UINT | - | - | Type of analog input Ai7 | 0...11 | 2 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------------|---------|-----------|-----|-------|--|---------------|---------|------|
| | | | | | See <i>Cfg_Ai1</i> | | | |
| <i>Cfg_Ai8</i> | 16101 | UINT | - | - | Type of analog input Ai8 See <i>Cfg_Ai1</i> | 0...11 | 2 | Num |
| <i>FullScaleMin_Ai1</i> | 15736 | WORD | -1 | - | Analog input Ai1 start of scale value NOTE: Minimum full scale: for current probes, value at 4 mA, for 0...10 V voltage probes, value at 0 V, for ratiometric probes (0...5 V), value at 10% (corresponding to 0.5 V). | -9999...+9999 | 0 | Num |
| <i>FullScaleMax_Ai1</i> | 15737 | WORD | -1 | - | Analog input Ai1 full scale value NOTE: Maximum full scale for current probes, value at 20 mA, for 0...10 V voltage probes, value at 10 V, for ratiometric probes (0...5 V), value at 90% (corresponding to 4.5 V). | -9999...+9999 | 1000 | Num |
| <i>FullScaleMin_Ai2</i> | 15738 | WORD | -1 | - | Analog input Ai2 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Num |
| <i>FullScaleMax_Ai2</i> | 15739 | WORD | -1 | - | Analog input Ai2 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Num |
| <i>FullScaleMin_Ai3</i> | 15740 | WORD | -1 | - | Analog input Ai3 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Num |
| <i>FullScaleMax_Ai3</i> | 15741 | WORD | -1 | - | Analog input Ai3 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Num |
| <i>FullScaleMin_Ai4</i> | 15742 | WORD | -1 | - | Analog input Ai4 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Num |
| <i>FullScaleMax_Ai4</i> | 15743 | WORD | -1 | - | Analog input Ai4 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Num |
| <i>FullScaleMin_Ai5</i> | 15744 | WORD | -1 | - | Analog input Ai5 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Num |
| <i>FullScaleMax_Ai5</i> | 15745 | WORD | -1 | - | Analog input Ai5 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Num |
| <i>FullScaleMin_Ai6</i> | 15746 | WORD | -1 | - | Analog input Ai6 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Num |
| <i>FullScaleMaxAi6</i> | 15747 | WORD | -1 | - | Analog input Ai6 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Num |
| <i>FullScaleMin_Ai7</i> | 16106 | WORD | -1 | - | Analog input Ai7 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Num |
| <i>FullScaleMax_Ai7</i> | 16107 | WORD | -1 | - | Analog input Ai7 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Num |
| <i>FullScaleMin_Ai8</i> | 16108 | WORD | -1 | - | Analog input Ai8 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Num |
| <i>FullScaleMaxAi8</i> | 16109 | WORD | -1 | - | Analog input Ai8 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|------------------------------|---------|-----------|-----|-------|--|--------------|---------|-------|
| <i>Calibration_Ai1</i> | 15748 | WORD | -1 | - | Analog input Ai1 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai2</i> | 15749 | WORD | -1 | - | Analog input Ai2 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai3</i> | 15750 | WORD | -1 | - | Analog input Ai3 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai4</i> | 15751 | WORD | -1 | - | Analog input Ai4 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai5</i> | 15752 | WORD | -1 | - | Analog input Ai5 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai6</i> | 15753 | WORD | -1 | - | Analog input Ai6 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai7</i> | 16118 | WORD | -1 | - | Analog input Ai7 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai8</i> | 16119 | WORD | -1 | - | Analog input Ai8 differential | -1000...1000 | 0 | Digit |
| <i>Cfg_AO3</i> | 15758 | WORD | - | - | Type of analog output AO3 <ul style="list-style-type: none"> 0 = current modulation 1 = current ON/OFF 2 = voltage modulation 3 = PWM mode | 0...3 | 0 | Num |
| <i>Cfg_AO4</i> | 15759 | WORD | - | - | Type of analog output AO4 See <i>Cfg_AO3</i> | 0...3 | 0 | Num |
| <i>PWM_frequency_AO3_AO4</i> | 15769 | WORD | - | Y | PWM Frequency for AO3 and AO4 in PWM mode | 0...2000 | 1000 | Hz |
| <i>PWM_polarity_AO3_AO4</i> | 15770 | WORD | - | - | PWM Polarity for AO3 and AO4 in PWM mode: 1 = direct, 0 = reversed | 0, 1 | 1 | Num |

Analog Inputs - Upper Board Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-----------------|---------|-----------|-----|-------|--|--------|---------|------|
| <i>Cfg_Ai9</i> | 16102 | UINT | - | - | Type of analog input Ai9 <ul style="list-style-type: none"> 0 = NTC (NK103) 1 = DI Input 2 = NTC (103AT) 3 = 4...20 mA 4 = 0...10 V 5 = 0...5 V (Ratiometric) 6 = Pt1000 7 = hΩ (NTC) 8 = daΩ (Pt1000) 9 = PTC 10 = 0...5 V 11 = 0...20 mA | 0...11 | 3 | Num |
| <i>Cfg_Ai10</i> | 16103 | UINT | - | - | Type of analog input Ai10 See <i>Cfg_Ai1</i> | 0...11 | 3 | Num |
| <i>Cfg_Ai11</i> | 16104 | UINT | - | - | Type of analog input Ai11 See <i>Cfg_Ai1</i> | 0...11 | 3 | Num |
| <i>Cfg_Ai12</i> | 16105 | UINT | - | - | Type of analog input Ai12 | 0...11 | 3 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--------------------------|---------|-----------|-----|-------|--|---------------|---------|-------|
| | | | | | See <i>Cfg_Ai1</i> | | | |
| <i>FullScaleMin_Ai9</i> | 16110 | WORD | -1 | - | Analog input Ai9 start of scale value NOTE: Minimum full scale: for current probes, value at 4 mA, for 0...10 V voltage probes, value at 0 V, for ratiometric probes (0...5 V), value at 10% (corresponding to 0.5 V). | -9999...+9999 | 0 | Num |
| <i>FullScaleMax_Ai9</i> | 16111 | WORD | -1 | - | Analog input Ai9 full scale value NOTE: Maximum full scale for current probes, value at 20 mA, for 0...10 V voltage probes, value at 10 V, for ratiometric probes (0...5 V), value at 90% (corresponding to 4.5 V). | -9999...+9999 | 1000 | Num |
| <i>FullScaleMin_Ai10</i> | 16112 | WORD | -1 | - | Analog input Ai10 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Num |
| <i>FullScaleMax_Ai10</i> | 16113 | WORD | -1 | - | Analog input Ai10 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Num |
| <i>FullScaleMin_Ai11</i> | 16114 | WORD | -1 | - | Analog input Ai11 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Num |
| <i>FullScaleMax_Ai11</i> | 16115 | WORD | -1 | - | Analog input Ai11 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Num |
| <i>FullScaleMin_Ai12</i> | 16116 | WORD | -1 | - | Analog input Ai12 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Num |
| <i>FullScaleMax_Ai12</i> | 16117 | WORD | -1 | - | Analog input Ai12 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Num |
| <i>Calibration_Ai9</i> | 16120 | WORD | -1 | - | Analog input Ai9 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai10</i> | 16121 | WORD | -1 | - | Analog input Ai10 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai11</i> | 16122 | WORD | -1 | - | Analog input Ai11 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai12</i> | 16123 | WORD | -1 | - | Analog input Ai12 differential | -1000...1000 | 0 | Digit |

ON Board RS485-1 Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--------------------------|---------|-----------|-----|-------|---|----------|---------|------|
| <i>Addr_RS485_OB1</i> | 16124 | WORD | - | Y | On-board RS-485 serial address | 0... 255 | 1 | Num |
| <i>Proto_RS485_OB1</i> | 16125 | WORD | - | Y | On-board RS-485 protocol selection <ul style="list-style-type: none"> 2 = uNET 3 = Modbus/RTU | 2, 3 | 3 | Num |
| <i>Databit_RS485_OB1</i> | 16126 | WORD | - | Y | On-board RS-485 data bit number Fixed setting 8 | 8 | 8 | Num |
| <i>Stopbit_RS485_OB1</i> | 16127 | WORD | - | Y | On-board RS-485 stop bit number | 1, 2 | 1 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------------|---------|-----------|-----|-------|--|-------|---------|------|
| | | | | | <ul style="list-style-type: none"> • 1 = 1 stop bit • 2 = 2 stop bit | | | |
| <i>Parity_RS485_OB1</i> | 16128 | WORD | - | Y | On-board RS-485 protocol parity <ul style="list-style-type: none"> • 0 = NULL • 1 = ODD • 2 = EVEN | 0...2 | 2 | Num |
| <i>Baud_RS485_OB1</i> | 16129 | WORD | - | Y | On-board RS-485 protocol baudrate <ul style="list-style-type: none"> • 0 = 9600 baud • 1 = 19200 baud • 2 = 38400 baud • 3 = 57600 baud • 4 = 76800 baud • 5 = 115200 baud | 0...5 | 2 | Num |

ON Board RS485-2 Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------------|---------|-----------|-----|-------|--|---------|---------|------|
| <i>Addr_RS485_OB</i> | 15774 | WORD | - | Y | On-board RS-485 serial address | 0...255 | 1 | Num |
| <i>Proto_RS485_OB</i> | 15775 | WORD | - | Y | On-board RS-485 protocol selection <ul style="list-style-type: none"> • 2 = uNET • 3 = Modbus/RTU | 2, 3 | 3 | Num |
| <i>Databit_RS485_OB</i> | 15776 | WORD | - | Y | On-board RS-485 data bit number Fixed setting 8 | 8 | 8 | Num |
| <i>Stopbit_RS485_OB</i> | 15777 | WORD | - | Y | On-board RS-485 stop bit number <ul style="list-style-type: none"> • 1 = 1 stop bit • 2 = 2 stop bit | 1, 2 | 1 | Num |
| <i>Parity_RS485_OB</i> | 15778 | WORD | - | Y | On-board RS-485 protocol parity <ul style="list-style-type: none"> • 0 = NULL • 1 = ODD • 2 = EVEN | 0...2 | 2 | Num |
| <i>Baud_RS485_OB</i> | 15779 | WORD | - | Y | On-board RS-485 protocol baudrate <ul style="list-style-type: none"> • 0 = 9600 baud • 1 = 19200 baud • 2 = 38400 baud • 3 = 57600 baud • 4 = 76800 baud • 5 = 115200 baud | | | |

ON Board CAN Expansion Bus Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--------------------|---------|-----------|-----|-------|---|---------|---------|------|
| <i>Addr_CAN_OB</i> | 15780 | WORD | - | Y | On-board CAN Expansion bus serial address | 1...127 | 1 | Num |
| <i>Baud_CAN_OB</i> | 15781 | WORD | - | Y | On-board CAN Expansion protocol baudrate <ul style="list-style-type: none"> • 2 = 500 kBd • 3 = 250 kBd • 4 = 125 kBd • 5 = 125 kBd • 6 = 50 kBd | 2...6 | 2 | Num |

RS-485 Passive Communication Module Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------------|---------|-----------|-----|-------|--|---------|---------|------|
| <i>Addr_RS485_PI</i> | 15782 | WORD | - | Y | RS-485 Passive Communication Module serial address | 0...255 | 1 | Num |
| <i>Proto_RS485_PI</i> | 15783 | WORD | - | Y | RS-485 Passive Communication Module protocol selection <ul style="list-style-type: none"> • 2 = uNET • 3 = Modbus/RTU | 2, 3 | 3 | Num |
| <i>Databit_RS485_PI</i> | 15784 | WORD | - | Y | RS-485 Passive Communication Module data bit number Fixed setting 8 | 8 | 8 | Num |
| <i>Stopbit_RS485_PI</i> | 15785 | WORD | - | Y | RS-485 Passive Communication Module stop bit number <ul style="list-style-type: none"> • 1 = 1 stop bit • 2 = 2 stop bit | 1, 2 | 1 | Num |
| <i>Parity_RS485_PI</i> | 15786 | WORD | - | Y | RS-485 Passive Communication Module protocol parity <ul style="list-style-type: none"> • 0 = NULL • 1 = ODD • 2 = EVEN | 0...2 | 2 | Num |
| <i>Baud_RS485_PI</i> | 15787 | WORD | - | Y | RS-485 Passive Communication Module protocol baudrate <ul style="list-style-type: none"> • 0 = 9600 baud • 1 = 19200 baud • 2 = 38400 baud • 3 = 57600 baud • 4 = 76800 baud • 5 = 115200 baud | 0...5 | 2 | Num |

CAN Expansion Bus Passive Communication Module Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--------------------|---------|-----------|-----|-------|---|---------|---------|------|
| <i>Addr_CAN_PI</i> | 15788 | WORD | - | Y | CAN Expansion bus Passive Communication Module serial address | 1...127 | 1 | Num |
| <i>Baud_CAN_PI</i> | 15789 | WORD | - | Y | CAN Expansion bus Passive Communication Module protocol baudrate <ul style="list-style-type: none"> • 2 = 500 kBd • 3 = 250 kBd • 4 = 125 kBd • 5 = 125 kBd • 6 = 50 kBd | 2...6 | 2 | Num |

RS-232 Passive Communication Module Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------------|---------|-----------|-----|-------|--|---------|---------|------|
| <i>Addr_RS232_PI</i> | 15790 | WORD | - | Y | RS-232 passive Communication Module serial address | 0...255 | 1 | Num |
| <i>Proto_RS232_PI</i> | 15791 | WORD | - | Y | RS-232 Passive Communication Module protocol selection <ul style="list-style-type: none"> • 2 = uNET • 3 = Modbus/RTU | 2...3 | 3 | Num |
| <i>Databit_RS232_PI</i> | 15792 | WORD | - | Y | RS-232 Passive Communication Module data bit number <ul style="list-style-type: none"> • 7 = 7 bit • 8 = 8 bit | 7...8 | 8 | Num |
| <i>Stopbit_RS232_PI</i> | 15793 | WORD | - | Y | RS-232 Passive Communication Module stop bit number <ul style="list-style-type: none"> • 1 = 1 stop bit • 2 = 2 stop bit | 1...2 | 1 | Num |
| <i>Parity_RS232_PI</i> | 15784 | WORD | - | Y | RS-232 Passive Communication Module protocol parity <ul style="list-style-type: none"> • 0 = NULL • 1 = ODD • 2 = EVEN | 0...2 | 2 | Num |
| <i>Baud_RS232_PI</i> | 15795 | WORD | - | Y | RS-232 Passive Communication Module protocol baudrate <ul style="list-style-type: none"> • 0 = 9600 baud • 1 = 19200 baud • 2 = 38400 baud • 3 = 57600 baud • 4 = 76800 baud • 5 = 115200 baud | 0...5 | 2 | Num |

Ethernet Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--------------------------|---------|-----------|-----|-------|---|-----------|---------|------|
| <i>Port_FTP_PI</i> | 15772 | WORD | - | Y | FTP Port number Value 0 corresponds to port 21 | 0...65535 | 65535 | Num |
| <i>Port_HTTP_PI</i> | 15796 | WORD | - | Y | HTTP port HTTP communication Port number Default 0 corresponds to port 80 | 0...65535 | 0 | Num |
| <i>Port_ETH_PI</i> | 15797 | WORD | - | Y | Port TCP/IP Modbus communication port. | 0...65535 | 65535 | Num |
| <i>Ip_1_ETH_PI</i> | 15798 | WORD | - | - | Ethernet passive Plug-in IP address (part 1) | 0...255 | 10 | Num |
| <i>Ip_2_ETH_PI</i> | 15799 | WORD | - | - | Ethernet passive Plug-in IP address (part 2) | 0...255 | 0 | Num |
| <i>Ip_3_ETH_PI</i> | 15800 | WORD | - | - | Ethernet passive Plug-in IP address (part 3) | 0...255 | 0 | Num |
| <i>Ip_4_ETH_PI</i> | 15801 | WORD | - | - | Ethernet passive Plug-in IP address (part 4) | 0...255 | 100 | Num |
| <i>DefGtwy_1_ETH_PI</i> | 15802 | WORD | - | Y | Default gateway (part 1) | 0...255 | 10 | Num |
| <i>DefGtwy_2_ETH_PI</i> | 15803 | WORD | - | Y | Default gateway (part 2) | 0...255 | 0 | Num |
| <i>DefGtwy_3_ETH_PI</i> | 15804 | WORD | - | Y | Default gateway (part 3) | 0...255 | 0 | Num |
| <i>DefGtwy_4_ETH_PI</i> | 15805 | WORD | - | Y | Default gateway (part 4) | 0...255 | 1 | Num |
| <i>NetMsk_1_ETH_PI</i> | 15806 | WORD | - | Y | Net mask (part 1) | 0...255 | 255 | Num |
| <i>NetMsk_2_ETH_PI</i> | 15807 | WORD | - | Y | Net mask (part 2) | 0...255 | 255 | Num |
| <i>NetMsk_3_ETH_PI</i> | 15808 | WORD | - | Y | Net mask (part 3) | 0...255 | 255 | Num |
| <i>NetMsk_4_ETH_PI</i> | 15809 | WORD | - | Y | Net mask (part 4) | 0...255 | 0 | Num |
| <i>PriDNS_1_ETH_PI</i> | 15810 | WORD | - | Y | Primary DNS server (part 1) | 0...255 | 8 | Num |
| <i>PriDNS_2_ETH_PI</i> | 15811 | WORD | - | Y | Primary DNS server (part 2) | 0...255 | 8 | Num |
| <i>PriDNS_3_ETH_PI</i> | 15812 | WORD | - | Y | Primary DNS server (part 3) | 0...255 | 8 | Num |
| <i>PriDNS_4_ETH_PI</i> | 15813 | WORD | - | Y | Primary DNS server (part 4) | 0...255 | 8 | Num |
| <i>SecDNS_1_ETH_PI</i> | 15814 | WORD | - | Y | Secondary DNS server (part 1) | 0...255 | 8 | Num |
| <i>SecDNS_2_ETH_PI</i> | 15815 | WORD | - | Y | Secondary DNS server (part 2) | 0...255 | 8 | Num |
| <i>SecDNS_3_ETH_PI</i> | 15816 | WORD | - | Y | Secondary DNS server (part 3) | 0...255 | 4 | Num |
| <i>SecDNS_4_ETH_PI</i> | 15817 | WORD | - | Y | Secondary DNS server (part 4) | 0...255 | 4 | Num |
| <i>EnableDHCP_ETH_PI</i> | 15818 | WORD | - | Y | Enable DHCP 0 = False, 1 = True | 0, 1 | 0 | Flag |
| <i>MAC_1_ETH_PI</i> | 16130 | WORD | - | Y | MAC address (first part) | 0 | 0 | Num |
| <i>MAC_2_ETH_PI</i> | 16131 | WORD | - | Y | MAC address (second part) | 0...24 | 24 | Num |
| <i>MAC_3_ETH_PI</i> | 16132 | WORD | - | Y | MAC address (third part) | 0...187 | 187 | Num |
| <i>MAC_4_ETH_PI</i> | 16133 | WORD | - | Y | MAC address (fourth part) | 0...255 | 255 | Num |
| <i>MAC_5_ETH_PI</i> | 16134 | WORD | - | Y | MAC address (fifth part) | 0...255 | 255 | Num |

Display Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--------------------------|---------|-----------|-----|-------|----------------|-----------|---------|------|
| <i>Hmi_Language</i> | 15819 | WORD | - | Y | Language | 0...65535 | 0 | Num |
| <i>Par_ContrLCD</i> | 15723 | WORD | - | Y | LCD contrast | 0...63 | 30 | Num |
| <i>Par_BackLightTime</i> | 15724 | WORD | - | Y | Backlight time | 0...3600 | 10 | Sec |

BACnet Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--------------------------------|---------|-----------|-----|-------|---|-----------|---------|------|
| <i>Load_BACnet_E2_Defaults</i> | 15766 | WORD | - | Y | Load default values for BACnet parameters in EEPROM at next boot | 0, 1 | 1 | Flag |
| <i>Port_BACnet_IP</i> | 15768 | WORD | - | Y | BACnet/IP Port number. 0 = port 47808 65535 = BACnet stack running only on PLC side | 0...65535 | 65535 | Num |

FileSystem Volumes

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--------------------|---------|-----------|-----|-------|---|-------|---------|------|
| <i>HTTP_volume</i> | 16136 | WORD | - | Y | Volume of HTTP files 0 = NOR Flash 1 = micro SD card | 0, 1 | 0 | Num |
| <i>DAT_volume</i> | 16137 | WORD | - | Y | Volume of *.DAT and *.RAW files 0 = NOR Flash 1 = micro SD card | 0, 1 | 0 | Num |
| <i>PLC_volume</i> | 16139 | WORD | - | Y | Volume of PLC file 0 = NOR Flash 1 = micro SD card | 0, 1 | 0 | Num |
| <i>HMI_volume</i> | 16140 | WORD | - | Y | Volume of HMI file 0 = NOR Flash 1 = micro SD card | 0, 1 | 0 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------|---------|-----------|-----|-------|---|-------|---------|------|
| <i>REM_volume</i> | 16141 | WORD | - | Y | Volume of HMI Remote file 0 = NOR Flash 1 = micro SD card | 0, 1 | 0 | Num |
| <i>PAR_volume</i> | 16142 | WORD | - | Y | Volume of CONNEC.PAR file 0 = NOR Flash 1 = micro SD card | 0, 1 | 0 | Num |

Miscellaneous

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------------|---------|-----------|-----|-------|--------------------------------------|-------|---------|------|
| <i>virtualDipSwitch</i> | 16143 | WORD | - | Y | Numeric prefix for system files name | 0...7 | 0 | Num |

Expansion Module Parameters Table

Folders

NOTE: Not all parameters listed are available depending on the accessible resources in the device.

The following tables present the Expansion module parameters, divided into categories (folders):

| Folder label |
|---|
| Acknowledgment, page 144 |
| AI Calibration, page 144 |
| AO Calibration, page 148 |
| Analog Inputs - Base Board, page 148 |
| Analog Inputs - Upper Board, page 150 |
| Analog Outputs Upper Board Folder, page 152 |
| ON Board CAN Expansion bus, page 152 |

Acknowledgment Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-----------------|---------|-----------|-----|-------|---|-----------|---------|------|
| <i>Par_TAB</i> | 15716 | WORD | - | Y | Map code NOTE: read/write parameter | 0...65535 | 0 | Num |
| <i>Par_POLI</i> | 15717 | WORD | - | Y | Model Code NOTE: read/write parameter | 0...65535 | 2049 | Num |
| <i>Par_PCH</i> | 15719 | BOOL | - | - | Device model NOTE: read/write parameter | 0...65535 | 324 | Num |

AI Calibration Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|----------------------|---------|-----------|-----|-------|--------------------------------|-----------|---------|------|
| <i>Gain_10V_AI1</i> | 15527 | WORD | - | - | 0...10 V calibration gain AI1 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI10</i> | 15590 | WORD | - | - | 0...10 V calibration gain AI10 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI2</i> | 15534 | WORD | - | - | 0...10 V calibration gain AI2 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI3</i> | 15541 | WORD | - | - | 0...10 V calibration gain AI3 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI4</i> | 15548 | WORD | - | - | 0...10 V calibration gain AI4 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI5</i> | 15555 | WORD | - | - | 0...10 V calibration gain AI5 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI6</i> | 15562 | WORD | - | - | 0...10 V calibration gain AI6 | 0...65535 | 32768 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|----------------------|---------|-----------|-----|-------|--|-----------|---------|------|
| <i>Gain_10V_AI7</i> | 15569 | WORD | - | - | 0...10 V calibration gain AI7 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI8</i> | 15576 | WORD | - | - | 0...10 V calibration gain AI8 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AI9</i> | 15583 | WORD | - | - | 0...10 V calibration gain AI9 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI1</i> | 15526 | WORD | - | - | 0...5 V _{ratiometric} calibration gain AI1 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI1</i> | 15529 | WORD | - | - | 0...5 V calibration gain AI1 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI10</i> | 15589 | WORD | - | - | 0...5 V _{ratiometric} calibration gain AI10 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI10</i> | 15592 | WORD | - | - | 0...5 V calibration gain AI10 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI2</i> | 15533 | WORD | - | - | 0...5 V _{ratiometric} calibration gain AI2 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI2</i> | 15536 | WORD | - | - | 0...5 V calibration gain AI2 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI3</i> | 15540 | WORD | - | - | 0...5 V _{ratiometric} calibration gain AI3 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI3</i> | 15543 | WORD | - | - | 0...5 V calibration gain AI3 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI4</i> | 15547 | WORD | - | - | 0...5 V _{ratiometric} calibration gain AI4 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI4</i> | 15550 | WORD | - | - | 0...5 V calibration gain AI4 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI5</i> | 15554 | WORD | - | - | 0...5 V _{ratiometric} calibration gain AI5 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI5</i> | 15557 | WORD | - | - | 0...5 V calibration gain AI5 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI6</i> | 15561 | WORD | - | - | 0...5 V _{ratiometric} calibration gain AI6 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI6</i> | 15564 | WORD | - | - | 0...5 V calibration gain AI6 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI7</i> | 15568 | WORD | - | - | 0...5 V _{ratiometric} calibration gain AI7 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI7</i> | 15571 | WORD | - | - | 0...5 V calibration gain AI7 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI8</i> | 15575 | WORD | - | - | 0...5 V _{ratiometric} calibration gain AI8 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI8</i> | 15578 | WORD | - | - | 0...5 V calibration gain AI8 | 0...65535 | 32768 | Num |
| <i>Gain_5Vr_AI9</i> | 15582 | WORD | - | - | 0...5 V _{ratiometric} calibration gain AI9 | 0...65535 | 32768 | Num |
| <i>Gain_5V_AI9</i> | 15585 | WORD | - | - | 0...5 V calibration gain AI9 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AI1</i> | 15528 | WORD | - | - | 0/4...20 mA calibration gain AI1 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AI10</i> | 15591 | WORD | - | - | 0/4...20 mA calibration gain AI10 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AI2</i> | 15535 | WORD | - | - | 0/4...20 mA calibration gain AI2 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AI3</i> | 15542 | WORD | - | - | 0/4...20 mA calibration gain AI3 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AI4</i> | 15549 | WORD | - | - | 0/4...20 mA calibration gain AI4 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AI5</i> | 15556 | WORD | - | - | 0/4...20 mA calibration gain AI5 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AI6</i> | 15563 | WORD | - | - | 0/4...20 mA calibration gain AI6 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AI7</i> | 15570 | WORD | - | - | 0/4...20 mA calibration gain AI7 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AI8</i> | 15577 | WORD | - | - | 0/4...20 mA calibration gain AI8 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AI9</i> | 15584 | WORD | - | - | 0/4...20 mA calibration gain AI9 | 0...65535 | 32768 | Num |
| <i>Gain_Ntc_AI1</i> | 15524 | WORD | - | - | NTC calibration gain AI1 | 0...65535 | 32768 | Num |
| <i>Gain_Ntc_AI10</i> | 15587 | WORD | - | - | NTC calibration gain AI10 | 0...65535 | 32768 | Num |
| <i>Gain_Ntc_AI2</i> | 15531 | WORD | - | - | NTC calibration gain AI2 | 0...65535 | 32768 | Num |
| <i>Gain_Ntc_AI3</i> | 15538 | WORD | - | - | NTC calibration gain AI3 | 0...65535 | 32768 | Num |
| <i>Gain_Ntc_AI4</i> | 15545 | WORD | - | - | NTC calibration gain AI4 | 0...65535 | 32768 | Num |
| <i>Gain_Ntc_AI5</i> | 15552 | WORD | - | - | NTC calibration gain AI5 | 0...65535 | 32768 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|------------------|---------|-----------|-----|-------|------------------------------------|----------------|---------|------|
| Gain_Ntc_AI6 | 15559 | WORD | - | - | NTC calibration gain AI6 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI7 | 15566 | WORD | - | - | NTC calibration gain AI7 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI8 | 15573 | WORD | - | - | NTC calibration gain AI8 | 0...65535 | 32768 | Num |
| Gain_Ntc_AI9 | 15580 | WORD | - | - | NTC calibration gain AI9 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI1 | 15525 | WORD | - | - | Pt1000 calibration gain AI1 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI10 | 15588 | WORD | - | - | Pt1000 calibration gain AI10 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI2 | 15532 | WORD | - | - | Pt1000 calibration gain AI2 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI3 | 15539 | WORD | - | - | Pt1000 calibration gain AI3 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI4 | 15546 | WORD | - | - | Pt1000 calibration gain AI4 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI5 | 15553 | WORD | - | - | Pt1000 calibration gain AI5 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI6 | 15560 | WORD | - | - | Pt1000 calibration gain AI6 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI7 | 15567 | WORD | - | - | Pt1000 calibration gain AI7 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI8 | 15574 | WORD | - | - | Pt1000 calibration gain AI8 | 0...65535 | 32768 | Num |
| Gain_Pt1000_AI9 | 15581 | WORD | - | - | Pt1000 calibration gain AI9 | 0...65535 | 32768 | Num |
| Gain_PTC_AI1 | 15530 | WORD | - | - | PTC calibration gain AI1 | 0...65535 | 32768 | Num |
| Gain_PTC_AI10 | 15593 | WORD | - | - | PTC calibration gain AI10 | 0...65535 | 32768 | Num |
| Gain_PTC_AI2 | 15537 | WORD | - | - | PTC calibration gain AI2 | 0...65535 | 32768 | Num |
| Gain_PTC_AI3 | 15544 | WORD | - | - | PTC calibration gain AI3 | 0...65535 | 32768 | Num |
| Gain_PTC_AI4 | 15551 | WORD | - | - | PTC calibration gain AI4 | 0...65535 | 32768 | Num |
| Gain_PTC_AI5 | 15558 | WORD | - | - | PTC calibration gain AI5 | 0...65535 | 32768 | Num |
| Gain_PTC_AI6 | 15565 | WORD | - | - | PTC calibration gain AI6 | 0...65535 | 32768 | Num |
| Gain_PTC_AI7 | 15572 | WORD | - | - | PTC calibration gain AI7 | 0...65535 | 32768 | Num |
| Gain_PTC_AI8 | 15579 | WORD | - | - | PTC calibration gain AI8 | 0...65535 | 32768 | Num |
| Gain_PTC_AI9 | 15586 | WORD | - | - | PTC calibration gain AI9 | 0...65535 | 32768 | Num |
| Offs_Ntc_AI1 | 15608 | WORD | -1 | - | NTC calibration offset AI1 | -32768...32767 | 0 | Num |
| Offs_Pt1000_AI1 | 15609 | WORD | -1 | - | Pt1000 calibration offset AI1 | -32768...32767 | 0 | Num |
| Offs_5V_AI1 | 15610 | WORD | -1 | - | 0...5 V calibration offset AI1 | -32768...32767 | 0 | Num |
| Offs_10V_AI1 | 15611 | WORD | -1 | - | 0...10 V calibration offset AI1 | -32768...32767 | 0 | Num |
| Offs_mA_AI1 | 15612 | WORD | -1 | - | 0/4...20 mA calibration offset AI1 | -32768...32767 | 0 | Num |
| Offs_5V_AI1 | 15613 | WORD | -1 | - | 0...5 V calibration offset AI1 | -32768...32767 | 0 | Num |
| Offs_PTC_AI1 | 15614 | WORD | -1 | - | PTC calibration offset AI1 | -32768...32767 | 0 | Num |
| Offs_Ntc_AI2 | 15615 | WORD | -1 | - | NTC calibration offset AI2 | -32768...32767 | 0 | Num |
| Offs_Pt1000_AI2 | 15616 | WORD | -1 | - | Pt1000 calibration offset AI2 | -32768...32767 | 0 | Num |
| Offs_5V_AI2 | 15617 | WORD | -1 | - | 0...5 V calibration offset AI2 | -32768...32767 | 0 | Num |
| Offs_10V_AI2 | 15618 | WORD | -1 | - | 0...10 V calibration offset AI2 | -32768...32767 | 0 | Num |
| Offs_mA_AI2 | 15619 | WORD | -1 | - | 0/4...20 mA calibration offset AI2 | -32768...32767 | 0 | Num |
| Offs_5V_AI2 | 15620 | WORD | -1 | - | 0...5 V calibration offset AI2 | -32768...32767 | 0 | Num |
| Offs_PTC_AI2 | 15621 | WORD | -1 | - | PTC calibration offset AI2 | -32768...32767 | 0 | Num |
| Offs_Ntc_AI3 | 15622 | WORD | -1 | - | NTC calibration offset AI3 | -32768...32767 | 0 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|------------------------|---------|-----------|-----|-------|------------------------------------|----------------|---------|------|
| <i>Offs_5V_AI3</i> | 15624 | WORD | -1 | - | 0...5 V calibration offset AI3 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI3</i> | 15625 | WORD | -1 | - | 0...10 V calibration offset AI3 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI3</i> | 15626 | WORD | -1 | - | 0/4...20 mA calibration offset AI3 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI3</i> | 15627 | WORD | -1 | - | 0...5 V calibration offset AI3 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI3</i> | 15628 | WORD | -1 | - | PTC calibration offset AI3 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI4</i> | 15629 | WORD | -1 | - | NTC calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI4</i> | 15630 | WORD | -1 | - | Pt1000 calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI4</i> | 15631 | WORD | -1 | - | 0...5 V calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI4</i> | 15632 | WORD | -1 | - | 0...10 V calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI4</i> | 15634 | WORD | -1 | - | 0...5 V calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI4</i> | 15635 | WORD | -1 | - | PTC calibration offset AI4 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI5</i> | 15636 | WORD | -1 | - | NTC calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI5</i> | 15637 | WORD | -1 | - | Pt1000 calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI5</i> | 15638 | WORD | -1 | - | 0...5 V calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI5</i> | 15639 | WORD | -1 | - | 0...10 V calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI5</i> | 15640 | WORD | -1 | - | 0/4...20 mA calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI5</i> | 15641 | WORD | -1 | - | 0...5 V calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI5</i> | 15642 | WORD | -1 | - | PTC calibration offset AI5 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI6</i> | 15643 | WORD | -1 | - | NTC calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI6</i> | 15645 | WORD | -1 | - | 0...5 V calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI6</i> | 15646 | WORD | -1 | - | 0...10 V calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI6</i> | 15647 | WORD | -1 | - | 0/4...20 mA calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI6</i> | 15648 | WORD | -1 | - | 0...5 V calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI6</i> | 15649 | WORD | -1 | - | PTC calibration offset AI6 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI7</i> | 15650 | WORD | -1 | - | NTC calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI7</i> | 15651 | WORD | -1 | - | Pt1000 calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI7</i> | 15652 | WORD | -1 | - | 0...5 V calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI7</i> | 15653 | WORD | -1 | - | 0...10 V calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI7</i> | 15654 | WORD | -1 | - | 0/4...20 mA calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI7</i> | 15655 | WORD | -1 | - | 0...5 V calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI7</i> | 15656 | WORD | -1 | - | PTC calibration offset AI7 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI8</i> | 15657 | WORD | -1 | - | NTC calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI8</i> | 15658 | WORD | -1 | - | Pt1000 calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI8</i> | 15659 | WORD | -1 | - | 0...5 V calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI8</i> | 15660 | WORD | -1 | - | 0...10 V calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI8</i> | 15661 | WORD | -1 | - | 0/4...20 mA calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI8</i> | 15662 | WORD | -1 | - | 0...5 V calibration offset AI8 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI9</i> | 15664 | WORD | -1 | - | NTC calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI9</i> | 15665 | WORD | -1 | - | Pt1000 calibration offset AI9 | -32768...32767 | 0 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------------|---------|-----------|-----|-------|-------------------------------------|----------------|---------|------|
| <i>Offs_5V_AI9</i> | 15666 | WORD | -1 | - | 0...5 V calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI9</i> | 15667 | WORD | -1 | - | 0...10 V calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI9</i> | 15668 | WORD | -1 | - | 0/4...20 mA calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI9</i> | 15669 | WORD | -1 | - | 0...5 V calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI9</i> | 15670 | WORD | -1 | - | PTC calibration offset AI9 | -32768...32767 | 0 | Num |
| <i>Offs_Ntc_AI10</i> | 15671 | WORD | -1 | - | NTC calibration offset AI10 | -32768...32767 | 0 | Num |
| <i>Offs_Pt1000_AI10</i> | 15672 | WORD | -1 | - | Pt1000 calibration offset AI10 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI10</i> | 15673 | WORD | -1 | - | 0...5 V calibration offset AI10 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AI10</i> | 15674 | WORD | -1 | - | 0...10 V calibration offset AI10 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AI10</i> | 15675 | WORD | -1 | - | 0/4...20 mA calibration offset AI10 | -32768...32767 | 0 | Num |
| <i>Offs_5V_AI10</i> | 15676 | WORD | -1 | - | 0...5 V calibration offset AI10 | -32768...32767 | 0 | Num |
| <i>Offs_PTC_AI10</i> | 15677 | WORD | -1 | - | PTC calibration offset AI10 | -32768...32767 | 0 | Num |

AO Calibration Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|---------------------|---------|-----------|-----|-------|------------------------------------|----------------|---------|------|
| <i>Gain_10V_AO1</i> | 15692 | WORD | - | - | 0...10 V calibration gain AO1 | 0...65535 | 32768 | Num |
| <i>Gain_10V_AO2</i> | 15694 | WORD | - | - | 0...10 V calibration gain AO2 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AO1</i> | 15693 | WORD | - | - | 0/4...20 mA calibration gain AO1 | 0...65535 | 32768 | Num |
| <i>Gain_mA_AO2</i> | 15695 | WORD | - | - | 0/4...20 mA calibration gain AO2 | 0...65535 | 32768 | Num |
| <i>Offs_mA_AO1</i> | 15705 | WORD | -1 | - | 0/4...20 mA calibration offset AO1 | -32768...32767 | 0 | Num |
| <i>Offs_10V_AO2</i> | 15706 | WORD | -1 | - | 0...10 V calibration offset AO2 | -32768...32767 | 0 | Num |
| <i>Offs_mA_AO2</i> | 15707 | WORD | -1 | - | 0/4...20 mA calibration offset AO2 | -32768...32767 | 0 | Num |

Analog Inputs - Base Board Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|----------------|---------|-----------|-----|-------|---|--------|---------|------|
| <i>Temp_UM</i> | 15725 | WORD | - | - | Temperature unit of measurement <ul style="list-style-type: none"> 0 = °C 1 = °F | 0, 1 | 0 | Num |
| <i>Cfg_Ai1</i> | 15726 | WORD | - | - | Type of analog input Ai1 <ul style="list-style-type: none"> 0 = NTC (NK103) 1 = DI Input 2 = NTC (103AT) | 0...11 | 2 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------------|---------|-----------|-----|-------|---|---------------|---------|-------|
| | | | | | <ul style="list-style-type: none"> 3 = 4...20 mA 4 = 0...10 V 5 = 0...5 V (Ratiometric) 6 = Pt1000 7 = hΩ (NTC) 8 = daΩ (Pt1000) 9 = PTC 10 = 0...5 V 11 = 0...20 mA | | | |
| <i>Cfg_Ai2</i> | 15727 | WORD | - | - | Type of analog input Ai2 See <i>Cfg_Ai1</i> | 0...11 | 2 | Num |
| <i>Cfg_Ai3</i> | 15728 | WORD | - | - | Type of analog input Ai3 See <i>Cfg_Ai1</i> | 0...11 | 2 | Num |
| <i>Cfg_Ai4</i> | 15729 | WORD | - | - | Type of analog input Ai4 See <i>Cfg_Ai1</i> | 0...11 | 2 | Num |
| <i>FullScaleMin_Ai1</i> | 15736 | WORD | - | - | Analog input Ai1 start of scale value NOTE: Minimum full scale: for current probes, value at 4 mA, for 0...10 V voltage probes, value at 0 V, for ratiometric probes (0...5 V), value at 10% (corresponding to 0.5 V). | -9999...+9999 | 0 | Digit |
| <i>FullScaleMax_Ai1</i> | 15737 | WORD | -1 | - | Analog input Ai1 full scale value NOTE: Maximum full scale for current probes, value at 20 mA, for 0...10 V voltage probes, value at 10 V, for ratiometric probes (0...5 V), value at 90% (corresponding to 4.5 V). | -9999...+9999 | 1000 | Digit |
| <i>FullScaleMin_Ai2</i> | 15738 | WORD | -1 | - | Analog input Ai2 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Digit |
| <i>FullScaleMax_Ai2</i> | 15739 | WORD | -1 | - | Analog input Ai2 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Digit |
| <i>FullScaleMin_Ai3</i> | 15740 | WORD | -1 | - | Analog input Ai3 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Digit |
| <i>FullScaleMax_Ai3</i> | 15741 | WORD | -1 | - | Analog input Ai3 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Digit |
| <i>FullScaleMin_Ai4</i> | 15742 | WORD | -1 | - | Analog input Ai4 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Digit |
| <i>FullScaleMax_Ai4</i> | 15743 | WORD | -1 | - | Analog input Ai4 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Digit |
| <i>Calibration_Ai1</i> | 15748 | WORD | -1 | - | Analog input Ai1 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai2</i> | 15749 | WORD | -1 | - | Analog input Ai2 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai3</i> | 15750 | WORD | -1 | - | Analog input Ai3 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_Ai4</i> | 15751 | WORD | -1 | - | Analog input Ai4 differential | -1000...1000 | 0 | Digit |
| <i>SubCfg_AI1</i> | 16010 | WORD | - | - | Sub configuration of analog input AI1 <ul style="list-style-type: none"> 0= Low Pass filter disabled, analog value in raw points; | 0...3 | 3 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------|---------|-----------|-----|-------|---|-------|---------|------|
| | | | | | <ul style="list-style-type: none"> 1= Low Pass filter disabled, analog value converted; 2= Low Pass filter enabled, analog value in raw points; 3 = Low Pass filter enabled, analog value converted. | | | |
| <i>SubCfg_AI2</i> | 16011 | WORD | - | - | Sub configuration of analog input AI2 <i>See SubCfg_AI1</i> | 0...3 | 3 | Num |
| <i>SubCfg_AI3</i> | 16012 | WORD | - | - | Sub configuration of analog input AI3 <i>See SubCfg_AI1</i> | 0...3 | 3 | Num |
| <i>SubCfg_AI4</i> | 16013 | WORD | - | - | Sub configuration of analog input AI4 <i>See SubCfg_AI1</i> | 0...3 | 3 | Num |

Analog Inputs - Upper Board Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------------|---------|-----------|-----|-------|--|---------------|---------|-------|
| <i>Cfg_AI5</i> | 15730 | WORD | - | - | Type of analog input Ai5 <i>See Cfg_AI1</i> | 0...11 | 2 | Num |
| <i>Cfg_AI6</i> | 15731 | WORD | - | - | Type of analog input Ai6 <i>See Cfg_AI1</i> | 0...11 | 2 | Num |
| <i>Cfg_AI7</i> | 16100 | WORD | - | - | Type of analog input Ai7 <i>See Cfg_AI1</i> | 0...11 | 2 | Num |
| <i>Cfg_AI8</i> | 16101 | WORD | - | - | Type of analog input Ai8 <i>See Cfg_AI1</i> | 0...11 | 2 | Num |
| <i>Cfg_AI9</i> | 16102 | WORD | - | - | Type of analog input Ai9 <i>See Cfg_AI1</i> | 0...11 | 3 | Num |
| <i>Cfg_AI10</i> | 16103 | WORD | - | - | Type of analog input Ai10 <i>See Cfg_AI1</i> | 0...11 | 3 | Num |
| <i>FullScaleMin_AI5</i> | 15744 | WORD | -1 | - | Analog input Ai5 start of scale value <i>See FullScaleMin_AI1</i> | -9999...+9999 | 0 | Digit |
| <i>FullScaleMax_AI5</i> | 15745 | WORD | -1 | - | Analog input Ai5 full scale value <i>See FullScaleMax_AI1</i> | -9999...+9999 | 1000 | Digit |
| <i>FullScaleMin_AI6</i> | 15746 | WORD | -1 | - | Analog input Ai6 start of scale value <i>See FullScaleMin_AI1</i> | -9999...+9999 | 0 | Digit |
| <i>FullScaleMaxAI6</i> | 15747 | WORD | -1 | - | Analog input Ai6 full scale value <i>See FullScaleMax_AI1</i> | -9999...+9999 | 1000 | Digit |
| <i>FullScaleMin_AI7</i> | 16106 | WORD | -1 | - | Analog input Ai7 start of scale value <i>See FullScaleMin_AI1</i> | -9999...+9999 | 0 | Digit |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--------------------------|---------|-----------|-----|-------|---|---------------|---------|-------|
| <i>FullScaleMax_Ai7</i> | 16107 | | -1 | - | Analog input Ai7 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Digit |
| <i>FullScaleMin_Ai8</i> | 16108 | | -1 | - | Analog input Ai8 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Digit |
| <i>FullScaleMaxAi8</i> | 16109 | | -1 | - | Analog input Ai8 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Digit |
| <i>FullScaleMin_Ai9</i> | 16110 | | -1 | - | Analog input Ai9 start of scale value NOTE: Minimum full scale: current probes, value at 4 mA, for 0...10 V voltage probes, value at 0 V, for ratiometric probes (0...5 V), value at 10% (corresponding to 0.5 V). | -9999...+9999 | 0 | Digit |
| <i>FullScaleMax_Ai9</i> | 16111 | | -1 | - | Analog input Ai9 full scale value NOTE: Maximum full scale current probes, value at 20 mA, for 0...10 V voltage probes, value at 10 V, for ratiometric probes (0...5 V), value at 90% (corresponding to 4.5 V). | -9999...+9999 | 1000 | Digit |
| <i>FullScaleMin_Ai10</i> | 16112 | | -1 | - | Analog input Ai10 start of scale value See <i>FullScaleMin_Ai1</i> | -9999...+9999 | 0 | Digit |
| <i>FullScaleMax_Ai10</i> | 16113 | | -1 | - | Analog input Ai10 full scale value See <i>FullScaleMax_Ai1</i> | -9999...+9999 | 1000 | Digit |
| <i>Calibration_AI5</i> | 15752 | | -1 | - | Analog input Ai5 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_AI6</i> | 15753 | | -1 | - | Analog input Ai6 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_AI7</i> | 16118 | | -1 | - | Analog input Ai7 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_AI8</i> | 16119 | | -1 | - | Analog input Ai8 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_AI9</i> | 16120 | | -1 | - | Analog input Ai9 differential | -1000...1000 | 0 | Digit |
| <i>Calibration_AI10</i> | 16121 | | -1 | - | Analog input Ai10 differential | -1000...1000 | 0 | Digit |
| <i>SubCfg_AI5</i> | 16014 | | - | - | Sub configuration of analog input AI5 See <i>SubCfg_AI1</i> | 0...3 | 3 | Num |
| <i>SubCfg_AI6</i> | 16015 | | - | - | Sub configuration of analog input AI6 See <i>SubCfg_AI1</i> | 0...3 | 3 | Num |
| <i>SubCfg_AI7</i> | 16016 | | - | - | Sub configuration of analog input AI7 See <i>SubCfg_AI1</i> | 0...3 | 3 | Num |
| <i>SubCfg_AI8</i> | 16017 | | - | - | Sub configuration of analog input AI8 See <i>SubCfg_AI1</i> | 0...3 | 3 | Num |
| <i>SubCfg_AI9</i> | 16018 | | - | - | Sub configuration of analog input AI9 See <i>SubCfg_AI1</i> | 0...3 | 3 | Num |
| <i>SubCfg_AI10</i> | 16019 | | - | - | Sub configuration of analog input AI10 See <i>SubCfg_AI1</i> | 0...3 | 3 | Num |

Analog Outputs Upper Board Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|------------------------------|---------|-----------|-----|-------|---|----------|---------|------|
| <i>Cfg_AO1</i> | 15758 | | - | - | Type of analog output AO1 <ul style="list-style-type: none"> 0= Current modulation 1 = Current ON/OFF 2 = Voltage modulation 3 = PWM mode | 0...3 | 0 | Num |
| <i>Cfg_AO2</i> | 15759 | | - | - | Type of analog output AO2 See <i>Cfg_AO1</i> | 0...3 | 0 | Num |
| <i>PWM_frequency_AO1_AO2</i> | 15769 | | - | Y | PWM Frequency for AO1 and AO2 in PWM mode | 0...2000 | 1000 | Hz |
| <i>PWM_polarity_AO1_AO2</i> | 15770 | | - | - | PWM Polarity for AO1 and AO2 in PWM mode <ul style="list-style-type: none"> 0= Reversed 1 = Direct | 0, 1 | 1 | Num |

ON Board CAN Expansion Bus Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-----------------------|---------|-----------|-----|-------|---|-----------|---------|------|
| <i>Addr_CAN_OB</i> | 15780 | | - | Y | On-board CAN Expansion Bus serial address | 1...127 | 1 | Num |
| <i>SendPeriodFDI1</i> | 17000 | | - | - | Min period of FDI1 transmission: 0 = max frequency | 0...65535 | 65535 | ms |
| <i>SendPeriodFDI2</i> | 17001 | | - | - | Min period of FDI2 transmission: 0 = max frequency | 0...65535 | 65535 | ms |

Display Color Touchscreen Parameters Table

Folders

NOTE: Not all parameters listed are available depending on the accessible resources in the device.

The following tables present the Display Color Touchscreen parameters, divided into categories (folders):

| Folder label |
|---------------------------|
| Acknowledgment, page 153 |
| AI Calibration, page 153 |
| Analog Inputs, page 154 |
| ON Board RS-485, page 154 |
| Display, page 155 |
| Remote Slave, page 154 |

Acknowledgment Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------|---------|-----------|-----|-------|---|-----------|---------|------|
| <i>Par_TAB</i> | 8192 | WORD | - | Y | Map code NOTE: read/write parameter | 0...65535 | 0 | Num |
| <i>Par_POLI</i> | 8193 | WORD | - | Y | Model Code NOTE: read/write parameter | 0...65535 | 0 | Num |
| <i>Par_PARMOD</i> | 8194 | WORD | - | - | Parameter modified <ul style="list-style-type: none"> • 0 = False • 1 = True | 0, 1 | 0 | Flag |

AI Calibration Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-----------------------|---------|-----------|-----|-------|--------------------------|-------|---------|------|
| <i>CAL_RH_interne</i> | 8195 | | - | - | Calibration value for RH | - | - | - |

Analog Inputs Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|------------------------|---------|-----------|-----|-------|---|--------------|---------|------------------|
| <i>Temp_UM</i> | 8196 | WORD | - | - | Unit of temperature measurement <ul style="list-style-type: none"> • 0 = °C • 1 = °F | 0, 1 | 0 | Num |
| <i>Calibration_NTC</i> | 8197 | WORD | - | - | NTC differential | -180...180 | 0 | °C/10 (°F/10) |
| <i>Calibration_RH</i> | 8206 | WORD | - | - | RH percentage differential | -1000...1000 | 0 | %/10 |

ON Board RS-485 Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------------|---------|-----------|-----|-------|---|---------|---------|------|
| <i>Addr_RS485_OB</i> | 8198 | WORD | - | Y | RS-485 On-board address | 0...247 | 1 | Num |
| <i>Proto_RS485_OB</i> | 8199 | WORD | - | - | Modbus working mode <ul style="list-style-type: none"> • 0 = Slave • 1 = Master | 0, 1 | (1) | Num |
| <i>DataBit_RS485_OB</i> | 8200 | WORD | - | Y | RS-485 On-board Data bit number | 8 | 8 | Num |
| <i>StopBit_RS485_OB</i> | 8201 | WORD | - | Y | RS-485 On-board stop bit number | 1, 2 | 1 | Num |
| <i>Parity_RS485_OB</i> | 8202 | WORD | - | Y | RS-485 On-board parity protocol <ul style="list-style-type: none"> • 0 = Null • 1 = Odd • 2 = Even | 0...2 | 2 | Num |
| <i>Baud_RS485_OB</i> | 8203 | WORD | - | Y | RS-485 On-board baud rate protocol <ul style="list-style-type: none"> • 0 = 9600 • 1 = 19200 • 2 = 38400 • 3 = 57600 • 4 = 115200 | 0...4 | 2 | Num |

(1) AVP1•000W0500: 0, AVP100•0P0500: 1

Remote Slave Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|---------------------------------|---------|-----------|-----|-------|----------------------------------|---------|------------------|------|
| <i>RemoteSlave1_addr</i> | 8254 | WORD | - | Y | Remote slave 1 address | 0...247 | 0 | Num |
| <i>RemoteSlave1_32bit_order</i> | 8262 | WORD | - | Y | Remote slave 1 MSB and LSB order | 0...3 | 0 ⁽¹⁾ | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--|---------|-----------|-----|-------|--|---------|------------------|------|
| | | | | | <ul style="list-style-type: none"> 0 = DWORD register not swapped and REAL register not swapped 1 = DWORD register swapped and REAL register not swapped 2 = DWORD register not swapped and REAL register swapped 3 = DWORD register swapped and REAL register swapped | | | |
| <i>RemoteSlave2_addr</i> | 8255 | WORD | - | Y | Remote slave 2 address | 0...247 | 0 | Num |
| <i>RemoteSlave2_32bit_order</i> | 8263 | WORD | - | Y | Remote slave 2 MSB and LSB order <i>See RemoteSlave1_32bit_order</i> | 0...3 | 0 ⁽¹⁾ | Num |
| <i>RemoteSlave3_addr</i> | 8256 | WORD | - | Y | Remote slave 3 address | 0...247 | 0 | Num |
| <i>RemoteSlave3_32bit_order</i> | 8264 | WORD | - | Y | Remote slave 3 MSB and LSB order <i>See RemoteSlave1_32bit_order</i> | 0...3 | 0 ⁽¹⁾ | Num |
| <i>RemoteSlave4_addr</i> | 8257 | WORD | - | Y | Remote slave 4 address | 0...247 | 0 | Num |
| <i>RemoteSlave4_32bit_order</i> | 8265 | WORD | - | Y | Remote slave 4 MSB and LSB order <i>See RemoteSlave1_32bit_order</i> | 0...3 | 0 ⁽¹⁾ | Num |
| <i>RemoteSlave5_addr</i> | 8258 | WORD | - | Y | Remote slave 5 address | 0...247 | 0 | Num |
| <i>RemoteSlave5_32bit_order</i> | 8266 | WORD | - | Y | Remote slave 5 MSB and LSB order <i>See RemoteSlave1_32bit_order</i> | 0...3 | 0 ⁽¹⁾ | Num |
| <i>RemoteSlave6_addr</i> | 8259 | WORD | - | Y | Remote slave 6 address | 0...247 | 0 | Num |
| <i>RemoteSlave6_32bit_order</i> | 8267 | WORD | - | Y | Remote slave 6 MSB and LSB order <i>See RemoteSlave1_32bit_order</i> | 0...3 | 0 ⁽¹⁾ | Num |
| <i>RemoteSlave7_addr</i> | 8260 | WORD | - | Y | Remote slave 7 address | 0...247 | 0 | Num |
| <i>RemoteSlave7_32bit_order</i> | 8268 | WORD | - | Y | Remote slave 7 MSB and LSB order <i>See RemoteSlave1_32bit_order</i> | 0...3 | 0 ⁽¹⁾ | Num |
| <i>RemoteSlave8_addr</i> | 8261 | WORD | - | Y | Remote slave 8 address | 0...247 | 0 | Num |
| <i>RemoteSlave8_32bit_order</i> | 8269 | WORD | - | Y | Remote slave 8 MSB and LSB order <i>See RemoteSlave1_32bit_order</i> | 0...3 | 0 ⁽¹⁾ | Num |
| (1) 0=Word NOT swapped, 1= Word swapped for WORD, 2= Word swapped for REAL, 3= Word swapped | | | | | | | | |

Display Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|------------------------|---------|-----------|-----|-------|---|-----------|---------|------|
| <i>Par_Orientation</i> | 8204 | WORD | - | Y | Display orientation <ul style="list-style-type: none"> 0 = Landscape 1 = Portrait | 0, 1 | 0 | - |
| <i>Par_Language</i> | 8205 | WORD | - | - | System Language | 0...65535 | 1 | Num |

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|------------------------------|---------|-----------|-----|-------|-------------------------|----------|---------|------|
| <i>Par_BackLightTime</i> | 8207 | WORD | - | - | Backlight time | 0...3600 | 10 | Sec |
| <i>Par_BackLightMinValue</i> | 8250 | WORD | - | - | Backlight minimum value | 0...100 | 5% | % |

AVK100000500 Parameters Table

Folders

The following tables present the parameters, divided into categories (folders):

| Folder label |
|--------------------------|
| Acknowledgment, page 157 |
| HMI Management, page 157 |
| Display, page 158 |
| Buzzer, page 158 |
| CAN, page 158 |

Acknowledgment Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|-------------------|---------|-----------|-----|-------|--|-----------|---------|------|
| <i>Par_TAB</i> | 15716 | WORD | - | Y | Map code NOTE: read/write parameter | 0...65535 | 0 | Num |
| <i>Par_POLI</i> | 15717 | WORD | - | Y | Model Code NOTE: read/write parameter | 0...65535 | 2049 | Num |
| <i>Par_PARMOD</i> | 15719 | BOOL | - | - | Parameter modified <ul style="list-style-type: none"> 0 = False 1 = True At least one parameter has been modified from the original configuration | 0, 1 | 0 | Flag |

HMI Management Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|---|---------|-----------|-----|-------|--|-----------|---------|--------|
| <i>Hmi_Language</i> | 15989 | WORD | - | - | - | 0...65535 | 0 | Num |
| <i>HmiList_Current</i> | 15820 | WORD | - | - | Current HMI <ul style="list-style-type: none"> 0 = HMI remote 1 | 0...11 | 0 | Num |
| <i>HmiList_ID</i> | 15821 | WORD | - | - | HMI remote navigation ID list | 0...254 | 0 | Num |
| <i>HmiList_Res</i> | 15833 | WORD | - | - | HMI remote navigation resource type <ul style="list-style-type: none"> 3 = CAN | 1...3 | 3 | Num |
| <i>HmiList_Addr</i> | 15845 | WORD | - | - | HMI remote navigation resource address for CAN | 0...255 | 124 | Num |
| <i>HmiList_File</i> | 15893 | 15 byte | - | - | HMI remote navigation file (DOS 8.3 uppercase format) | ***** | (1) | String |
| (1) Default file name: <i>HMIREM.KBD</i> | | | | | | | | |

Display Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--------------------------|---------|-----------|-----|-------|---|-----------|---------|------|
| <i>Par_Language</i> | 15819 | WORD | - | - | Display language: <ul style="list-style-type: none"> • 0 = Italian • 1 = English • 2 = French • 3 = German • 4 = Spanish | 0...65535 | 1 | Num |
| <i>Par_ContrLCD</i> | 15723 | WORD | - | Y | LCD Contrast Allows adjustment of the LCD display contrast | 0...64 | 40 | Num |
| <i>Par_BackLightTime</i> | 15724 | WORD | - | - | Backlight time Allows adjustment of LCD display switch-on time. | 0...3600 | 10 | Sec |

Buzzer Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--------------------|---------|-----------|-----|-------|--|-------|---------|------|
| <i>Buzzer_Mode</i> | 15990 | WORD | - | - | Buzzer Mode: <ul style="list-style-type: none"> • 0 = always off • 1 = beep per key • 2 = active on Red LED | 0...2 | 0 | Num |

CAN Folder

| LABEL | ADDRESS | DATA TYPE | CPL | RESET | DESCRIPTION | RANGE | DEFAULT | U.M. |
|--------------------|---------|-----------|-----|-------|--|---------|---------|------|
| <i>Addr_CAN_OB</i> | 15780 | WORD | - | Y | On-board CAN serial address. | 1...127 | 127 | Num |
| <i>Baud_CAN_OB</i> | 15781 | WORD | - | Y | On-board CAN protocol baudrate: <ul style="list-style-type: none"> • 2 = 500 kBd • 3 = 250 kBd • 4 = 125 kBd • 5 = 125 kBd • 6 = 50 kBd | 2...6 | 2 | Num |

Commissioning

What's in This Part

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|---|-----|
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FREE Studio Plus

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General Description..... 160

Overview

Components and accessories are described below.

General Description

Overview

The FREE Studio Plus development tool makes it possible to create and customize IEC 61131-3 programs for various types of application. You can download FREE Studio Plus from [Eliwell web site download center](#). It is intended for applications in HVAC&R.

FREE Studio Plus Component

FREE Studio Plus permits to:

- Create and manage libraries, applications, and diagnostics.
- Manage previously developed applications, upload/download applications, and modify device parameters from a serial port.

PC Connection

FREE Advance can be connected to a PC through the USB port and a USB cable:

- Type A USB (HOST). Used to connect a USB memory key drive when downloading the application.
- Type Mini-B USB (DEVICE). Used to connect AV•••••6•500 / AV•••••5•500 to a PC via Mini-B/A USB cable for debugging, commissioning, downloading, and uploading with FREE Studio Plus.
- Type micro-B USB (DEVICE). Used to connect AVP1•0•••0500 to a PC via micro-B/A USB cable for debugging, commissioning, downloading, and uploading with FREE Studio Plus.

The AV•••••6•500 / AV•••••5•500 can also be supplied through the USB cable with limited functionalities related to debugging, commissioning, downloading and uploading with FREE Studio Plus. For more information, refer to the FREE Studio Plus Operating Guide.

NOTE: Do not apply voltage via 24 Vac/dc while the equipment is already connected to a PC via Mini-B USB cable (AV•••••6•500 only).

Before applying power via 24 Vac/dc power supply connection:

- Disconnect the Mini-B USB cable.
- Supply the FREE Advance controller via its 24 Vac/dc power supply connector.
- Reconnect the Mini-B USB cable.

NOTE: Inactive connections are not closed automatically. If all connections are open and the cable is disconnected, a reconnect is not possible and the controller must be power cycled.

NOTICE

LOSS OF COMMUNICATION

- Close all open TCP connections between PC and the controller before disconnecting the Ethernet cable.
- Close all open TCP connections before replacing an Ethernet cable.

Failure to follow these instructions can result in equipment damage.

Controller Connection Types

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| Connection with a PC through Modbus SL/USB..... | 164 |
| Connection with a USB Memory Key..... | 165 |
| Connection with a PC through Ethernet..... | 167 |

First Commissioning

Overview

There are several processes to connect the PC to the FREE Advance controller:

| Protocol | Factory status | Connection with | Connector |
|------------|----------------|---|-------------|
| Modbus SL | Enabled | USB/RS-485 adapter TSXCUSB485 with cable VW3A83O6D3O. | CN1 / CN19 |
| USB | | Mini-B/A USB cable | CN16 / CN17 |
| HTTP | | Ethernet cable | CN20 |
| Modbus TCP | Disabled | Ethernet cable | CN20 |
| BACnet IP | | | CN20 |
| FTP | | | CN20 |

For reasons of Internet security, Modbus TCP / BACnet IP / FTP are disabled by default. Therefore you can manually enable Modbus TCP / BACnet IP / FTP.

However, doing so may expose your network to possible cyberattacks if you do not take additional measures to protect your enterprise. In addition, you may be subject to laws and regulations concerning cybersecurity.

⚠ WARNING

UNAUTHENTICATED ACCESS AND SUBSEQUENT NETWORK INTRUSION

- Observe and respect any and all pertinent national, regional and local cybersecurity and/or personal data laws and regulations when enabling Modbus TCP / BACnet IP / FTP if you wish to communicate to third party devices on an industrial network.
- Isolate your industrial network from other networks inside your company.
- Protect any network against unintended access by using firewalls, VPN, or other, proven security measures

Failure to follow these instructions can result in death, serious injury, or equipment damage.

First Connection

Once the first connection between PC and FREE Advance controller starts, FREE Studio Plus asks you to enter the default password of the web-server and to replace it by a new different one.

Lets consider that the FREE Advance controller has 3 scenarios:

| Scenario | Description | Firmware Version | |
|----------------------|--|-------------------|-------------------|
| | | AV•30***60500 | AV•84***6•500 |
| BRAND NEW | Represents a controller just manufactured with default password of the web-server. | 668.10 or greater | 596.10 or greater |
| NOT BRAND NEW | Represents a controller already accessed by a user and which default password of the web-server has changed. | | |
| OBSOLETE | Represents a controller already available on the market without default password settings/ restrictions | Lower than 668.10 | Lower than 596.10 |

CyberSecurity Defense-in-Depth

Schneider Electric and Eliwell adhere to industry best practices in the development and implementation of control systems. This includes a "Defense-in-Depth" approach to secure an Industrial Control System. This approach places the controllers behind one or more firewalls to restrict access to authorized personnel and protocols only.

| |
|--|
| ▲ WARNING |
| <p>UNAUTHENTICATED ACCESS AND SUBSEQUENT UNAUTHORIZED MACHINE OPERATION</p> <ul style="list-style-type: none"> • Evaluate whether your environment or your machines are connected to your critical infrastructure and, if so, take appropriate steps in terms of prevention, based on Defense-in-Depth, before connecting the automation system to any network. • Limit the number of devices connected to a network to the minimum necessary. • Isolate your industrial network from other networks inside your company. • Protect any network against unintended access by using firewalls, VPN, or other, proven security measures. • Monitor activities within your systems. • Prevent subject devices from direct access or direct link by unauthorized parties or unauthenticated actions. • Prepare a recovery plan including backup of your system and process information. <p>Failure to follow these instructions can result in death, serious injury, or equipment damage.</p> |

Replace the Default Password

Change the default password upon first use. In addition, consider carefully the implications for giving any access to other people.

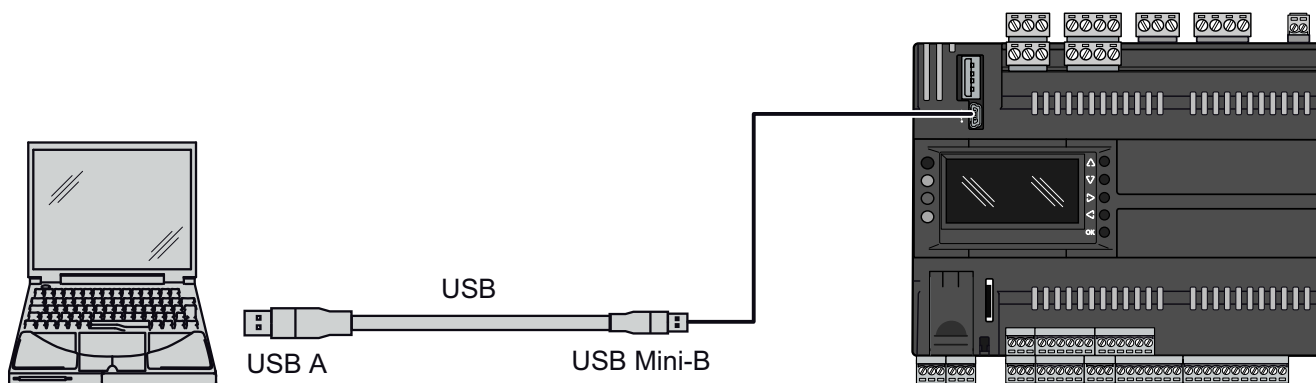
| |
|---|
| ⚠ WARNING |
| <p>UNAUTHORIZED DATA ACCESS</p> <ul style="list-style-type: none"> Immediately change any and all default passwords to new, secure passwords. Do not distribute passwords to unauthorized or otherwise unqualified personnel. <p>Failure to follow these instructions can result in death, serious injury, or equipment damage.</p> |

NOTE: A secure password is one that has not been shared or distributed to any unauthorized personnel and does not contain any personal or otherwise obvious information. Further, a mix of upper and lower case letters and numbers offer greater security. You should choose a password length of at least seven characters.

Connection with a PC through Modbus SL/USB

Connecting the PC to the Controller

Direct connection between the PC and the controller:



To connect the PC to the controller, use a type A / type Mini-B USB cable.

Following operations are possible between the PC and the controller in direct USB connection:

| Data type | PC → Controller | Controller → PC |
|------------------------|-----------------|-----------------|
| Parameters | ✓ | ✓ |
| Controller application | ✓ | ✓ |
| HMI application | ✓ | ✓ |
| Data file | ✓ | ✓ |
| BIOS | ✓ | - |

First Commissioning

FREE Advance first connection via Modbus Serial Line (USB device / RS-485):

| Step | Action |
|------|--|
| 1 | Connect the PC to a BRAND NEW controller. |
| 2 | Launch FREE Studio Plus. |

| Step | Action |
|------|---|
| 3 | In the Configuration tab, click On-line > Setup Communication to configure the communication port. |
| 4 | In the Configuration tab, click On-line > Connect to connect to the controller. NOTE: FREE Studio Plus verifies if it is a BRAND NEW controller. If it is a NOT BRAND NEW or a OBSOLETE controller, the connection can be directly established. |
| 5 | Enter the default login: "administrator" |
| 6 | Enter the default password: "password". |
| 7 | Enter the new password. |
| 8 | Click OK to validate. Result: If the new password is different from the default one, the connection can be directly established. You can now configure the controller and activate the communication port with the dedicated parameters, page 128. |

Cybersecurity

After the first connection, you can manually enable Modbus TCP / BACnet IP / FTP.

However, doing so may expose your network to possible cyberattacks if you do not take additional measures to protect your enterprise. In addition, you may be subject to laws and regulations concerning cybersecurity.

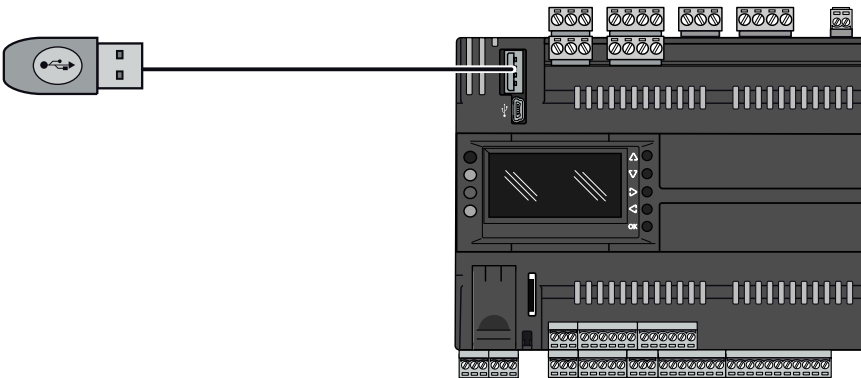
For cybersecurity details, refer to:

- CyberSecurity Defense-in-Depth, page 163.
- Replace the default password, page 163.

Connection with a USB Memory Key

Connecting a USB Memory Key to the Controller

Connection of the USB memory key to the AV•••••6•500 controller:



The USB memory key is connected on the type A USB port of the controller.

Following operations are possible between the USB memory key and the controller in direct USB connection:

| Data type | Memory key → Controller | Controller → Memory key |
|------------------------|-------------------------|-------------------------|
| Parameters | ✓ | ✓ |
| Controller application | ✓ | ✓ |
| HMI application | ✓ | ✓ |
| Data file | ✓ | ✓ |
| BIOS | - | - |

First Programming: USB Memory Key → Controller

In FREE Studio Plus, at each time you select **Create USB programming files**, you must enter a new password for **BRAND NEW** controller only (new password different of the default password of the web-server).

FREE Advance first programming via USB memory key:

| Step | Action |
|------|---|
| 1 | Connect the USB memory key to a BRAND NEW controller. |
| 2 | <ul style="list-style-type: none"> • USB content is downloaded into the controller: yellow LED flashes during download. • When the download is completed, green LED flashes twice and switch ON to confirm successful download. <p>NOTE:</p> <ul style="list-style-type: none"> • If the password file does not exist in the USB memory key, the download is not executed into a BRAND NEW controller. • If it is a NOT BRAND NEW or a OBSOLETE controller, USB content can be directly downloaded into the controller. • If it is a OBSOLETE controller, the file related to the password changed must be removed. |
| 3 | Remove USB memory key. |

NOTE: The USB memory key contains the default login and default password in clear text, you must pay particular attention to protect these informations.

Cybersecurity

After the first connection, you can manually enable Modbus TCP / BACnet IP / FTP.

However, doing so may expose your network to possible cyberattacks if you do not take additional measures to protect your enterprise. In addition, you may be subject to laws and regulations concerning cybersecurity.

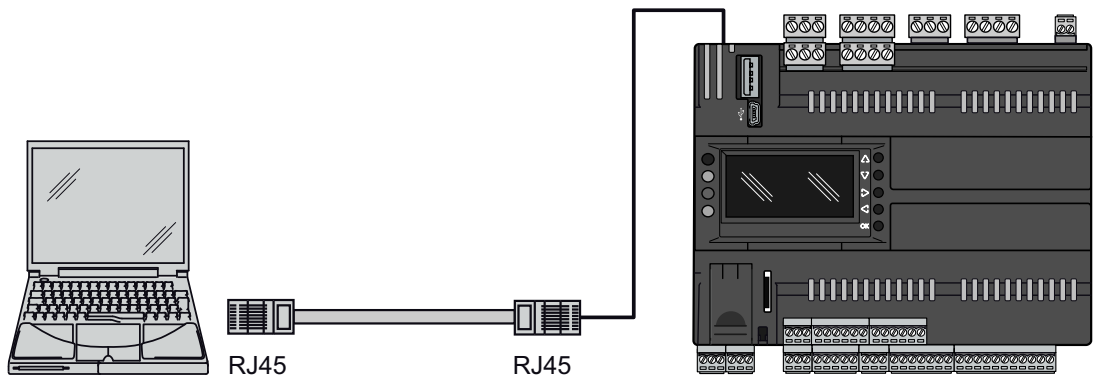
For cybersecurity details, refer to:

- CyberSecurity Defense-in-Depth, page 163.
- Replace the default password, page 163.

Connection with a PC through Ethernet

Connecting the PC to the Controller

Direct connection between the PC and the AV•••••6•500 controller:



To connect the PC to the controller, use a RJ45 Ethernet cable.

Following operations are possible between the PC and the controller in direct Ethernet connection:

| Data type | PC → Controller | Controller → PC |
|------------------------|-----------------|-----------------|
| Parameters | ✓ | ✓ |
| Controller application | ✓ | ✓ |
| HMI application | ✓ | ✓ |
| Data file | ✓ | ✓ |
| BIOS | ✓ | - |

First Commissioning

FREE Advance first connection via RJ45 Ethernet cable:

| Step | Action |
|------|--|
| 1 | Connect the PC to a BRAND NEW controller. |
| 2 | Launch FREE Studio Plus. |
| 3 | In the Configuration tab, click On-line > Setup Communication to configure the communication port. The Modbus TCP protocol must be selected. The default IP address for a BRAND NEW controller is: 10.0.0.100 |
| 4 | In the Configuration tab, click On-line > Connect to connect to the controller. NOTE: FREE Studio Plus verifies if it is a BRAND NEW controller. If it is a NOT BRAND NEW or OBSOLETE controller: <ul style="list-style-type: none"> • If Modbus TCP enabled, the connection can be directly established. • If Modbus TCP disabled and HTTP disabled, the connection is not established. • If Modbus TCP disabled and HTTP enabled, FREE Studio Plus redirects to the webpage. |
| 5 | Enter the default login: "administrator" |
| 6 | Enter the default password: "password". |
| 7 | Enter the new password. |
| 8 | Click OK to validate. Result: If the new password is different from the default one, the connection can be directly established. You can now configure the controller and activate the communication port with the dedicated parameters, page 128. |

Cybersecurity

After the first connection, you can manually enable Modbus TCP / BACnet IP / FTP.

However, doing so may expose your network to possible cyberattacks if you do not take additional measures to protect your enterprise. In addition, you may be subject to laws and regulations concerning cybersecurity.

For cybersecurity details, refer to:

- CyberSecurity Defense-in-Depth, page 163.
- Replace the default password, page 163.

Expansion and Remote Display Connection Types

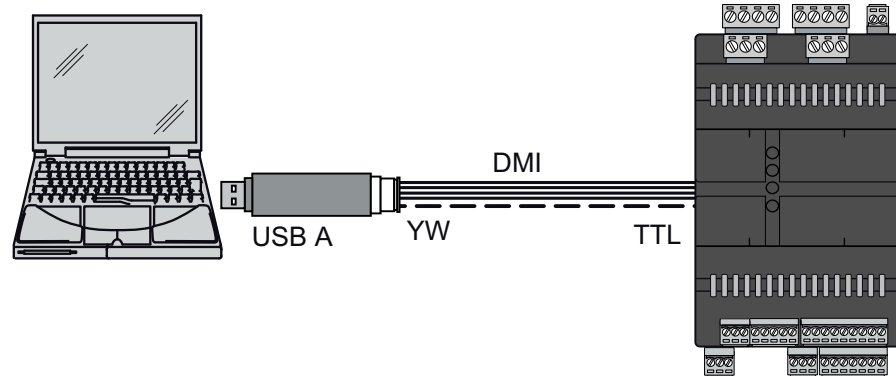
What's in This Chapter

Connection for Expansion Module and Remote display 169

Connection for Expansion Module and Remote display

Connecting The PC to an Expansion Module

Direct connection between the PC and an expansion module:



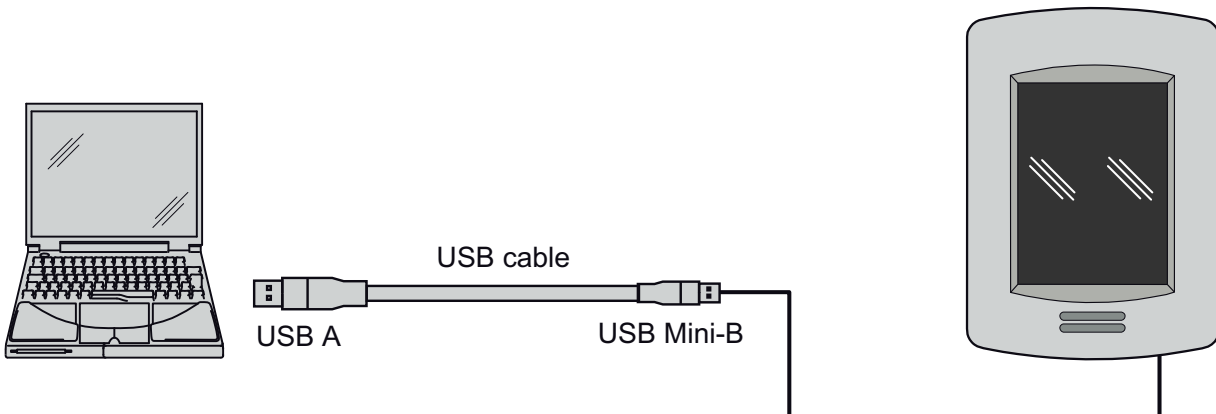
To connect the PC to the expansion module, use a DMI programming cable (Yellow) on the TTL port of the device.

Following operations are possible between the PC and the Expansion Module:

| Data type | PC → Expansion module | Expansion module →PC |
|------------------------|-----------------------|----------------------|
| Parameters | ✓ | ✓ |
| Controller application | - | - |
| HMI application | - | - |
| Data file | - | - |
| BIOS | ✓ | - |

Connecting the PC to the AVP1•0•••0500 Remote Display

Direct connection between the PC and the AVP1•0•••0500 remote display:



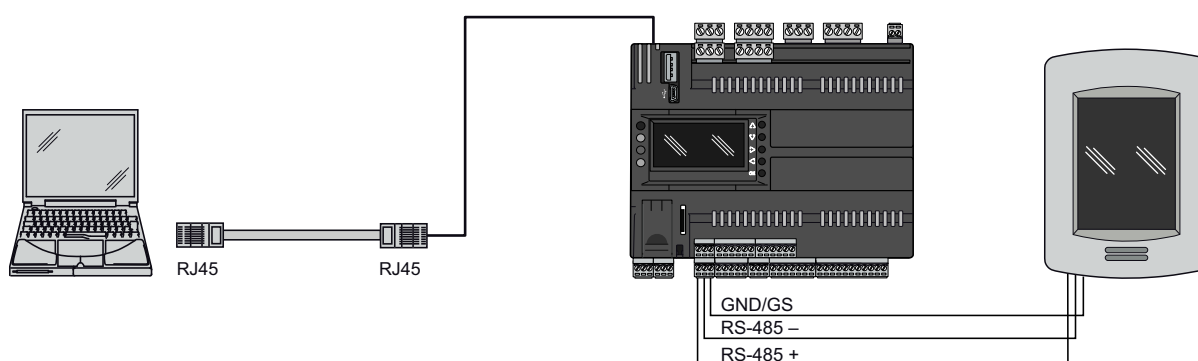
To connect the PC to the remote display, use a type A / type micro-B USB cable.

Following operations are possible between the PC and the controller in direct USB connection:

| Data type | PC → Remote display | Remote display →PC |
|------------------------|---------------------|--------------------|
| Parameters | ✓ | ✓ |
| Controller application | ✓ | - |
| HMI application | ✓ | - |
| Data file | - | - |
| BIOS | ✓ | - |

Connecting the PC to AVP1•0•••0500 the Remote Display through a Controller

Connection between the PC and the AVP1•0•••0500 remote display through a controller:



To connect the PC to the AVP1•0•••0500 remote display trough a controller, use:

- A RJ45 Ethernet cable between the PC and the controller.
- An RS-485 connection between the controller and the remote display

NOTE: Bridge function must be enabled in the AV•••••6•500 / AV•••••5•500 controller, AVP1•0•••0500 run as Slave Modbus/RTU.

Following operations are possible between the PC and the remote display connected through the controller:

| Data type | PC → Remote display | Remote display →PC |
|------------------------|---------------------|--------------------|
| Parameters | ✓ | ✓ |
| Controller application | ✓ | - |
| HMI application | ✓ | - |
| Data file | - | - |
| BIOS | ✓ | - |

Connecting the AVK1000000500 Remote Display

For commissioning, the AVK1000000500 remote display can only be connected to a controller. You can upload HMI pages and upload BIOS.

Following operations are possible between the controller and the AVK1000000500 remote display:

| Data type | Controller → Remote display | Remote display → Controller |
|------------------------|------------------------------------|------------------------------------|
| Parameters | - | - |
| Controller application | - | - |
| HMI pages | ✓ | - |
| Data file | - | - |
| BIOS | ✓ | - |

For more details, refer to Diagnostic Menu, page 120.

BIOS Update

What's in This Chapter

BIOS Update 172

BIOS Update

Overview

There are several ways to update the FREE Advance controller, FREE Advance Expansion and FREE Advance Display Color Touchscreen BIOS:

- Downloading into the FREE Advance Logic Controller from USB memory key
- Downloading into the FREE Advance Logic Controller from PC with FREE Studio Plus
- Downloading into the FREE EVE Expansion Module from PC with FREE Studio Plus
- Downloading into the FREE AVP Display Color Touchscreen from PC with FREE Studio Plus

If you remove power to the device, or there is a power outage or communication interruption during the transfer of the application, your device may become inoperative. If a communication interruption or a power outage occurs, reattempt the transfer. If there is a power outage or communication interruption during a firmware update, or if an invalid firmware is used, your device will become inoperative. In this case, use a valid firmware and reattempt the firmware update.

NOTICE

INOPERABLE EQUIPMENT

- Do not interrupt the transfer of the application program or a firmware change once the transfer has begun.
- Re-initiate the transfer if the transfer is interrupted for any reason.
- Do not attempt to place the device into service until the file transfer has completed successfully.

Failure to follow these instructions can result in equipment damage.

Download Controller BIOS from USB Memory Key

Steps to download controller BIOS from USB memory key:

| Step | Action |
|------|--|
| 1 | Trace the BIOS file (it has the file extension .bin) in one of the following ways: <ul style="list-style-type: none"> If you have FREE Studio Plus installed on your PC, BIOS is available in the following: <code><C:\Programs>\Eliwell\free Studio\Catalog\FreeAdvance\Firmware_XXX</code> Download .bin file from website - Firmware Update section. |
| 2 | Copy this file into a USB memory key (for example, mskxxx_yy.bin) |
| 3 | Connect USB memory key to FREE Advance Logic Controller, page 165. <ul style="list-style-type: none"> BIOS is downloaded into FREE Advance Logic Controller: yellow LED flashes during download. When the download is completed, green LED flashes twice and switch ON to confirm successful download. |
| 4 | Remove USB memory key. <ul style="list-style-type: none"> FREE Advance Logic Controller automatically resets and restarts. If a SYSTEM FAULT message appears, it is related to a watchdog time-out that occurred while updating the BIOS and, in this case, can be ignored. BIOS update has been completed successfully. |

FREE Advance Logic Controller does not download a non-compliant BIOS (for example you cannot download BIOS for FREE Smart Logic Controller into an FREE Advance Logic Controller and vice versa).

Download Controller BIOS from PC with FREE Studio Plus software

Steps to download Controller BIOS from PC:

| Step | Action |
|------|--|
| 1 | Connect the FREE Advance Logic Controller via USB, page 164, RS-485, or Ethernet, page 167 to the PC. |
| 2 | Open FREE Studio Plus software. |
| 3 | Open a existing project or create a new one. |
| 4 | Select the Commissioning tab. |
| 5 | In the menu, select Target > Setup communication . |
| 6 | Click Connect . |
| 7 | Click on the controller name in the Commissioning window. |
| 8 | Click BIOS download . |
| 9 | Select the .bin file you want to download, located in: <ul style="list-style-type: none"> <code><C:\Programs>\Eliwell\free Studio\Catalog\FreeAdvance\Firmware_XXX</code> |
| 10 | Click Download button. The operation may take a few minutes. If the download terminates successfully, a confirmation is displayed. |
| 11 | Disconnect the device from the PC. |

Download BIOS of Controller, Expansion Module, or Touchscreen Remote Display from PC with FREE Studio Plus Installer software

Steps to download BIOS from PC:

| Step | Action |
|------|--|
| 1 | Connect the FREE Advance Logic Controller, the FREE EVE Expansion Module or the FREE AVP Display Color Touchscreen to the PC. |
| 2 | Open FREE Studio Plus Installer software. |
| 3 | Use the Network Scan or add the device you want to update from the Catalog to the Tree . |
| 4 | Click Connect . |
| 5 | Right-click on the device name in the Tree . |
| 6 | Select BIOS download . |
| 7 | <p>Select the .bin file you want to download:</p> <ul style="list-style-type: none"> For FREE Advance Logic Controller, the BIOS files are located in: <C:\Programs>\Eliwell\free Studio\Catalog\FreeAdvance\Firmware_XXX For FREE EVE Expansion Module, the BIOS files are located in: <C:\Programs>\Eliwell\free Studio\Catalog\TM172E\Firmware_XXX For FREE AVP Display Color Touchscreen, the BIOS files are located in: <C:\Programs>\Eliwell\free Studio\Catalog\TM172DC\Firmware_XXX |
| 8 | <p>Click Download.</p> <p>The operation may take a few minutes.</p> <p>If the download terminates successfully, a confirmation is displayed.</p> |
| 9 | Disconnect the device from the PC. |

Download BIOS of AVK1000000500

To download BIOS, connect the remote display to the controller, page 171 and download the BIOS via the DIAGNOSTIC Menu, page 120.

Appendices

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Appendices

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 NTC 10k-2 beta (25/50) 3977 Resistance Temperature Table 177
 Pt1000 Resistance Temperature Table..... 178

NTC 10k beta 3435 Resistance Temperature Table

Celsius

| T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) |
|--------|---------|--------|--------|--------|--------|--------|-------|--------|-------|--------|-------|
| -40 | 187 400 | -13 | 48 590 | 14 | 15 270 | 41 | 5 630 | 68 | 2 366 | 95 | 1 108 |
| -39 | 177 500 | -12 | 46 410 | 15 | 14 680 | 42 | 5 440 | 69 | 2 296 | 96 | 1 080 |
| -38 | 168 200 | -11 | 44 350 | 16 | 14 110 | 43 | 5 257 | 70 | 2 229 | 97 | 1 052 |
| -37 | 159 400 | -10 | 42 390 | 17 | 13 570 | 44 | 5 081 | 71 | 2 164 | 98 | 1 025 |
| -36 | 151 100 | -9 | 40 500 | 18 | 13 050 | 45 | 4 912 | 72 | 2 101 | 99 | 999.0 |
| -35 | 143 400 | -8 | 38 700 | 19 | 12 560 | 46 | 4 750 | 73 | 2 040 | 100 | 973.7 |
| -34 | 136 100 | -7 | 37 000 | 20 | 12 090 | 47 | 4 594 | 74 | 1 981 | 101 | 949.0 |
| -33 | 129 200 | -6 | 35 380 | 21 | 11 630 | 48 | 4 444 | 75 | 1 925 | 102 | 925.0 |
| -32 | 122 800 | -5 | 33 850 | 22 | 11 200 | 49 | 4 300 | 76 | 1 870 | 103 | 901.8 |
| -31 | 116 700 | -4 | 32 390 | 23 | 10 780 | 50 | 4 162 | 77 | 1 817 | 104 | 879.3 |
| -30 | 110 900 | -3 | 31 000 | 24 | 10 380 | 51 | 4 027 | 78 | 1 766 | 105 | 857.4 |
| -29 | 105 400 | -2 | 29 690 | 25 | 10 000 | 52 | 3 897 | 79 | 1 716 | 106 | 836.3 |
| -28 | 100 100 | -1 | 28 440 | 26 | 9 633 | 53 | 3 773 | 80 | 1 669 | 107 | 815.7 |
| -27 | 95 220 | 0 | 27 250 | 27 | 9 281 | 54 | 3 653 | 81 | 1 622 | 108 | 795.8 |
| -26 | 90 570 | 1 | 26 100 | 28 | 8 945 | 55 | 3 537 | 82 | 1 577 | 109 | 776.4 |
| -25 | 86 180 | 2 | 25 000 | 29 | 8 623 | 56 | 3 426 | 83 | 1 534 | 110 | 757.6 |
| -24 | 82 040 | 3 | 23 960 | 30 | 8 314 | 57 | 3 319 | 84 | 1 492 | 111 | 739.2 |
| -23 | 78 130 | 4 | 22 970 | 31 | 8 016 | 58 | 3 216 | 85 | 1 451 | 112 | 721.4 |
| -22 | 74 440 | 5 | 22 030 | 32 | 7 730 | 59 | 3 117 | 86 | 1 412 | 113 | 704.1 |
| -21 | 70 940 | 6 | 21 130 | 33 | 7 456 | 60 | 3 022 | 87 | 1 374 | 114 | 687.3 |
| -20 | 67 640 | 7 | 20 280 | 34 | 7 193 | 61 | 2 929 | 88 | 1 337 | 115 | 671.0 |
| -19 | 64 440 | 8 | 19 460 | 35 | 6 941 | 62 | 2 839 | 89 | 1 301 | 116 | 655.2 |
| -18 | 61 420 | 9 | 18 690 | 36 | 6 700 | 63 | 2 753 | 90 | 1 266 | 117 | 639.8 |
| -17 | 58 570 | 10 | 17 950 | 37 | 6 468 | 64 | 2 670 | 91 | 1 233 | 118 | 624.8 |
| -16 | 55 870 | 11 | 17 230 | 38 | 6 246 | 65 | 2 589 | 92 | 1 200 | 119 | 610.3 |
| -15 | 53 310 | 12 | 16 550 | 39 | 6 033 | 66 | 2 512 | 93 | 1 169 | 120 | 596.1 |
| -14 | 50 880 | 13 | 15 900 | 40 | 5 829 | 67 | 2 438 | 94 | 1 138 | | |

Fahrenheit

| T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) |
|--------|---------|--------|--------|--------|--------|--------|-------|--------|-------|--------|-------|
| -40.0 | 187 400 | 8.6 | 48 590 | 57.2 | 15 270 | 105.8 | 5 630 | 154.4 | 2 366 | 203.0 | 1 108 |
| -38.2 | 177 500 | 10.4 | 46 410 | 59.0 | 14 680 | 107.6 | 5 440 | 156.2 | 2 296 | 204.8 | 1 080 |
| -36.4 | 168 200 | 12.2 | 44 350 | 60.8 | 14 110 | 109.4 | 5 257 | 158.0 | 2 229 | 206.6 | 1 052 |

| T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) |
|--------|---------|--------|--------|--------|--------|--------|-------|--------|-------|--------|-------|
| -34.6 | 159 400 | 14.0 | 42 390 | 62.6 | 13 570 | 111.2 | 5 081 | 159.8 | 2 164 | 208.4 | 1 025 |
| -32.8 | 151 100 | 15.8 | 40 500 | 64.4 | 13 050 | 113.0 | 4 912 | 161.6 | 2 101 | 210.2 | 999.0 |
| -31.0 | 143 400 | 17.6 | 38 700 | 66.2 | 12 560 | 114.8 | 4 750 | 163.4 | 2 040 | 212.0 | 973.7 |
| -29.2 | 136 100 | 19.4 | 37 000 | 68.0 | 12 090 | 116.6 | 4 594 | 165.2 | 1 981 | 213.8 | 949.0 |
| -27.4 | 129 200 | 21.2 | 35 380 | 69.8 | 11 630 | 118.4 | 4 444 | 167.0 | 1 925 | 215.6 | 925.0 |
| -25.6 | 122 800 | 23.0 | 33 850 | 71.6 | 11 200 | 120.2 | 4 300 | 168.8 | 1 870 | 217.4 | 901.8 |
| -23.8 | 116 700 | 24.8 | 32 390 | 73.4 | 10 780 | 122.0 | 4 162 | 170.6 | 1 817 | 219.2 | 879.3 |
| -22.0 | 110 900 | 26.6 | 31 000 | 75.2 | 10 380 | 123.8 | 4 027 | 172.4 | 1 766 | 221.0 | 857.4 |
| -20.2 | 105 400 | 28.4 | 29 690 | 77.0 | 10 000 | 125.6 | 3 897 | 174.2 | 1 716 | 222.8 | 836.3 |
| -18.4 | 100 100 | 30.2 | 28 440 | 78.8 | 9 633 | 127.4 | 3 773 | 176.0 | 1 669 | 224.6 | 815.7 |
| -16.6 | 95 220 | 32.0 | 27 250 | 80.6 | 9 281 | 129.2 | 3 653 | 177.8 | 1 622 | 226.4 | 795.8 |
| -14.8 | 90 570 | 33.8 | 26 100 | 82.4 | 8 945 | 131.0 | 3 537 | 179.6 | 1 577 | 228.2 | 776.4 |
| -13.0 | 86 180 | 35.6 | 25 000 | 84.2 | 8 623 | 132.8 | 3 426 | 181.4 | 1 534 | 230.0 | 757.6 |
| -11.2 | 82 040 | 37.4 | 23 960 | 86.0 | 8 314 | 134.6 | 3 319 | 183.2 | 1 492 | 231.8 | 739.2 |
| -9.4 | 78 130 | 39.2 | 22 970 | 87.8 | 8 016 | 136.4 | 3 216 | 185.0 | 1 451 | 233.6 | 721.4 |
| -7.6 | 74 440 | 41.0 | 22 030 | 89.6 | 7 730 | 138.2 | 3 117 | 186.8 | 1 412 | 235.4 | 704.1 |
| -5.8 | 70 940 | 42.8 | 21 130 | 91.4 | 7 456 | 140.0 | 3 022 | 188.6 | 1 374 | 237.2 | 687.3 |
| -4.0 | 67 640 | 44.6 | 20 280 | 93.2 | 7 193 | 141.8 | 2 929 | 190.4 | 1 337 | 239.0 | 671.0 |
| -2.2 | 64 440 | 46.4 | 19 460 | 95.0 | 6 941 | 143.6 | 2 839 | 192.2 | 1 301 | 240.8 | 655.2 |
| -0.4 | 61 420 | 48.2 | 18 690 | 96.8 | 6 700 | 145.4 | 2 753 | 194.0 | 1 266 | 242.6 | 639.8 |
| 1.4 | 58 570 | 50.0 | 17 950 | 98.6 | 6 468 | 147.2 | 2 670 | 195.8 | 1 233 | 244.4 | 624.8 |
| 3.2 | 55 870 | 51.8 | 17 230 | 100.4 | 6 246 | 149.0 | 2 589 | 197.6 | 1 200 | 246.2 | 610.3 |
| 5.0 | 53 310 | 53.6 | 16 550 | 102.2 | 6 033 | 150.8 | 2 512 | 199.4 | 1 169 | 248.0 | 596.1 |
| 6.8 | 50 880 | 55.4 | 15 900 | 104.0 | 5 829 | 152.6 | 2 438 | 201.2 | 1 138 | | |

NTC 10k-2 beta (25/50) 3977 Resistance Temperature Table

Celsius

| T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) |
|--------|---------|--------|--------|--------|--------|--------|--------|--------|-------|--------|-------|
| -39.44 | 323 839 | -18.33 | 88 090 | 2.78 | 28 365 | 23.89 | 10 501 | 45.00 | 4 367 | 66.11 | 2 003 |
| -38.33 | 300 974 | -17.22 | 82 670 | 3.89 | 26 834 | 25.00 | 10 000 | 46.11 | 4 182 | 67.22 | 1 927 |
| -37.22 | 279 880 | -16.11 | 77 620 | 5.00 | 25 395 | 26.11 | 9 526 | 47.22 | 4 006 | 68.33 | 1 855 |
| -36.11 | 260 410 | -15.00 | 72 911 | 6.11 | 24 042 | 27.22 | 9 078 | 48.33 | 3 838 | 69.44 | 1 785 |
| -35.00 | 242 427 | 13.89 | 68 518 | 7.22 | 22 770 | 28.33 | 8 653 | 49.44 | 3 679 | 70.56 | 1 718 |
| -33.89 | 225 809 | 12.78 | 64 419 | 8.33 | 21 573 | 29.44 | 8 251 | 50.56 | 3 525 | 71.67 | 1 655 |
| -32.78 | 210 443 | 11.67 | 60 592 | 9.44 | 20 446 | 30.56 | 7 866 | 51.67 | 3 380 | 72.78 | 1 594 |
| -31.67 | 196 227 | 10.56 | 57 017 | 10.56 | 19 376 | 31.67 | 7 505 | 52.78 | 3 242 | 73.89 | 1 536 |
| -30.56 | 183 068 | 9.44 | 53 647 | 11.67 | 18 378 | 32.78 | 7 163 | 53.89 | 3 111 | 75.00 | 1 480 |
| -29.44 | 170 775 | 8.33 | 50 526 | 12.78 | 17 437 | 33.89 | 6 838 | 55.00 | 2 985 | 76.11 | 1 427 |
| -28.33 | 159 488 | 7.22 | 47 606 | 13.89 | 16 550 | 35.00 | 6 530 | 56.11 | 2 865 | 77.22 | 1 375 |
| -27.22 | 149 024 | 6.11 | 44 874 | 15.00 | 15 714 | 36.11 | 6 238 | 57.22 | 2 751 | 78.33 | 1 326 |
| -26.11 | 139 316 | 5.00 | 42 317 | 16.11 | 14 925 | 37.22 | 5 960 | 58.33 | 2 642 | 79.44 | 1 279 |
| -25.00 | 130 306 | 3.89 | 39 921 | 17.22 | 14 180 | 38.33 | 5 697 | 59.44 | 2 538 | 80.56 | 1 234 |
| -23.89 | 121 939 | 2.78 | 37 676 | 18.33 | 13 478 | 39.44 | 5 447 | 60.56 | 2 438 | 81.67 | 1 190 |

| T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) |
|--------|---------|--------|--------|--------|--------|--------|-------|--------|-------|--------|-------|
| -22.78 | 114 165 | 1.67 | 35 573 | 19.44 | 12 814 | 40.56 | 5 207 | 61.67 | 2 343 | 82.78 | 1 149 |
| -21.67 | 106 939 | 0.56 | 33 599 | 20.56 | 12 182 | 41.67 | 4 981 | 62.78 | 2 252 | 83.89 | 1 109 |
| -20.56 | 100 218 | 0.56 | 31 732 | 21.67 | 11 590 | 42.78 | 4 766 | 63.89 | 2 165 | 85.00 | 1 070 |
| -19.44 | 93 909 | 1.67 | 29 996 | 22.78 | 11 030 | 43.89 | 4 561 | 65.00 | 2 082 | 86.11 | 1 034 |

Fahrenheit

| T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) |
|--------|---------|--------|--------|--------|--------|--------|--------|--------|-------|--------|-------|
| -39 | 323 839 | -1 | 88 090 | 37 | 28 365 | 75 | 10 501 | 113 | 4 367 | 151 | 2 003 |
| -37 | 300 974 | 1 | 82 670 | 39 | 26 834 | 77 | 10 000 | 115 | 4 182 | 153 | 1 927 |
| -35 | 279 880 | 3 | 77 620 | 41 | 25 395 | 79 | 9 526 | 117 | 4 006 | 155 | 1 855 |
| -33 | 260 410 | 5 | 72 911 | 43 | 24 042 | 81 | 9 078 | 119 | 3 838 | 157 | 1 785 |
| -31 | 242 427 | 57 | 68 518 | 45 | 22 770 | 83 | 8 653 | 121 | 3 679 | 159 | 1 718 |
| -29 | 225 809 | 55 | 64 419 | 47 | 21 573 | 85 | 8 251 | 123 | 3 525 | 161 | 1 655 |
| -27 | 210 443 | 53 | 60 592 | 49 | 20 446 | 87 | 7 866 | 125 | 3 380 | 163 | 1 594 |
| -25 | 196 227 | 51 | 57 017 | 51 | 19 376 | 89 | 7 505 | 127 | 3 242 | 165 | 1 536 |
| -23 | 183 068 | 49 | 53 647 | 53 | 18 378 | 91 | 7 163 | 129 | 3 111 | 167 | 1 480 |
| -21 | 170 775 | 47 | 50 526 | 55 | 17 437 | 93 | 6 838 | 131 | 2 985 | 169 | 1 427 |
| -19 | 159 488 | 45 | 47 606 | 57 | 16 550 | 95 | 6 530 | 133 | 2 865 | 171 | 1 375 |
| -17 | 149 024 | 43 | 44 874 | 59 | 15 714 | 97 | 6 238 | 135 | 2 751 | 173 | 1 326 |
| -15 | 139 316 | 41 | 42 317 | 61 | 14 925 | 99 | 5 960 | 137 | 2 642 | 175 | 1 279 |
| -13 | 130 306 | 39 | 39 921 | 63 | 14 180 | 101 | 5 697 | 139 | 2 538 | 177 | 1 234 |
| -11 | 121 939 | 37 | 37 676 | 65 | 13 478 | 103 | 5 447 | 141 | 2 438 | 179 | 1 190 |
| -9 | 114 165 | 35 | 35 573 | 67 | 12 814 | 105 | 5 207 | 143 | 2 343 | 181 | 1 149 |
| -7 | 106 939 | 33 | 33 599 | 69 | 12 182 | 107 | 4 981 | 145 | 2 252 | 183 | 1 109 |
| -5 | 100 218 | 33 | 31 732 | 71 | 11 590 | 109 | 4 766 | 147 | 2 165 | 185 | 1 070 |
| -3 | 93 909 | 35 | 29 996 | 73 | 11 030 | 111 | 4 561 | 149 | 2 082 | 187 | 1 034 |

Pt1000 Resistance Temperature Table

Celsius

| T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) |
|--------|--------|--------|--------|--------|---------|--------|---------|--------|---------|--------|---------|
| -100 | 602.56 | -49 | 807.03 | 2 | 1007.81 | 53 | 1205.52 | 104 | 1400.22 | 155 | 1591.91 |
| -99 | 606.61 | -48 | 811.00 | 3 | 1011.72 | 54 | 1209.36 | 105 | 1404.00 | 156 | 1595.64 |
| -98 | 610.66 | -47 | 814.97 | 4 | 1015.62 | 55 | 1213.21 | 106 | 1407.79 | 157 | 1599.37 |
| -97 | 614.71 | -46 | 818.94 | 5 | 1019.53 | 56 | 1217.05 | 107 | 1411.58 | 158 | 1603.09 |
| -96 | 618.76 | -45 | 822.90 | 6 | 1023.43 | 57 | 1220.90 | 108 | 1415.36 | 159 | 1606.82 |
| -95 | 622.80 | -44 | 826.87 | 7 | 1027.33 | 58 | 1224.74 | 109 | 1419.14 | 160 | 1610.54 |
| -94 | 626.84 | -43 | 830.83 | 8 | 1031.23 | 59 | 1228.58 | 110 | 1422.93 | 161 | 1614.27 |
| -93 | 630.88 | -42 | 834.79 | 9 | 1035.13 | 60 | 1232.42 | 111 | 1426.71 | 162 | 1617.99 |
| -92 | 634.92 | -41 | 838.75 | 10 | 1039.03 | 61 | 1236.26 | 112 | 1430.49 | 163 | 1621.71 |
| -91 | 638.96 | -40 | 842.71 | 11 | 1042.92 | 62 | 1240.09 | 113 | 1434.26 | 164 | 1625.43 |
| -90 | 643.00 | -39 | 846.66 | 12 | 1046.82 | 63 | 1243.93 | 114 | 1438.04 | 165 | 1629.15 |

| T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) | T (°C) | R (Ω) |
|--------|--------|--------|---------|--------|---------|--------|---------|--------|---------|--------|---------|
| -89 | 647.03 | -38 | 850.62 | 13 | 1050.71 | 64 | 1247.77 | 115 | 1441.82 | 166 | 1632.86 |
| -88 | 651.06 | -37 | 854.57 | 14 | 1054.60 | 65 | 1251.60 | 116 | 1445.59 | 167 | 1636.58 |
| -87 | 655.09 | -36 | 858.53 | 15 | 1058.49 | 66 | 1255.43 | 117 | 1449.37 | 168 | 1640.30 |
| -86 | 659.12 | -35 | 862.48 | 16 | 1062.38 | 67 | 1259.26 | 118 | 1453.14 | 169 | 1644.01 |
| -85 | 663.15 | -34 | 866.43 | 17 | 1066.27 | 68 | 1263.09 | 119 | 1456.91 | 170 | 1647.72 |
| -84 | 667.17 | -33 | 870.38 | 18 | 1070.16 | 69 | 1266.92 | 120 | 1460.68 | 171 | 1651.43 |
| -83 | 671.20 | -32 | 874.32 | 19 | 1074.05 | 70 | 1270.75 | 121 | 1464.45 | 172 | 1655.14 |
| -82 | 675.22 | -31 | 878.27 | 20 | 1077.94 | 71 | 1274.58 | 122 | 1468.22 | 173 | 1658.85 |
| -81 | 679.24 | -30 | 882.22 | 21 | 1081.82 | 72 | 1278.40 | 123 | 1471.98 | 174 | 1662.56 |
| -80 | 683.25 | -29 | 886.16 | 22 | 1085.70 | 73 | 1282.23 | 124 | 1475.75 | 175 | 1666.27 |
| -79 | 687.27 | -28 | 890.10 | 23 | 1089.59 | 74 | 1286.05 | 125 | 1479.51 | 176 | 1669.97 |
| -78 | 691.29 | -27 | 894.04 | 24 | 1093.47 | 75 | 1289.87 | 126 | 1483.28 | 177 | 1673.68 |
| -77 | 695.30 | -26 | 897.98 | 25 | 1097.35 | 76 | 1293.70 | 127 | 1487.04 | 178 | 1677.38 |
| -76 | 699.31 | -25 | 901.92 | 26 | 1101.23 | 77 | 1297.52 | 128 | 1490.80 | 179 | 1681.08 |
| -75 | 703.32 | -24 | 905.86 | 27 | 1105.10 | 78 | 1301.33 | 129 | 1494.56 | 180 | 1684.78 |
| -74 | 707.33 | -23 | 909.80 | 28 | 1108.98 | 79 | 1305.15 | 130 | 1498.32 | 181 | 1688.48 |
| -73 | 711.34 | -22 | 913.73 | 29 | 1112.86 | 80 | 1308.97 | 131 | 1502.08 | 182 | 1692.18 |
| -72 | 715.34 | -21 | 917.67 | 30 | 1116.73 | 81 | 1312.78 | 132 | 1505.83 | 183 | 1695.88 |
| -71 | 719.34 | -20 | 921.60 | 31 | 1120.60 | 82 | 1316.60 | 133 | 1509.59 | 184 | 1699.58 |
| -70 | 723.35 | -19 | 925.53 | 32 | 1124.47 | 83 | 1320.41 | 134 | 1513.34 | 185 | 1703.27 |
| -69 | 727.35 | -18 | 929.46 | 33 | 1128.35 | 84 | 1324.22 | 135 | 1517.10 | 186 | 1706.96 |
| -68 | 731.34 | -17 | 933.39 | 34 | 1132.21 | 85 | 1328.03 | 136 | 1520.85 | 187 | 1710.66 |
| -67 | 735.34 | -16 | 937.32 | 35 | 1136.08 | 86 | 1331.84 | 137 | 1524.60 | 188 | 1714.35 |
| -66 | 739.34 | -15 | 941.24 | 36 | 1139.95 | 87 | 1335.65 | 138 | 1528.35 | 189 | 1718.04 |
| -65 | 743.33 | -14 | 945.17 | 37 | 1143.82 | 88 | 1339.46 | 139 | 1532.10 | 190 | 1721.73 |
| -64 | 747.32 | -13 | 949.09 | 38 | 1147.68 | 89 | 1343.26 | 140 | 1535.84 | 191 | 1725.42 |
| -63 | 751.31 | -12 | 953.02 | 39 | 1151.55 | 90 | 1347.07 | 141 | 1539.59 | 192 | 1729.10 |
| -62 | 755.30 | -11 | 956.94 | 40 | 1155.41 | 91 | 1350.87 | 142 | 1543.33 | 193 | 1732.79 |
| -61 | 759.29 | -10 | 960.86 | 41 | 1159.27 | 92 | 1354.68 | 143 | 1547.08 | 194 | 1736.48 |
| -60 | 763.28 | -9 | 964.78 | 42 | 1163.13 | 93 | 1358.48 | 144 | 1550.82 | 195 | 1740.16 |
| -59 | 767.26 | -8 | 968.70 | 43 | 1166.99 | 94 | 1362.28 | 145 | 1554.56 | 196 | 1743.84 |
| -58 | 771.25 | -7 | 972.61 | 44 | 1170.85 | 95 | 1366.08 | 146 | 1558.30 | 197 | 1747.52 |
| -57 | 775.23 | -6 | 976.53 | 45 | 1174.70 | 96 | 1369.87 | 147 | 1562.04 | 198 | 1751.20 |
| -56 | 779.21 | -5 | 980.44 | 46 | 1178.56 | 97 | 1373.67 | 148 | 1565.78 | 199 | 1754.88 |
| -55 | 783.19 | -4 | 984.36 | 47 | 1182.41 | 98 | 1377.47 | 149 | 1569.52 | 200 | 1758.56 |
| -54 | 787.17 | -3 | 988.27 | 48 | 1186.27 | 99 | 1381.26 | 150 | 1573.25 | | |
| -53 | 791.14 | -2 | 992.18 | 49 | 1190.12 | 100 | 1385.06 | 151 | 1576.99 | | |
| -52 | 795.12 | -1 | 996.09 | 50 | 1193.97 | 101 | 1388.85 | 152 | 1580.72 | | |
| -51 | 799.09 | 0 | 1000.00 | 51 | 1197.82 | 102 | 1392.64 | 153 | 1584.45 | | |
| -50 | 803.06 | 1 | 1003.91 | 52 | 1201.67 | 103 | 1396.43 | 154 | 1588.18 | | |

Fahrenheit

| T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) |
|--------|--------|--------|--------|--------|---------|--------|---------|--------|---------|--------|---------|
| -148.0 | 602.56 | -56.2 | 807.03 | 35.6 | 1007.81 | 127.4 | 1205.52 | 219.2 | 1400.22 | 311.0 | 1591.91 |
| -146.2 | 606.61 | -54.4 | 811.00 | 37.4 | 1011.72 | 129.2 | 1209.36 | 221.0 | 1404.00 | 312.8 | 1595.64 |

| T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) |
|--------|--------|--------|--------|--------|---------|--------|---------|--------|---------|--------|---------|
| -144.4 | 610.66 | -52.6 | 814.97 | 39.2 | 1015.62 | 131.0 | 1213.21 | 222.8 | 1407.79 | 314.6 | 1599.37 |
| -142.6 | 614.71 | -50.8 | 818.94 | 41.0 | 1019.53 | 132.8 | 1217.05 | 224.6 | 1411.58 | 316.4 | 1603.09 |
| -140.8 | 618.76 | -49.0 | 822.90 | 42.8 | 1023.43 | 134.6 | 1220.90 | 226.4 | 1415.36 | 318.2 | 1606.82 |
| -139.0 | 622.80 | -47.2 | 826.87 | 44.6 | 1027.33 | 136.4 | 1224.74 | 228.2 | 1419.14 | 320.0 | 1610.54 |
| -137.2 | 626.84 | -45.4 | 830.83 | 46.4 | 1031.23 | 138.2 | 1228.58 | 230.0 | 1422.93 | 321.8 | 1614.27 |
| -135.4 | 630.88 | -43.6 | 834.79 | 48.2 | 1035.13 | 140.0 | 1232.42 | 231.8 | 1426.71 | 323.6 | 1617.99 |
| -133.6 | 634.92 | -41.8 | 838.75 | 50.0 | 1039.03 | 141.8 | 1236.26 | 233.6 | 1430.49 | 325.4 | 1621.71 |
| -131.8 | 638.96 | -40.0 | 842.71 | 51.8 | 1042.92 | 143.6 | 1240.09 | 235.4 | 1434.26 | 327.2 | 1625.43 |
| -130.0 | 643.00 | -38.2 | 846.66 | 53.6 | 1046.82 | 145.4 | 1243.93 | 237.2 | 1438.04 | 329.0 | 1629.15 |
| -128.2 | 647.03 | -36.4 | 850.62 | 55.4 | 1050.71 | 147.2 | 1247.77 | 239.0 | 1441.82 | 330.8 | 1632.86 |
| -126.4 | 651.06 | -34.6 | 854.57 | 57.2 | 1054.60 | 149.0 | 1251.60 | 240.8 | 1445.59 | 332.6 | 1636.58 |
| -124.6 | 655.09 | -32.8 | 858.53 | 59.0 | 1058.49 | 150.8 | 1255.43 | 242.6 | 1449.37 | 334.4 | 1640.30 |
| -122.8 | 659.12 | -31.0 | 862.48 | 60.8 | 1062.38 | 152.6 | 1259.26 | 244.4 | 1453.14 | 336.2 | 1644.01 |
| -121.0 | 663.15 | -29.2 | 866.43 | 62.6 | 1066.27 | 154.4 | 1263.09 | 246.2 | 1456.91 | 338.0 | 1647.72 |
| -119.2 | 667.17 | -27.4 | 870.38 | 64.4 | 1070.16 | 156.2 | 1266.92 | 248.0 | 1460.68 | 339.8 | 1651.43 |
| -117.4 | 671.20 | -25.6 | 874.32 | 66.2 | 1074.05 | 158.0 | 1270.75 | 249.8 | 1464.45 | 341.6 | 1655.14 |
| -115.6 | 675.22 | -23.8 | 878.27 | 68.0 | 1077.94 | 159.8 | 1274.58 | 251.6 | 1468.22 | 343.4 | 1658.85 |
| -113.8 | 679.24 | -22.0 | 882.22 | 69.8 | 1081.82 | 161.6 | 1278.40 | 253.4 | 1471.98 | 345.2 | 1662.56 |
| -112.0 | 683.25 | -20.2 | 886.16 | 71.6 | 1085.70 | 163.4 | 1282.23 | 255.2 | 1475.75 | 347.0 | 1666.27 |
| -110.2 | 687.27 | -18.4 | 890.10 | 73.4 | 1089.59 | 165.2 | 1286.05 | 257.0 | 1479.51 | 348.8 | 1669.97 |
| -108.4 | 691.29 | -16.6 | 894.04 | 75.2 | 1093.47 | 167.0 | 1289.87 | 258.8 | 1483.28 | 350.6 | 1673.68 |
| -106.6 | 695.30 | -14.8 | 897.98 | 77.0 | 1097.35 | 168.8 | 1293.70 | 260.6 | 1487.04 | 352.4 | 1677.38 |
| -104.8 | 699.31 | -13.0 | 901.92 | 78.8 | 1101.23 | 170.6 | 1297.52 | 262.4 | 1490.80 | 354.2 | 1681.08 |
| -103.0 | 703.32 | -11.2 | 905.86 | 80.6 | 1105.10 | 172.4 | 1301.33 | 264.2 | 1494.56 | 356.0 | 1684.78 |
| -101.2 | 707.33 | -9.4 | 909.80 | 82.4 | 1108.98 | 174.2 | 1305.15 | 266.0 | 1498.32 | 357.8 | 1688.48 |
| -99.4 | 711.34 | -7.6 | 913.73 | 84.2 | 1112.86 | 176.0 | 1308.97 | 267.8 | 1502.08 | 359.6 | 1692.18 |
| -97.6 | 715.34 | -5.8 | 917.67 | 86.0 | 1116.73 | 177.8 | 1312.78 | 269.6 | 1505.83 | 361.4 | 1695.88 |
| -95.8 | 719.34 | -4.0 | 921.60 | 87.8 | 1120.60 | 179.6 | 1316.60 | 271.4 | 1509.59 | 363.2 | 1699.58 |
| -94.0 | 723.35 | -2.2 | 925.53 | 89.6 | 1124.47 | 181.4 | 1320.41 | 273.2 | 1513.34 | 365.0 | 1703.27 |
| -92.2 | 727.35 | -0.4 | 929.46 | 91.4 | 1128.35 | 183.2 | 1324.22 | 275.0 | 1517.10 | 366.8 | 1706.96 |
| -90.4 | 731.34 | 1.4 | 933.39 | 93.2 | 1132.21 | 185.0 | 1328.03 | 276.8 | 1520.85 | 368.6 | 1710.66 |
| -88.6 | 735.34 | 3.2 | 937.32 | 95.0 | 1136.08 | 186.8 | 1331.84 | 278.6 | 1524.60 | 370.4 | 1714.35 |
| -86.8 | 739.34 | 5.0 | 941.24 | 96.8 | 1139.95 | 188.6 | 1335.65 | 280.4 | 1528.35 | 372.2 | 1718.04 |
| -85.0 | 743.33 | 6.8 | 945.17 | 98.6 | 1143.82 | 190.4 | 1339.46 | 282.2 | 1532.10 | 374.0 | 1721.73 |
| -83.2 | 747.32 | 8.6 | 949.09 | 100.4 | 1147.68 | 192.2 | 1343.26 | 284.0 | 1535.84 | 375.8 | 1725.42 |
| -81.4 | 751.31 | 10.4 | 953.02 | 102.2 | 1151.55 | 194.0 | 1347.07 | 285.8 | 1539.59 | 377.6 | 1729.10 |
| -79.6 | 755.30 | 12.2 | 956.94 | 104.0 | 1155.41 | 195.8 | 1350.87 | 287.6 | 1543.33 | 379.4 | 1732.79 |
| -77.8 | 759.29 | 14.0 | 960.86 | 105.8 | 1159.27 | 197.6 | 1354.68 | 289.4 | 1547.08 | 381.2 | 1736.48 |
| -76.0 | 763.28 | 15.8 | 964.78 | 107.6 | 1163.13 | 199.4 | 1358.48 | 291.2 | 1550.82 | 383.0 | 1740.16 |
| -74.2 | 767.26 | 17.6 | 968.70 | 109.4 | 1166.99 | 201.2 | 1362.28 | 293.0 | 1554.56 | 384.8 | 1743.84 |
| -72.4 | 771.25 | 19.4 | 972.61 | 111.2 | 1170.85 | 203.0 | 1366.08 | 294.8 | 1558.30 | 386.6 | 1747.52 |
| -70.6 | 775.23 | 21.2 | 976.53 | 113.0 | 1174.70 | 204.8 | 1369.87 | 296.6 | 1562.04 | 388.4 | 1751.20 |
| -68.8 | 779.21 | 23.0 | 980.44 | 114.8 | 1178.56 | 206.6 | 1373.67 | 298.4 | 1565.78 | 390.2 | 1754.88 |
| -67.0 | 783.19 | 24.8 | 984.36 | 116.6 | 1182.41 | 208.4 | 1377.47 | 300.2 | 1569.52 | 392.0 | 1758.56 |
| -65.2 | 787.17 | 26.6 | 988.27 | 118.4 | 1186.27 | 210.2 | 1381.26 | 302.0 | 1573.25 | | |
| -63.4 | 791.14 | 28.4 | 992.18 | 120.2 | 1190.12 | 212.0 | 1385.06 | 303.8 | 1576.99 | | |

| T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) | T (°F) | R (Ω) |
|--------|--------|--------|---------|--------|---------|--------|---------|--------|---------|--------|-------|
| -61.6 | 795.12 | 30.2 | 996.09 | 122.0 | 1193.97 | 213.8 | 1388.85 | 305.6 | 1580.72 | | |
| -59.8 | 799.09 | 32.0 | 1000.00 | 123.8 | 1197.82 | 215.6 | 1392.64 | 307.4 | 1584.45 | | |
| -58.0 | 803.06 | 33.8 | 1003.91 | 125.6 | 1201.67 | 217.4 | 1396.43 | 309.2 | 1588.18 | | |

Glossary

A

analog input:

Converts received voltage or current levels into numerical values. You can store and process these values within the logic controller.

analog output:

Converts numerical values within the logic controller and sends out proportional voltage or current levels.

application:

A program including configuration data, symbols, and documentation.

AWG:

(*American wire gauge*) The standard that specifies wire section sizes in North America.

B

BIOS:

(*basic input output system*) Part of the firmware used during the booting process.

BOOL:

(*boolean*) A basic data type in computing. A **BOOL** variable can have one of these values: 0 (**FALSE**), 1 (**TRUE**). A bit that is extracted from a word is of type **BOOL**.

C

controller:

Automates industrial processes (also known as programmable logic controller or programmable controller).

COP:

(*Coefficient Of Performance*) It is a ratio of cooling provided to work required.

D

digital I/O:

(*digital input/output*) An individual circuit connection at the electronic module that corresponds directly to a data table bit. The data table bit holds the value of the signal at the I/O circuit. It gives the control logic digital access to I/O values.

E

EEPROM:

(*electrically erasable programmable read-only memory*) A type of non-volatile memory to store required data even when power is removed.

EIA:

(*electronic industries alliance*) The trade organization for establishing electrical/electronic and data communication standards (including RS-232 and RS-485) in the United States.

EMC:

(*electromagnetic compatibility*)

EN:

EN identifies one of many European standards maintained by CEN (*European Committee for Standardization*), CENELEC (*European Committee for Electrotechnical Standardization*), or ETSI (*European Telecommunications Standards Institute*).

expansion bus:

An electronic communication bus between expansion I/O modules and a controller.

F**firmware:**

Represents the BIOS, data parameters, and programming instructions that constitute the operating system on a controller. The firmware is stored in non-volatile memory within the controller.

FLA:

(Full-Load Amperes) Amount of current drawn by the motor at rated load and rated voltage.

flash memory:

A non-volatile memory that can be overwritten. It is stored on a special EEPROM that can be erased and reprogrammed.

H**HVAC&R:**

(heating, ventilation, and air conditioning and refrigeration)

I**I/O:**

(input/output)

ID:

(identifier/identification)

IEC 61131-3:

Part 3 of a 3-part IEC standard for industrial automation equipment. IEC 61131-3 is concerned with controller programming languages and defines 2 graphical and 2 textual programming language standards. The graphical programming languages are ladder diagram and function block diagram. The textual programming languages include structured text and instruction list.

IP20:

(ingress protection) The protection classification according to IEC 60529 offered by an enclosure, shown by the letter IP and 2 digits. The first digit indicates 2 factors: helping protect persons and for equipment. The second digit indicates helping protect against water. IP20 devices help protect against electric contact of objects larger than 12.5 mm, but not against water.

L**LAN:**

(local area network) A short-distance communications network that is implemented in a home, office, or institutional environment.

LCD:

(liquid crystal display) Used in many HMI devices to display menus and messages to machine operators.

LED:

(light emitting diode) An indicator that illuminates under a low-level electrical charge.

LRA:

(Locked-Rotor Amperes) Amount of current drawn by the motor at rated voltage while its rotor is locked. This provides an indication of the inrush current during start-up.

M**Modbus SL:**

(Modbus serial line) Implementation of the protocol over a RS-232 or RS-485 serial connection.

Modbus:

The protocol that allows communications between many devices connected to the same network.

ms:

(millisecond)

N**NC:**

(normally closed) A contact pair that closes when the actuator is de-energized (no power is applied) and opens when the actuator is energized (power is applied).

NEMA:

(national electrical manufacturers association) The standard for the performance of various classes of electrical enclosures. The NEMA standards cover corrosion resistance, ability to help protect from rain, submersion, and so on. For IEC member countries, the IEC 60529 standard classifies the ingress protection rating for enclosures.

network:

A system of interconnected devices that share a common data path and protocol for communications.

NO:

(normally open) A contact pair that opens when the actuator is de-energized (no power is applied) and closes when the actuator is energized (power is applied).

NTC:

(Negative Temperature Coefficient)

P**PLC:**

(programmable logic controller) An industrial computer used to automate manufacturing, industrial, and other electromechanical processes. PLCs are different from common computers in that they are designed to have multiple input and output arrays and adhere to more robust specifications for shock, vibration, temperature, and electrical interference among other things.

power supply terminals:

The power supply is connected to these terminals to provide power to the controller.

protocol:

A convention or standard definition that controls or enables the connection, communication, and data transfer between 2 computing system and devices.

Pt1000:

(platinum 1000) Resistance thermometers, also referred to as resistance temperature detectors, are sensors used to measure temperature by correlating electrical resistance with temperature. As the temperature changes, the resistance to an electrical current passing through them predictably changes likewise. They are characterized by their nominal resistance R_0 at a temperature of 0 °C.

- Pt1000 ($R_0 = 1 \text{ k}\Omega$)

PTC:

(Positive Temperature Coefficient)

PWM:

(pulse width modulation) A fast output that oscillates between off and on in an adjustable duty cycle, producing a rectangular wave form (though you can adjust it to produce a square wave). The PWM is well adapted to simulate or approximate an analog output in that it regulates the voltage of the output over its period making it useful in light dimming or speed control applications, among others.

R**RS-485:**

A standard type of serial communication bus, based on 2 wires (also known as EIA RS-485).

RTC:

(real-time clock) A battery-backed time-of-day and calendar clock that operates continuously, even when the controller is not powered for the life of the battery.

S**SELV:**

(safety extra low voltage) A system that follows IEC 61140 guidelines for power supplies is protected in such a way that voltage between any 2 accessible parts (or between 1 accessible part and the PE terminal for class 1 equipment) does not exceed a specified value under normal conditions or under inoperable conditions.

sink input:

A wiring arrangement in which the device provides current to the input electronic module. A sink input is referenced to 0 Vdc.

SL:

(serial line)

SPDT:

(single-pole, double-throw)

SPST:

(single-pole, single-throw)

SSR:

(solid-state relay)

T

terminal block:

(terminal block) The component that mounts in an electronic module and provides electrical connections between the controller and the field devices.

U

UL:

(underwriters laboratories) A US organization for product testing and safety certification.

W

WORD:

A type encoded in a 16-bit format.

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9MA10291.04